
Ultrasonic sensors

XX range

Catalogue



Simply easy!™

Optimise detection with XX range

Detect objects in challenging applications with our XX ultrasonic sensors range. These ultrasonic sensors offer an efficient solution for reliable and high performance detection at distances of up to 8 m, on window mode*.

* The window mode enables suppression of the foreground and the background using the same sensor.

> A technology suited to your needs

Detect objects regardless lightning conditions or material reflectivity degree.

> 3 operating modes for efficient detection

Ideal for detecting irregular-shaped objects.

> Short or long distance detection

From 50 mm up to 8 m.

Contents

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> A technology suited to your needs

Ultrasonic sensors enable non-contact detection of objects in many kinds of industrial environment, irrespective of :

- material (metal, plastic, wood, cardboard, etc.),
- nature (solid, liquid, powder, paste, etc.),
- colour,
- degree of transparency.

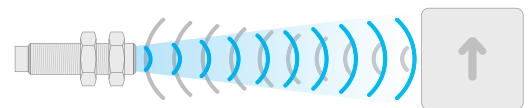
The ultrasonic sensors are simple to install; they feature integrated connectors, or cable versions in select models, and offer a wide range of cabling and mounting accessories for a seamless integration.

> 3 operating modes for efficient detection

Diffuse mode

An object reflects the ultrasonic wave back to the sensor which, in turn, changes the output state.

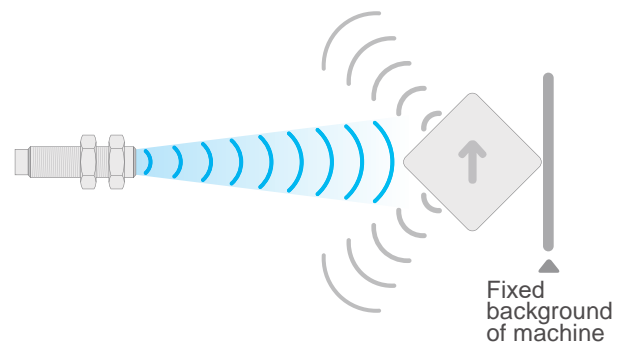
This operating mode is well suited for detecting objects with flat surfaces that are positioned perpendicularly to the direction of the ultrasonic beam.



Reflex mode

The sensor is permanently detecting a fixed background (previously taught) on a machine or application. When another object breaks the ultrasonic beam, the output changes its state.

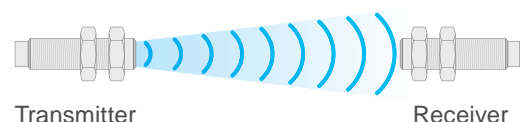
Well suited for detecting objects that absorb the ultrasonic waves (sponges, etc.) or that do not reflect the wave back to the sensor (non-flat surfaces, pointy or irregular-shaped objects).



Thru-beam mode

The transmitter is constantly sending an ultrasonic wave to the receiver. When an object breaks the ultrasonic beam, the output changes its state.

Well suited for small object detection and applications where higher accuracy and faster response time are required.



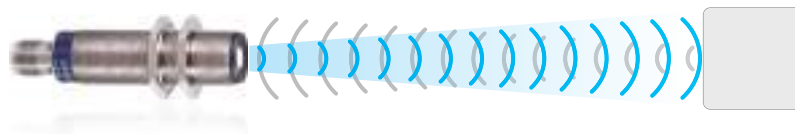
> Long distance proximity detection

Ultrasonic technology allows now for long distance proximity detection. The XXV Ø18 ultrasonic sensors enable detection from 0 to 50 mm (i.e. 2.5 times farther than standard inductive proximity sensors) with minimal environment constraints or object material and colour restrictions.

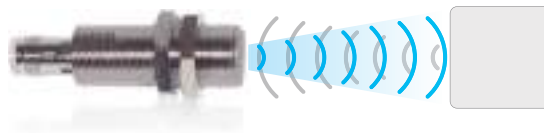
Sensors mounted too close to moving-metal parts are exposed to hits or impacts which can cause machine downtime. Being able to install sensors farther away from moving targets reduces the exposure to potential incidents. You increase installation profitability!

x 2.5
detection distance
than standard
inductive proximity
sensors

XXV Ø 18 sensor

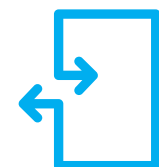


Standard inductive proximity sensor



The XXV ultrasonic sensor is a “Plug and Play” solution with no adjustment or teaching required. Its solid-state output changes state when an object is less than 50 mm away from the sensor face.

Its accurate and well-defined transmission angle enables precise detection. Crosstalk with other sensors and object edge effects are mastered.

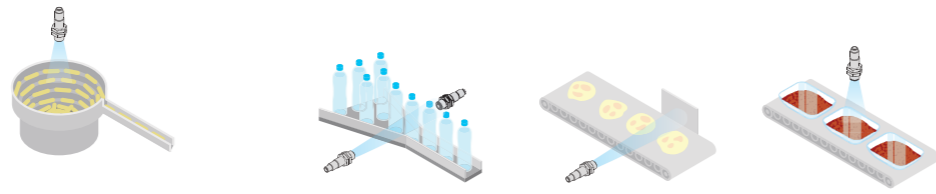


Plug & Play solution

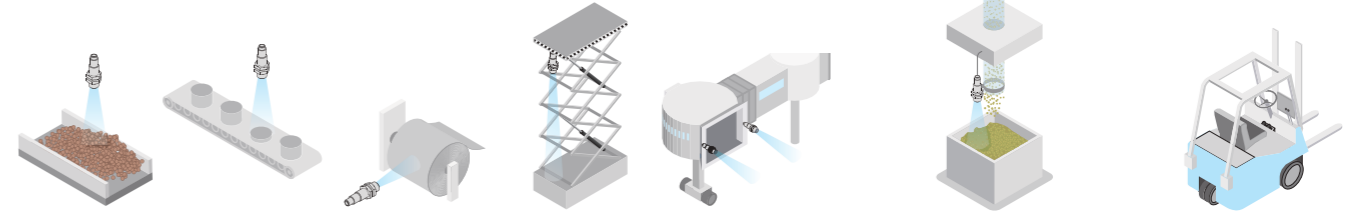


100 %
Worldwide availability









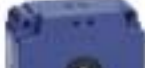
| Sensor type | Detection "Digital" | | | | | | | Regulation "Analogue output" | | | | | Level monitoring | | Mobile equipment |
|-------------|---------------------|--|--|--|--|--|--|------------------------------|--|--|--|--|------------------|--|------------------|
|-------------|---------------------|--|--|--|--|--|--|------------------------------|--|--|--|--|------------------|--|------------------|

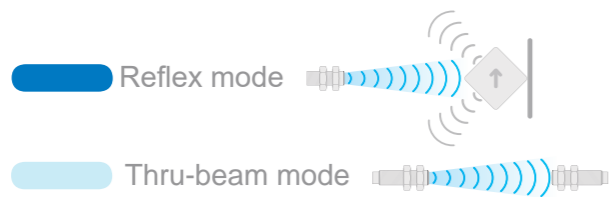


| Assembly | | Conveying | | | Packaging | |
|--------------|----------------|------------------|---------------------|-----|-----------|------------------|
| Machine part | Vibrating bowl | Presence Absence | Transparent bottles | Jam | Flow | Transparent film |



| Conveying | | Packaging | Handling | | Process | | Handling |
|----------------|----------------|----------------------|---------------------------|--------------------------|-------------------------|------------------|----------|
| Material level | Height of part | Radius of strip roll | Height of elevating table | Aircraft boarding bridge | Monitoring 2 thresholds | Filling Emptying | Forklift |

| | | | | | | | |
|--|------------|------------|------------------|------------------|------------|------------|------------|
|  Ø 18 (M18x1) | [Blue bar] | | [Blue bar] | | | | |
|  Ø 12 (M12x1) | [Blue bar] | | [Light blue bar] | | | | |
|  Ø 18 (M18x1) | [Blue bar] | [Blue bar] | [Blue bar] | [Light blue bar] | [Blue bar] | [Blue bar] | [Blue bar] |
|  Ø 30 (M30x1.5) | [Blue bar] | | | [Blue bar] | [Blue bar] | | |
|  79x32.5+Ø 54 | | | | | | | |
|  7.6x19x33 | | [Blue bar] | | | [Blue bar] | [Blue bar] | |
|  16x30x74 | | [Blue bar] | | | | | [Blue bar] |
|  18x33x60 Ø 18 (M18x1) | [Blue bar] | | [Blue bar] | [Blue bar] | [Blue bar] | | [Blue bar] |
|  80x80x34 | | | | [Blue bar] | [Blue bar] | | |



| | | | | | | | |
|------------|------------|------------|------------|------------|------------|------------|------------|
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| | [Blue bar] | | [Blue bar] | [Blue bar] | | | [Blue bar] |



Ultrasonic sensors

XX range

Cylindrical type

Applications
Non-contact detection of sound reflecting objects regardless their shape, material, colour, orientation, etc.

Sensors with solid-state digital output

Cylindrical type

Ø 12 (M12 x 1)



Ø 18 (M18 x 1)



Ø 18 (M18 x 1) (continued)



Ø 30 (M30 x 1.5)



Cylindrical type

Application, monitoring 2 levels

Ø 18 (M18 x 1)

Ø 30 (M30 x 1.5)



| | | | | | | | |
|---------------------------------|-----------|--|-----------------|--------------|-----------------------------|----------------|-----------------------------|
| Sensing distance Sn | Diffuse | 5 cm | 10 cm | – | 5 cm | 15 cm | 50 cm |
| | Reflex | – | – | – | – | – | 50 cm |
| | Thru-beam | – | – | 20 cm | – | – | – |
| Assured operating distance (mm) | | 6.4...51 fixed | 6.4...102 fixed | – | 2...50 fixed | 25...152 fixed | Adjustable using teach mode |
| Power supply | | 12...24 V $\overline{\text{---}}$ with protection against reverse polarity | | | | | |
| Type of output | | PNP/NPN | NPN or PNP | PNP/NPN | PNP or NPN | PNP/NPN | NPN or PNP |
| Function | | NO | NO | NO/NC | NO/NC | NO | NO |
| Degree of protection | | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 |
| Connection | | M8 connector | M8 connector | M8 connector | M12 connector or pre-cabled | M12 connector | M12 connector or pre-cabled |
| Sensor type | | XX512A1● | XX512A2● | XX●12A8● | XXV18B1● | XX518A1● | XX518A3● |
| Page | | 22 | | | 22 | 26 | |

| | | | | | | | | | |
|---------------------------------|-----------|-----------------------------|-----------------------------|--------------------------------------|--|--|-----------------------------|----------------------------|---------------|
| Sensing distance Sn | Diffuse | – | 1 m | 1 m | 2 m/4 m depending on model | 8 m | 50 cm | 1 m/2 m depending on model | 8 m |
| | Reflex | – | 1 m | 1 m | 2 m/4 m depending on model | 8 m depending on model | – | – | – |
| | Thru-beam | – | – | – | – | – | – | – | – |
| Assured operating distance (mm) | | 61 cm/1 m | – | – | – | – | – | – | – |
| Power supply | | Adjustable using teach mode | Adjustable using teach mode | | | | Adjustable using teach mode | | |
| Type of output | | PNP/NPN | PNP | PNP or NPN or PNP/NPN | | PNP or NPN | PNP or NPN | | |
| Function | | NO/NC | NO or NC (selectable) | NO or NC or NO+NC or NO+NO | | NO + NC NO or NC (selectable) | NO NO + NO NO + NO | | |
| Degree of protection | | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 |
| Connection | | M12 connector | M12 connector | M12 connector | M12 connector | M12 connector | M12 connector | M12 connector | M12 connector |
| Sensor type | | XX●18A3● XX●18A4● | XX●18●1PM12 | XX●30●●1PM12 XX6V3A1● XX630A1● | XX●30●●2PM12 XXS30●●4PM12 XX630A2● | XX630A3● XXS30P8PPM12 XXS30P8NNM12 | XX218A3● | XX230A1● XX230A2● | XX230A3● |
| Page | | 26 | 30 | 36 and 42 | | | 40 | | (1) |

Sensors with analogue output

Cylindrical type

Ø 18 (M12 x 1)



Ø 30 (M30 x 1.5)



| | | |
|---------------------------------|--|-----------------------------|
| Sensing distance Sn | 50 cm | 1 m |
| Assured operating distance (mm) | Adjustable using teach mode | Adjustable using teach mode |
| Power supply | 12...24 V $\overline{\text{---}}$ with protection against reverse polarity | |
| Type of output | 4-20 mA or 0-10 V | 4-20 mA or 0-10 V |
| Degree of protection | IP 67 | IP 67 |
| Connection | M12 connector | M12 connector |
| Sensor type | XX918A3● | XX●18●1AM12 XX●18●1VM12 |
| Page | 26 | 30 |

| | | | | |
|---------------------------------|--|-------------------------|---------------|---|
| Sensing distance Sn | 1 m | 2 m | 4 m | 8 m |
| Assured operating distance (mm) | Adjustable using teach mode | | | |
| Power supply | 12...24 V $\overline{\text{---}}$ or 24 V $\overline{\text{---}}$, depending on model, with protection against reverse polarity | | | |
| Type of output | 4-20 mA or 0-10 V | | | 4-20 mA or 0-10 V PNP, NO or NC (selectable) |
| Degree of protection | IP 67 | IP 67 | IP 67 | IP 67 |
| Connection | M12 connector | M12 connector | M12 connector | M12 connector |
| Sensor type | XX●30●1●M12 XX9V3A1● XX930A1● | XX●30●2●M12 XX930A2● | XXS30●4●M12 | XX930A3● XXS30P8APM12 XXS30P8VPM12 |
| Page | 36 | 36 | 42 | 36 and 42 |

(1) Please visit our website: www.tesensors.com

Applications
Non-contact detection of sound reflecting objects regardless their shape, material, colour, orientation, etc.

Dimensions (mm)

Sensors with solid-state digital output

Flat format

7.6 x 19 x 33

16 x 30 x 74



| | |
|---------------------------------|---|
| Sensing distance Sn | Diffuse |
| | Reflex |
| | Thru-beam |
| Assured operating distance (mm) | 6.4...100 fixed |
| Power supply | 12...24 V $\overline{\text{DC}}$ with protection against reverse polarity |
| Type of output | NPN or PNP |
| Function | NO |
| Degree of protection | IP 67 |
| Connection | M12 connector on flying lead |
| Sensor type | XX7F1A2 |
| Page | 72 |

| | |
|---|---------------------|
| 10 cm | 25 cm |
| – | – |
| – | – |
| 6.4...100 fixed | 51...250 fixed |
| 12...24 V $\overline{\text{DC}}$ with protection against reverse polarity | |
| NPN or PNP | PNP |
| NO | NO |
| IP 67 | IP 67 |
| M12 connector on flying lead | M12 connector |
| XX7F1A2 | XX7K1A2PAM12 |
| 72 | 72 |

Sensors with solid-state digital output and analogue output

Format for mobile equipments

Dimensions (mm)

79 x 32.5 + Ø 54



| | | | |
|---------------------------------|---|---------------------------------------|----------------------|
| Sensing distance Sn | 3 m | | |
| Assured operating distance (mm) | 0.425...3 | | |
| Power supply | $\overline{\text{DC}}$ 12...24 V with protection against reverse polarity | | |
| Type of output | 0.5 - 4.5 V + PNP or 4-20 mA + PNP or CAN J1939 (depending on model) | | |
| Degree of protection | IP 65, IP 67, IP 69K | IP 65, IP 67 | IP 65, IP 67, IP 69K |
| Connection | Deutsch DTM04 connector on flying lead (0.15 m) | M12 connector on flying lead (0.15 m) | Pre-cabled (0.5 m) |
| Sensor type | XXW54P3 •PL01DM6 | XXW54P3 •PL01DM12 | XXW54P3 •PL05 |
| Page | 63 | 63 | 63 |

18 x 33 x 60 + Ø 18 (M18 x 1)

80 x 80 x 34



| | |
|---|----------------------|
| 50 cm (adjustable) | 1 m (adjustable) |
| 50 cm (adjustable) | 1 m (adjustable) |
| – | – |
| Adjustable using teach mode | |
| 12...24 V $\overline{\text{DC}}$ with protection against reverse polarity | |
| NPN or PNP | NPN or PNP |
| NO | NO |
| IP 67 | IP 67 |
| M12 connector | M12 connector |
| XX7V1A1 •AM12 | XX8D1A1 •AM12 |
| 72 | 72 |

Sensors with analogue output

Flat format

18 x 33 x 65 + Ø 18 (M18 x 1)

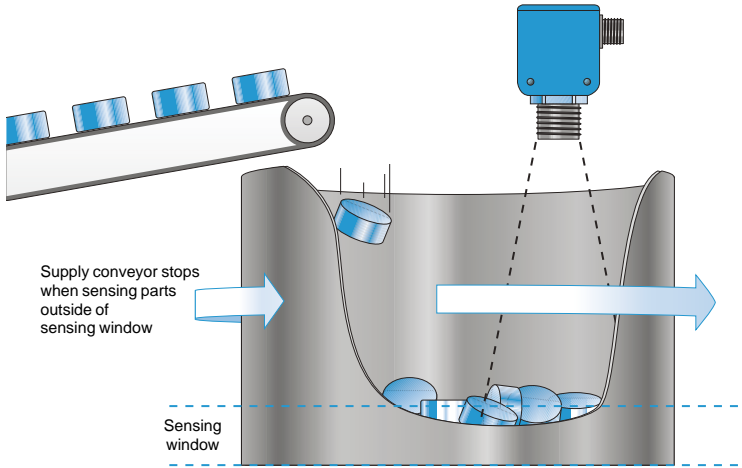
80 x 80 x 34



| | | | |
|---|--|---|--|
| 50 cm (adjustable) | 1 m (adjustable) | | |
| Adjustable using teach mode | | | |
| 12...24 V $\overline{\text{DC}}$ with protection against reverse polarity | 24 V $\overline{\text{DC}}$ with protection against reverse polarity | 12...24 V $\overline{\text{DC}}$ with protection against reverse polarity | 24 V $\overline{\text{DC}}$ with protection against reverse polarity |
| 4-20 mA | 0-10 V | 4-20 mA | 0-10 V |
| IP 67 | IP 67 | IP 67 | IP 67 |
| M12 connector | M12 connector | M12 connector | M12 connector |
| XX9V1A1C2M12 | XX9V1A1F1M12 | XX9D1A1C2M12 | XX9D1A1F1M12 |
| 73 | | 73 | |

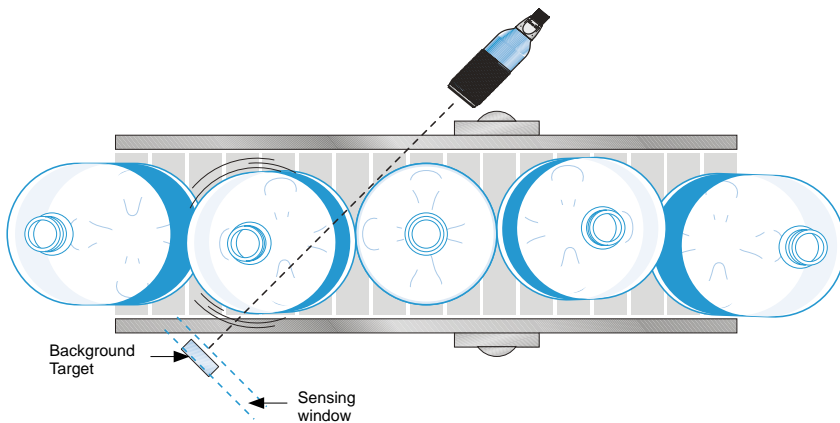
Feeder bowl supply control

XXS18, XXA18, XX7V1A1



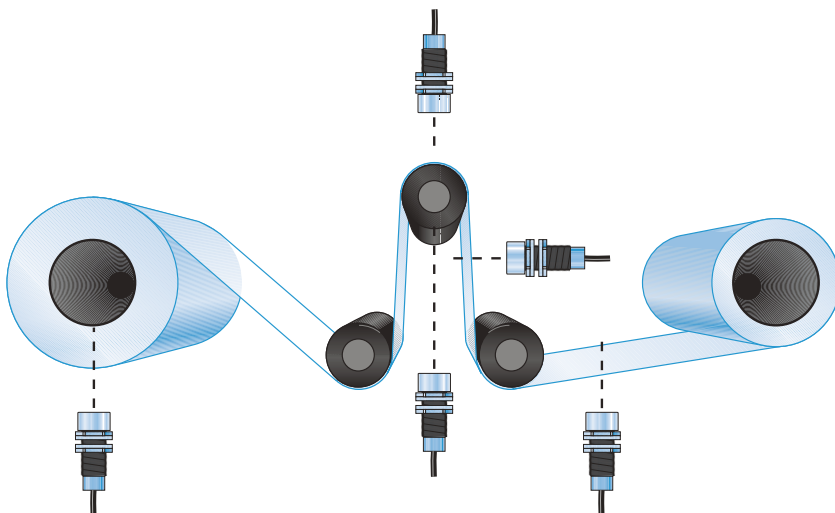
Conveyor jam and backup detection

XXS18, XXA18, XXB18A3



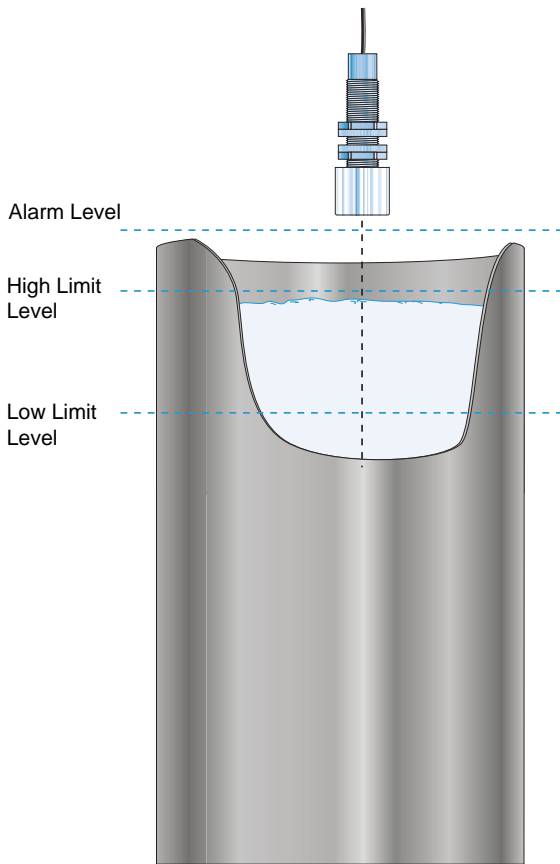
Web process control sensing functions

XXS18, XXS30



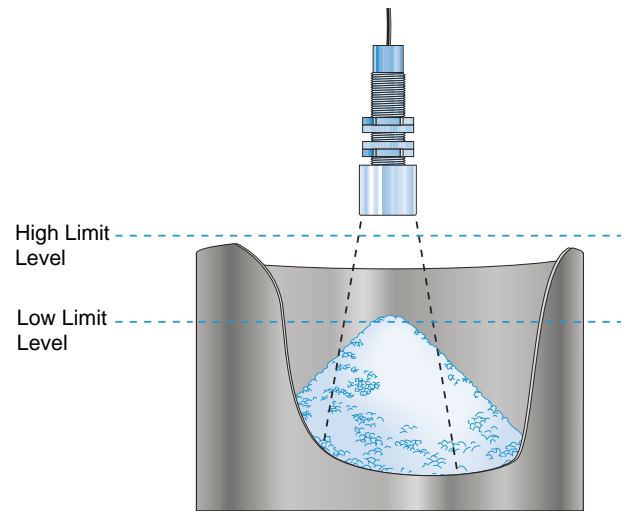
Dual level high-low latch control detection of liquids

XXS30P8, XX230A3



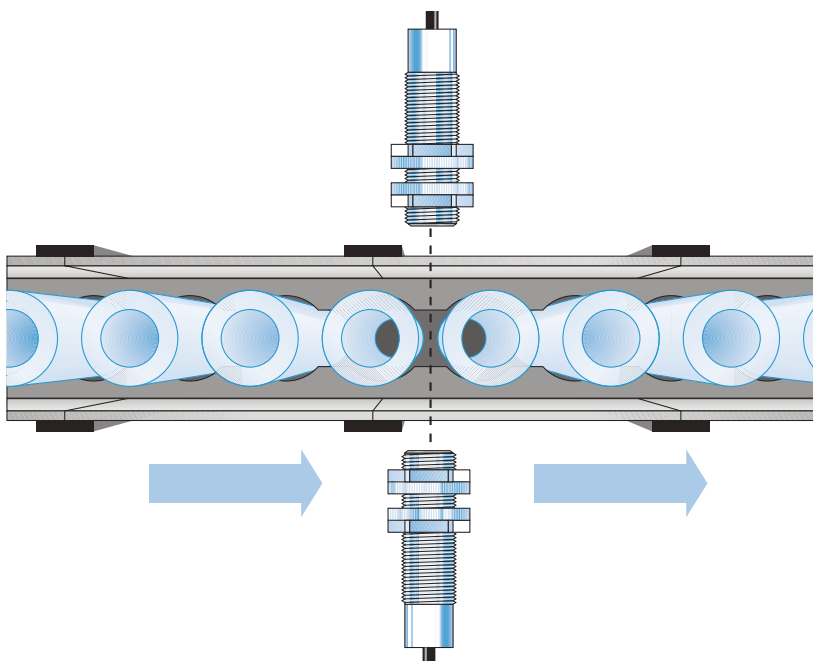
High level detection

XXS30P8, XX630A3



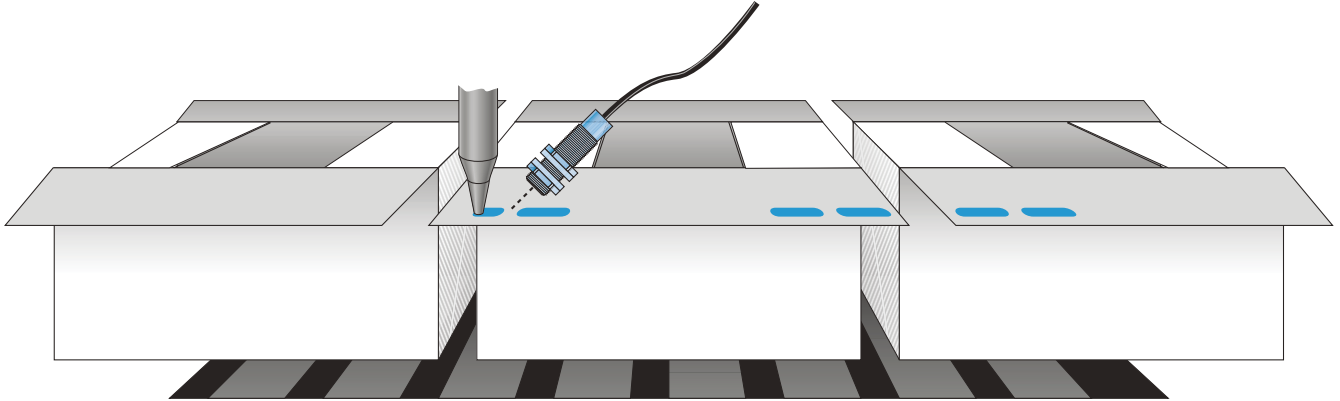
Accurate high speed counting of cylindrical clear objects

XXT18 + XXR18



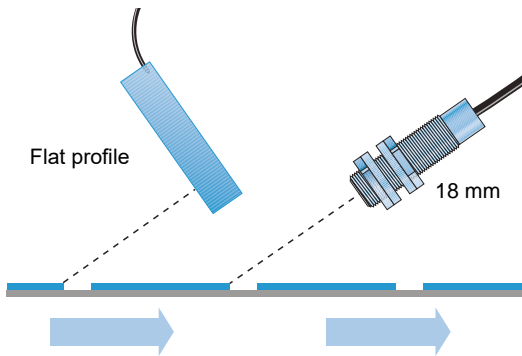
Glue bead detection

XXV18



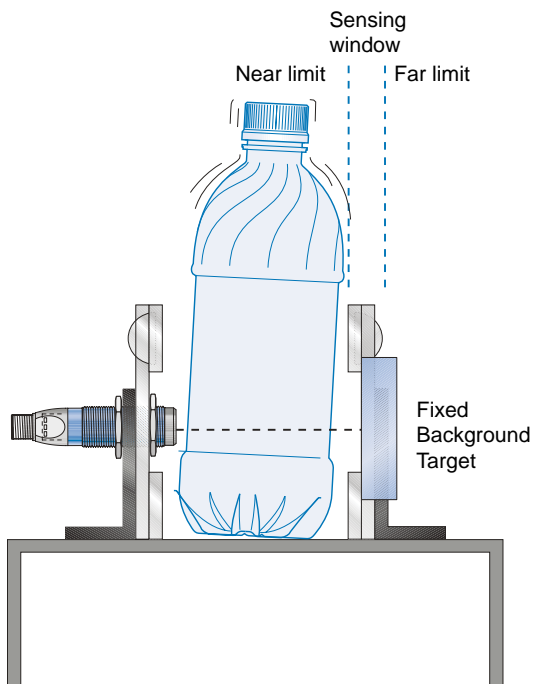
Label edge detection on carrier web

XX7K, XX7F (flat format), XX518A3 (M18)



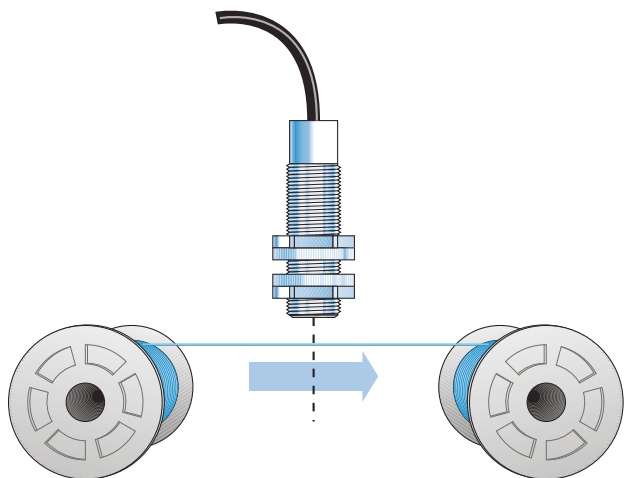
Clear bottle detection for sustainable environments

XXS18, XXA18, XXB18



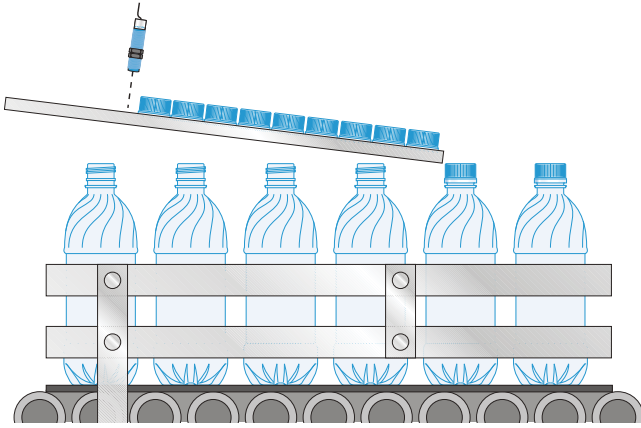
Broken wire/thread detection

XXV18



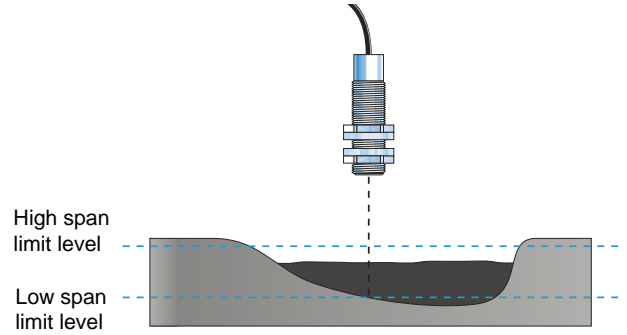
Missing cap detection low cap supply

Automatically stops filler and capper
XX512



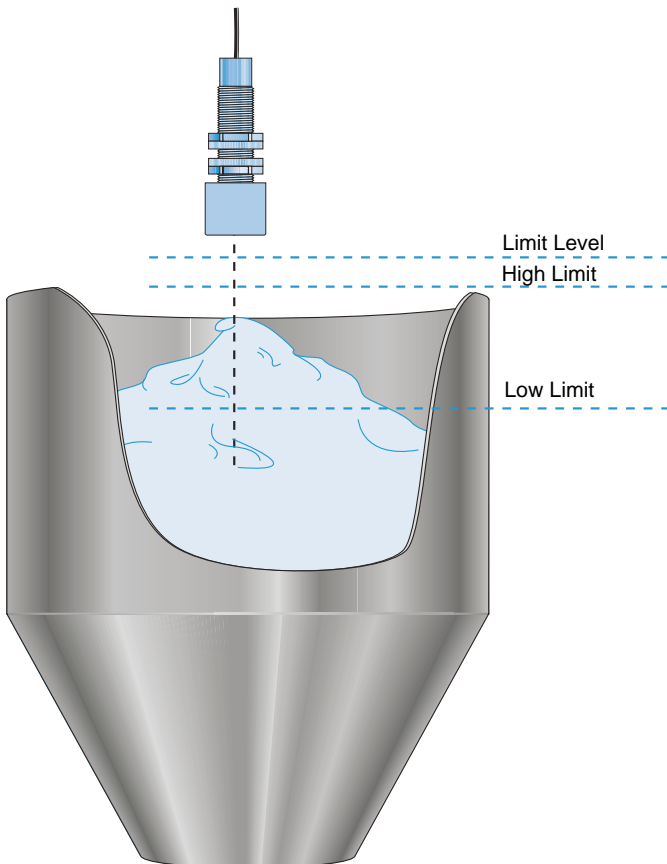
Continuous level monitoring

Analog output sensors
XXS18, XXS30, XX918, XX930



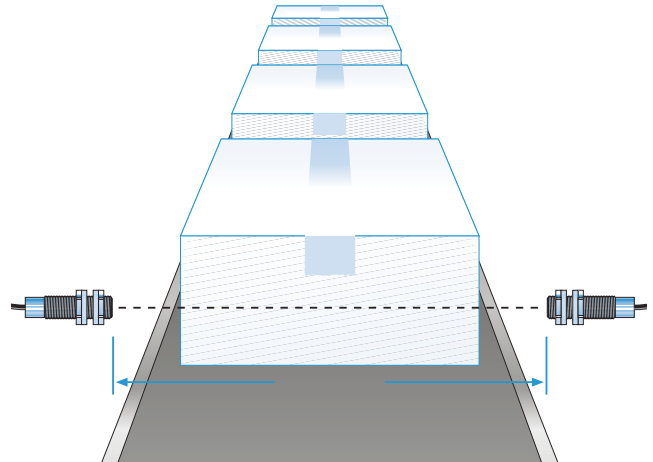
Dual level high-low latch control detection

XXS30●●PM12, XX230



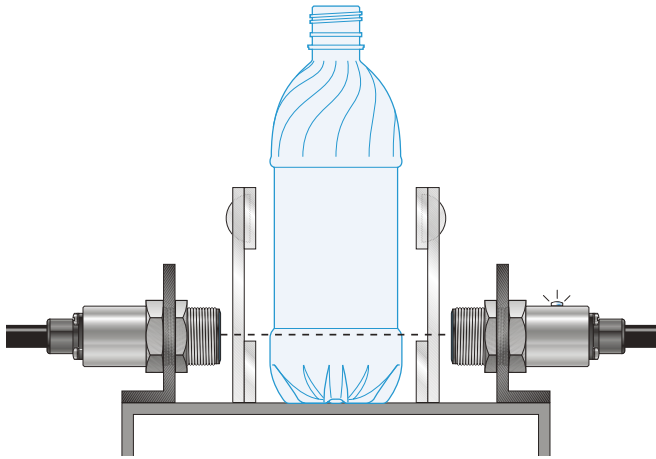
Lead edge or backup detection

XXT18 and XXR18



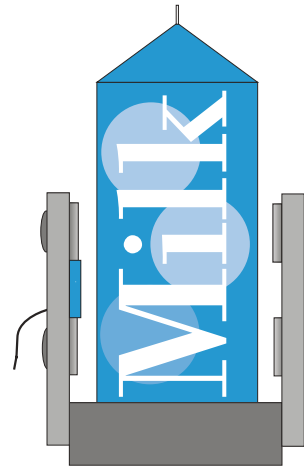
Clear bottle detection

XXT12 and XXR12



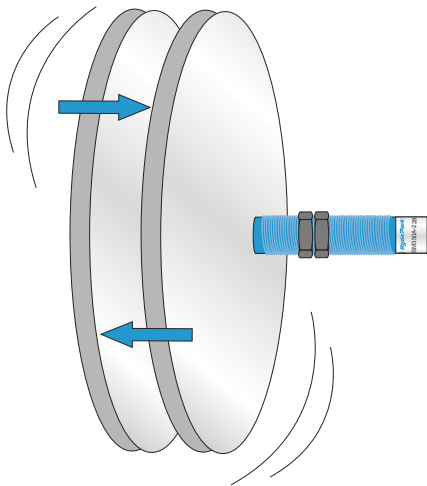
Container detection

XX7F1



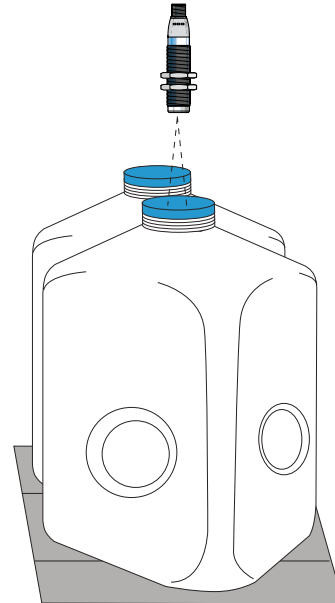
Metal material detection

XX512



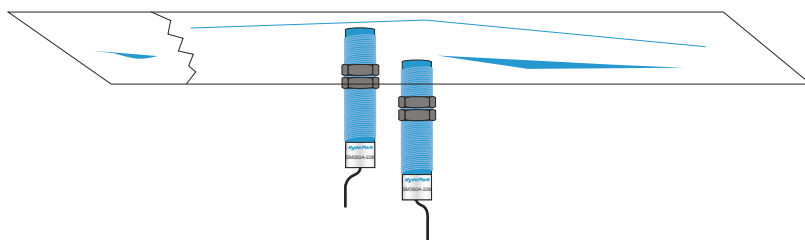
Missing cap detection

XX518



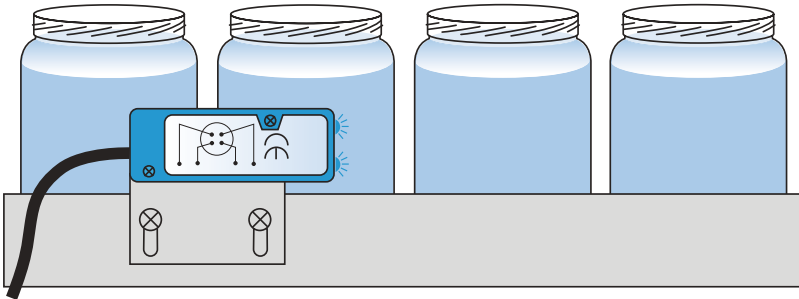
Clear web detection

XX512



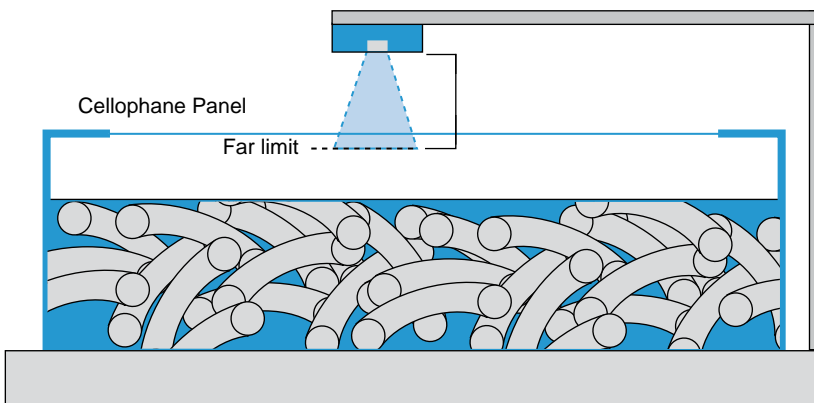
Container detection

XX7F1



Clear cellophane panel detection

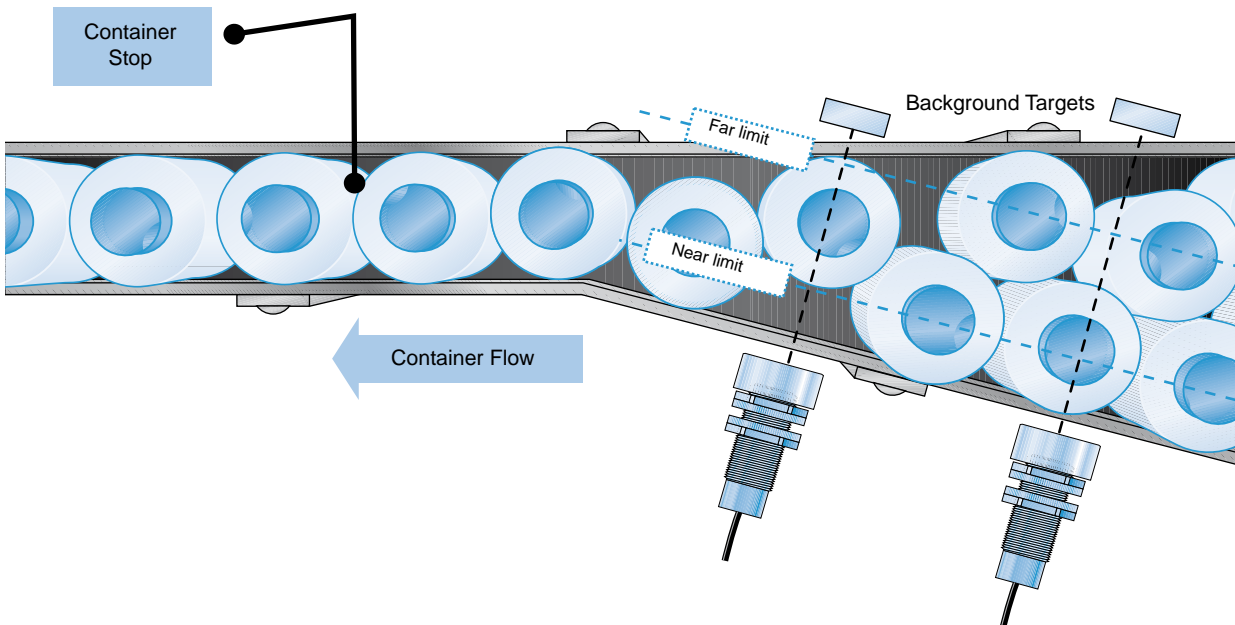
XX7F1A2



Single file jam protection

Dual level latch control sensor

XX218 and XX230



Quality, standards and certifications

Quality control

The XX ultrasonic sensors models are subjected to special precautions in order to guarantee their reliability in arduous industrial environments.

■ Qualification

A **qualification procedure** on the characteristics of XX range ultrasonic sensors is carried out in our laboratories.

■ Production

The electrical characteristics and the sensing distances at the ambient and operating temperatures are 100% verified.

Sensors are statistically selected during the course of production and subjected to **monitoring tests** on all qualified characteristics.

■ Customer returns

Returned ultrasonic sensors are subjected to systematic analysis and corrective actions are implemented to eliminate recurrence of the fault.

Conformity to standards

The XX ultrasonic sensors models conform to the standards IEC 60947-5-2.
Standards and characteristics: refer to pages 23, 27, 32, 38, 41, 45, 46, 50, 54 and 58.

Resistance to chemicals in the environment

To ensure lasting efficient operation, it is essential that any chemicals coming into contact with the ultrasonic sensors will not affect their casing and, in doing so, prevent their reliable operation.

Due to the materials used, the XX ultrasonic sensors models are very resistant to:

■ Chemical agents:

salts, aliphatic and aromatic oils,
petroleum, diluted bases and acids.

Depending on their nature and concentration, tests should be carried out beforehand for the following chemical agents:

alcohols, ketones and phenols.

■ Food and beverage industry products:

vegetable oils, animal fats,
fruit juices,
milk proteins, etc.

Resistance to the environment

■ IP 65: protection against water jets.

Tested in accordance with IEC 60529: the device is subjected to water sprayed from a Ø 6.3 mm nozzle, at a flow rate of 12.5 litres/min for 3 min at a distance of 3 m.
No deterioration in either operating or insulation characteristics is permitted.

■ IP 67: protection against the effects of immersion.

Tested in accordance with IEC 60529: the sensor is immersed for 30 minutes in 1 m of water.
No deterioration in either operating or insulation characteristics is permitted.

■ IP 69K: protection against the effects of high pressure cleaning. Adherence to standard

DIN 40050 which stipulates that the product must withstand a water jet at a pressure of 90 bar and temperature of +80°C for 3 minutes.

No deterioration in either operating or insulation characteristics is permitted.

Recommendations

The ultrasonic sensors are designed for use in standard industrial applications involving presence detection.
 Since these sensors do not incorporate a redundant electrical circuit, they are not suitable for use in safety applications.
 For safety applications, please refer to our website www.tesensors.com

Principle of ultrasonic detection



Presentation

Ultrasonic sensors enable detection, without contact, of objects irrespective of its:

- material (metal, plastic, wood, cardboard, etc.),
- nature (solid, liquid, powder, etc.),
- colour,
- degree of transparency.

They are used in industrial applications for detecting, for example:

- the position of machine parts,
- the presence of the windscreen during automobile assembly,
- the flow of objects on a conveyor system: glass bottles, cardboard packages, cakes, etc.,
- the level
- of different colour paints in pots,
- of plastic pellets in injection moulding machine feeders.

The ultrasonic sensors are simple to install due to their integral connector and availability of cabling and fixing accessories.

Operating principle

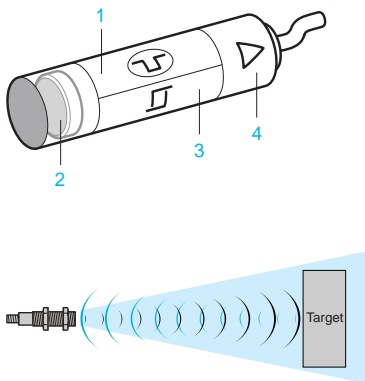
The principle of ultrasonic detection is based on measuring the time taken between transmission of an ultrasonic wave (pressure wave) and reception of its echo (return of transmitted wave).

The XX ultrasonic sensors models comprise:

- 1 a high voltage generator
- 2 a piezoelectric transducer (transmitter and receiver)
- 3 a signal processing stage
- 4 an output stage

Excited by the high voltage generator **1**, the transducer (transmitter-receiver) **2** generates a pulsed ultrasonic wave (200 to 500 kHz depending on the product) which travels through the ambient air at the speed of sound. When the wave strikes an object, it reflects (echo) and travels back towards the transducer. A micro controller **3** analyses the signal received and measures the time interval between the transmitted signal and the echo. By comparison with the preset or taught times, it determines and controls the output states **4**.

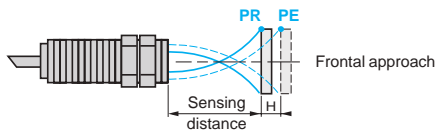
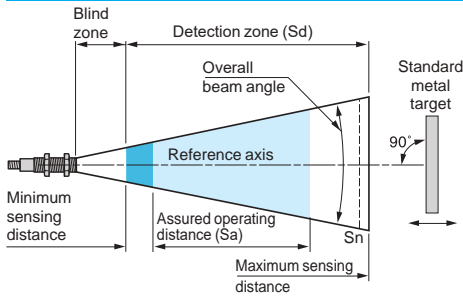
The output stage **4** controls a solid-state switch (PNP or NPN transistor) corresponding to a NO or NC contact (detection of object).



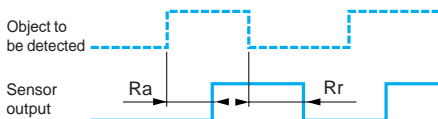
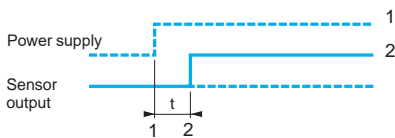
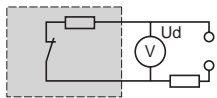
Advantages of ultrasonic detection

- No physical contact with the object to be detected, therefore, no wear and detection possible of fragile and/or freshly painted objects, etc.
- Detection of materials, irrespective of colour, at the same distance, without adjustment or correction factor.
- Teach mode function, by simply pressing a button, for defining the effective detection zone. Teaching of the minimum and maximum sensing distances (very precise foreground and background suppression, ± 6 mm).
- Very good resistance to industrial environments (robust products entirely encapsulated in resin).
- Solid-state units: no moving parts in the sensor, therefore, service life independent of the number of operating cycles.
- Various types of outputs to suit requirements:
 - Digital output for level control or detection of any type of object
 - Analogue output for controlling systems that require a signal that is proportional to the distance at which the object is detected.

Terminology



PR = drop-out point
PE = pick-up point



Definitions

The terms listed below are defined by the standard IEC 60947-5-2:

■ **Nominal sensing distance (Sn)**
Conventional value for indicating the sensing distance. It does not take into account manufacturing tolerances nor variations caused by external conditions such as voltage and temperature.

■ **Detection zone (Sd)**
Zone in which the sensor is sensitive to objects.

■ **Minimum sensing distance**
Lower limit of the specified detection zone.

■ **Maximum sensing distance**
Upper limit of the specified detection zone.

■ **Assured operating distance (Sa)**
This corresponds to the operating zone of the sensor (activation of outputs), and is included in the detection zone. It is also known as the "detection window".
Its limits are fixed:

- at the factory for fixed sensing distance sensors,
- when setting-up within the application for sensors with teach mode.

■ **Blind zone:** Zone located in front of the sensing face of the sensor.
For diffuse sensors, it is the zone in which the object will not be reliably detected.
For reflex sensors, it is the zone in which the target (fixed background of machine for example) will not be reliably detected, but the object can be in this zone.
For thru-beam sensors, there is no blind zone.

■ **Differential travel**
The differential travel (H) or hysteresis is the distance between the pick-up point as the standard metal target moves towards the sensor and the drop-out point as it moves away from the sensor.

■ **Repeat accuracy**
The repeat accuracy (R) is the precision of reproduction between two successive measurements of the sensing distance, made in identical conditions.

■ **Overall beam angle**
Fixed angle around the reference axis of an ultrasonic proximity sensor.

■ **Standard metal target**
The standard IEC 60947-5-2 defines the standard target as a square metal plate, 1 mm thick with rolled finish, placed perpendicularly to the reference axis.
Its side dimension depends on the detection zone:

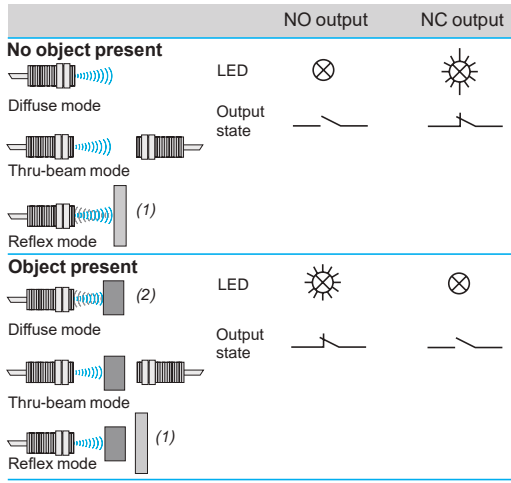
| Detection zone (mm) | Size of target (mm) |
|---------------------|---------------------|
| < 300 | 10 x 10 |
| 300 < d < 800 | 20 x 20 |
| > 800 | 100 x 100 |

■ **Voltage drop (Ud)**
The voltage drop (Ud) corresponds to the voltage at the terminals of the sensor when in the closed state (value measured at the nominal current of the sensor).

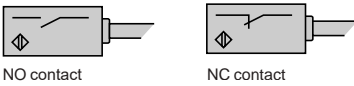
■ **First-up delay**
Time required to ensure operation of the sensor's output signal following power-up.
1 Power-up
2 Output signal state (0 or 1)

■ **Response time**
Response time (Ra): time taken between the instant the object to be detected enters the active zone and the changing of the output signal state. This time limits the passing speed of the target in relation to its dimensions.
Recovery time (Rr): time taken between the object being detected leaving the active zone and the changing of the output signal state. This time limits the interval between 2 objects.

Digital outputs



(1) Fixed background of machine
(2) Object



LED indicators

The majority of XX ultrasonic sensors models incorporate light-emitting diode output state indicators.

- Ø 12 sensor
 - Green LED (power on)
 - Yellow LED (object present)
- Ø 18 sensor, sensitivity 500 mm (except thru-beam versions XXT18 and XXR18)
 - Yellow LED (object present) or green LED (power on) + user assistance when adjusting the detection zone
- Ø 30 sensor
 - Multicolour LED for assisting the user when adjusting the detection distance
 - Yellow LED (object present)
 - Analogue version with LED (object present, with luminosity increasing as output signal increases)
- Parallelepiped format sensor
 - XX●F: Dual colour yellow (object present) or green (power on) LED
 - XX●V: Dual colour yellow (object present) or green (power on) LED + user assistance when adjusting the detection zone
 - XX7K: Yellow LED (object present); green LED (power on)
 - XXTK: Yellow LED (object present) only
 - XX●D: Yellow LED (object present); green LED (power on)
 - Analogue version with LED (object present, with luminosity increasing as output signal increases)

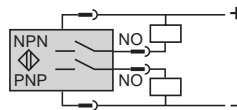
Sensors with digital switching

Output contact logic

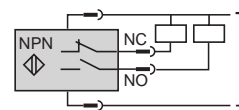
- NO contact (normally open)
Corresponds to a sensor whose output changes to the closed state when an object is present in the detection window.
- NC contact (normally closed)
Corresponds to a sensor whose output changes to the open state when an object is present in the detection window.

4-wire technique

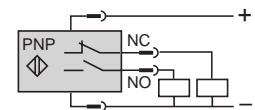
NO output/PNP and NPN



NO + NC output/NPN



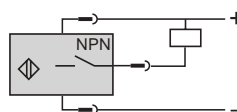
NO + NC output/PNP



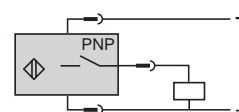
These sensors comprise 2 wires for the supply and 1 wire for each output signal

3-wire technique

NO output/NPN



NO output/PNP



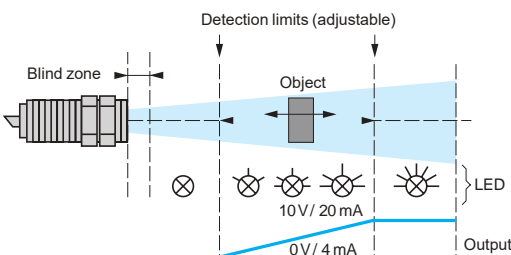
These sensors comprise 2 wires for the supply and 1 wire for the output signal,

- PNP type:** switching the positive side to the load.
- NPN type:** switching the negative side to the load.

Sensors with analogue output

Operation

The characteristic feature of these sensors is the output which delivers a signal (either current or voltage) that is proportional to the distance of the object being detected. Within the detection limits, which are adjustable using teach mode, the value of the output signal increases or decreases in relation to the distance of the object. When an object is detected, an LED indicator (D) illuminates and its luminosity increases in relation to the value of the output signal. The slope of the signal can simply be changed by pressing the teach button



Advantages

- Visual information available relating to the sensor/object distance.
- Protection against reverse polarity.
- Protection against overloads and short-circuits.
- No residual current, low voltage drop.

Power supply

Sensors for DC circuits

- **DC source:** Check that the voltage limits of the sensor and the acceptable level of ripple, are compatible with the supply used.
- **AC source** (comprising transformer, rectifier, smoothing capacitor): The supply voltage must be within the operating limits specified for the sensor.

Where the voltage is derived from a single phase AC supply, the voltage must be rectified and smoothed to ensure that:

- the peak voltage of the DC supply is lower than the maximum voltage rating of the sensor.

Peak voltage = nominal voltage $\times \sqrt{2}$

- the minimum voltage of the supply is greater than the minimum voltage rating of the sensor,

given that:

$$\Delta V = (I \times t) / C$$

$$\Delta V = \text{max. ripple: } 10\% (V),$$

I = anticipated load current (mA),

t = period of 1 cycle (10 ms full-wave rectified for a 50 Hz supply frequency),

C = capacitance (μF).

As a general rule, use a transformer with a lower secondary voltage (U_e) than the required DC voltage (U).

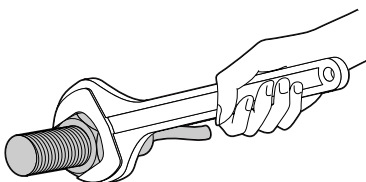
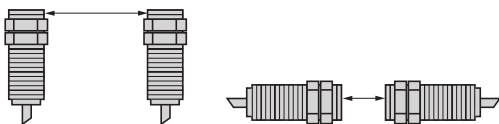
Example:

18 V \sim to obtain 24 V \dots ,

36 V \sim to obtain 48 V \dots .

Setting-up precautions

For diffuse sensors:



Mounting

Mounting distance between ultrasonic sensors

If 2 standard sensors are mounted too close to each other, the wave transmitted by one sensor is likely to interfere with the other and result in erratic operation.

In order to avoid this, it is necessary to adhere to the minimum distances between sensors. See setting-up precautions.

Maximum tightening torque

| Cylindrical sensors | Diameter mm | Tightening torque | Flat sensors | Screw | Tightening Torque |
|---------------------|----------------|------------------------|--------------|-------|------------------------|
| XX●12● | Ø 12 | 0.7 N.m/ 0.52 lb-ft | XX●F● | M3 | 0.7 N.m/ 0.52 lb-ft |
| XX●18● | Ø 18 | 1 N.m/ 0.74 lb-ft | XX●K● | M4 | 1 N.m/ 0.74 lb-ft |
| XX●30● | Ø 30 | 1.35 N.m/ 1 lb-ft | XX●V● | M3 | 0.7 N.m/ 0.52 lb-ft |
| XX●V3● | Ø 30 | 1.35 N.m/ 1 lb-ft | | Ø 18 | 1 N.m/ 0.74 lb-ft |
| XXS18* | Ø 18 (Plastic) | 2 N.m / | | | |
| XXA18* | | 1.47 lb-ft | | | |
| | Ø 18 (Metal) | 15 N.m / | | | |
| | | 11.06 lb-ft | | | |

Interchangeability

Interchangeability is made easy by using **indexed** fixing clamps:

- XSZB112 (Ø 12 mm),
- XSZB118 (Ø 18 mm),
- XSZB130 (Ø 30 mm),
- XXZB118 (Ø 18 mm),

Cabling

Electrical connection

- **Connect the sensor before switching on the supply**

- **Length of cable**

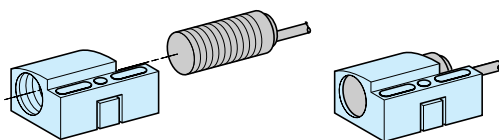
No limitation up to 200 m or up to a line capacitance of $< 0.1 \mu\text{F}$.

It is, however, advisable to take into account the voltage drop on the line.

- **Separation of control and power cables**

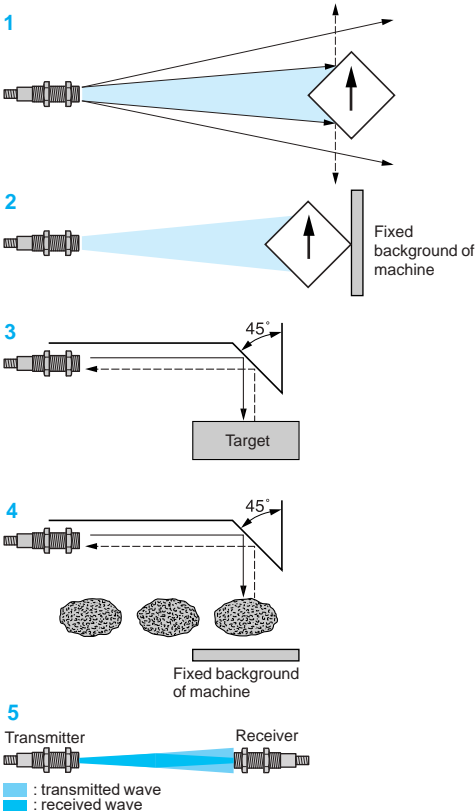
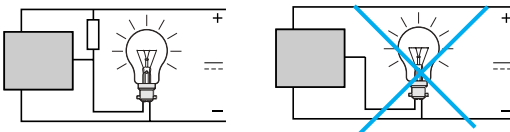
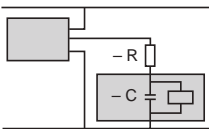
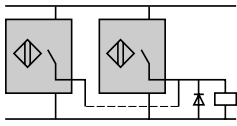
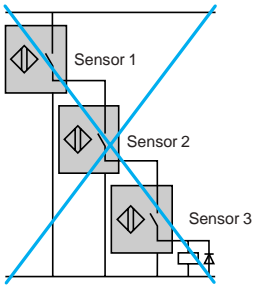
The sensors are immune to electrical interference encountered in normal industrial conditions. Where extreme conditions of electrical "noise" could occur (large motors, spot welders, etc.), it is advisable to protect against transients in the normal way:

- suppress interference at source,
- separate power and control wiring from each other,
- smooth the supply,
- limit the length of cable.



XSZB1●●

Setting-up precautions (continued)



Connection in series

This connection method is not recommended.

- Correct operation of the sensors cannot be assured and, if this method is used, tests should be made before installation.

The following points should be taken into account:

Sensor 1 carries the load current in addition to the no-load current consumption values of the other sensors connected in series. For certain models, this connection method is not possible unless a current limiting resistor is used.

When in the closed state, each sensor will produce a voltage drop and, therefore, the load voltage should be selected accordingly.

As sensor 1 closes, sensor 2 will not operate until a certain time "T" has elapsed (corresponding to the first-up delay) and likewise for the following sensors in the sequence.

"Flywheel" diodes should be used when the load being switched is inductive.

Sensors and units in series with an external mechanical contact

- The following points should be taken into account:

When the mechanical contact is open, the sensor is not supplied.

When the contact closes, the sensor will not operate until a certain time "T" has elapsed (corresponding to the first-up delay).

Connection in parallel

- No specific restrictions. The use of "flywheel" diodes is recommended when an inductive load (relay) is being switched.

Capacitive load (C > 0.1 mF)

- At switch-on, it is necessary to limit (by resistor) the charging current of the capacitive load C. The voltage drop in the sensor can also be taken into account by subtracting it from the supply voltage for calculation of R.

$$R = \frac{U \text{ (supply)}}{I \text{ max. (sensor)}}$$

Load comprising an incandescent lamp

- If the load comprises an incandescent lamp, the cold state resistance can be 10 times lower than the hot state resistance. This can cause very high current levels on switching. Fit a pre-heat resistance in parallel with the sensor.

$$R = \frac{U^2}{P} \times 10, U = \text{supply voltage and } P = \text{lamp power}$$

Detection

Influencing factors

The ultrasonic sensors are particularly suited for the detection of objects that are capable of reflecting an acoustic wave and, in general, having a flat surface perpendicular to the detection axis. However, the correct operation of the ultrasonic sensor can be disrupted by:

- air currents, which can accelerate or divert the acoustic wave transmitted by the sensor (ejection of part by air jet),
- high temperature gradients within the detection zone: an object emitting considerable heat can create zones of varying temperature that will modify the propagation time of the wave and thus prevent reliable operation,
- sound insulators: sound absorbing materials (cotton, fabrics, rubber, etc.),
- the angle between the face of the object to be detected and the reference axis of the sensor: when the angle is offset from 90°, the wave is no longer reflected back along the sensor axis and the operating distance is reduced. The greater the distance between the sensor and the target, the greater the effect. Detection is not possible when the angle exceeds ± 10°.
- the shape of the object to be detected: similar to the example above, an excessively angular object can be difficult to detect 1. In this case, use reflex mode detection.

Detection systems

Diffuse mode

In this mode, it is the object itself that reflects the ultrasonic wave back to the sensor which, in turn, switches its output. It is the most widely used and the most simple mode. In this mode, the object will not be detected in the blind zone.

Reflex or beam break mode

The sensor is in a permanently detecting state on a fixed background of the machine and when the object to be detected breaks the acoustic beam the output switches state 2. This mode is particularly recommended in cases where the shape of the object changes (irregular, angular, non perpendicular) and also for objects that absorb sound (see above). This mode can be achieved by using a diffuse mode sensor (with background teaching) or, more simply, by using a ready to use reflex mode sensor.

In cases where space is restricted, a reflector 3 and 4, angled at 45°, can be used. This system can be used for both the diffuse and reflex modes. This reflector can be a flat part of the machine or a separate element. In this mode, the background of the machine must not be within the blind zone. But if the object is within this zone, it will be reliably detected.

Thru-beam mode

Detection is achieved using both a transmitter and receiver, with the transmitter permanently transmitting an acoustic wave to the receiver. The breaking of the beam by the presence of an object switches the output of the receiver. This mode provides long detection distances 5. In this mode there is no blind zone.

Ultrasonic sensors

XX range, General purpose
Cylindrical, plastic or metal
DC supply, solid-state digital output

121383



XX512A1KAM8

PF131112



XX518A1KAM12

PF511482



XXV18B1PAM12

| Diffuse mode | | | | | |
|-----------------|----------------------------|----------------------|----------------------|----------------------|--------------|
| Ø 12 sensors | | | | | |
| Sensors | Sensing distance (Sn) m | Function/output | Connection | Reference | Weight kg |
| Ø 12 Plastic | 0.05 | NO/PNP + NO/NPN | M8 connector | XX512A1KAM8 | 0.011 |
| | 0.1 | NO/NPN | M8 connector | XX512A2NAM8 | 0.011 |
| | | NO/PNP | M8 connector | XX512A2PAM8 | 0.011 |
| Ø 18 sensors | | | | | |
| Ø 18 Plastic | 0.15 | NO/PNP + NO/NPN | M12 connector | XX518A1KAM12 | 0.033 |
| Ø 18 Metal | 0.05 | NO/NPN | Pre-cabled (L = 2 m) | XXV18B1NAL2 | 0.110 |
| | | | M12 connector | XXV18B1NAM12 | 0.050 |
| | NO/PNP | Pre-cabled (L = 2 m) | XXV18B1PAL2 | 0.110 | |
| | | | Pre-cabled (L = 5 m) | XXV18B1PAL5 | 0.200 |
| | | | M12 connector | XXV18B1PAM12 | 0.050 |
| | NC/NPN | Pre-cabled (L = 5 m) | XXV18B1NBL5 | 0.200 | |
| | | | NC/PNP | Pre-cabled (L = 2 m) | XXV18B1PBL2 |
| M12 connector | XXV18B1PBM12 | 0.050 | | | |
| Thru-beam mode | | | | | |
| Ø 12 sensors | | | | | |
| Transmitter | 0.2 | – | M8 connector | XXT12A8M8 | 0.020 |
| Receiver | 0.2 | NO/PNP + NO/NPN | M8 connector | XXR12A8KAM8 | 0.020 |

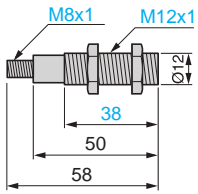
| Sensor type | | XX512A1● | XX512A2● | XX●12A8● | XXV18B1● | XX518A1● |
|--|--------------------------|--|-------------|-------------|-----------------------------------|-----------------------------------|
| General characteristics | | | | | | |
| Conformity to standards | | CE, IEC 60947-5-2 | | | | |
| Product certifications | | UL | UL | UL | cULus | cULus |
| Nominal sensing distance (Sn) | | m 0.05 | 0.1 | 0.2 | 0.05 | 0.15 |
| Blind zone (in diffuse mode the object is not detected in this zone, in reflex mode the background is not detected in this zone) | | mm 0...6.4 | 0...6.4 | – | 0...2 | 0... 19 |
| Detection window | | Fixed | | | | Fixe |
| Detection system | Diffuse mode | ● | ● | – | ● | ● |
| | Reflex mode | – | – | – | – | – |
| | Thru-beam mode | – | – | ● | – | – |
| Transmission frequency (transmitter resonance) | | kHz 500 | | | 360 | 200 |
| Differential travel | | mm < 0.7 | < 0.7 | – | < 3 | – |
| Repeat accuracy | | mm ± 0.7 | | ± 0.79 | ± 1.5 | ± 0.79 |
| Overall beam angle (see detection lobe) | | 11° | 10° | 10° | 10° | 20 |
| Minimum size of object to be detected | | | | | | |
| Cylinder Ø (in mm), at distance (in mm) | | Ø 2.5 at 38 | Ø 2.5 at 50 | Ø 12 at 200 | Ø 2.5 at 20 | Ø 1.6 at 63 |
| Deviation angle from 90° of the object to be detected | | ± 10° | ± 10° | – | ± 8° | ± 10° |
| Materials | Case | ULTEM® | | | Nickel plated brass | ULTEM® |
| | | Stainless steel 303 for XX630AS1●●●● | | | | |
| | Sensing face (1) | Epoxy | | | Epoxy | Silicone |
| Connection | Connector | M8, 4-pin | M8 3-pin | M8, 4-pin | M12, 4-pin | M12, 4-pin |
| | Pre-cabled (wire c.s.a.) | – | – | – | 3 x 0.34 mm ² / AWG 22 | – |
| Supply characteristics | | | | | | |
| Rated supply voltage | | V 12...24 V $\overline{\text{---}}$ with protection against reverse polarity | | | | |
| Voltage limits (including ripple) | | V $\overline{\text{---}}$ 10...28 V | | | $\overline{\text{---}}$ 10...36 V | $\overline{\text{---}}$ 10...28 V |
| Current consumption, no-load | | mA 25 | 50 | 15 | 60 | |
| Output characteristics | | | | | | |
| LED indicators | Output state | Yellow LED | | | | – |
| | Power on | Green LED | | | | – |
| | Setting-up assistance | – | – | – | – | – |
| Switching capacity (with overload and short-circuit protection) | | mA < 100 | | | | < 200 |
| Voltage drop | | V < 1 (NPN), < 1.5 (PNP), 1.1 for XX●12A8, < 2 for XXV18B1●, 0.5 for XX630A2● | | | | |
| Maximum switching frequency | | Hz 125 | 125 | 125 | 80 | 80 |
| Delays | First-up | ms 20 | 20 | 20 | 5 | 350 |
| | Response | ms 2 | 3 | 0.4 | 4 | 3 |
| | Recovery | ms 2 | 3 | 0.4 | 4 | 3 |
| Environment characteristics | | | | | | |
| Degree of protection | | Conforming to IEC 60529 and IEC 60947-5-2 | | | IP 67 | IP 65 IP 67 or (2) |
| Storage temperature | | °C - 40...+ 80 | | | | |
| Operating temperature | | °C - 20...+ 65 | | | 0...+ 60 | 0...+ 50 |
| Vibration resistance | | Conforming to IEC 60068-2-6 | | | | |
| Mechanical shock resistance | | Conforming to IEC 60068-2-27 | | | | |
| Resistance to electromagnetic interference | | Conforming to IEC 60947-5-2 | | | | |

(1) Silicone face for optimum chemical resistance.

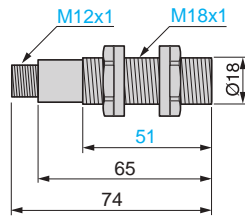
(2) Double insulation for pre-cabled sensors. IP 69K for sensors with M12 connector.

Dimensions

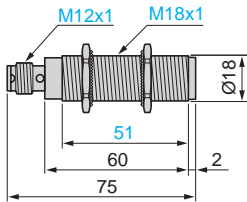
XX●12A●●●M8



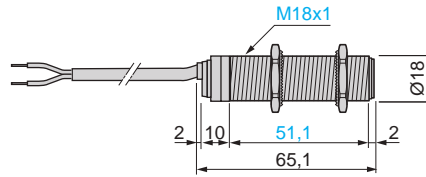
XX518A1KAM12
XXT18A●M12
XXR18A●●●●●



XXV18B1●●●M12



XXV18B1●●L●

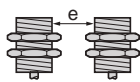


Setting-up precautions

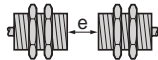
Minimum mounting distances

Diffuse sensors, cylindrical type

Side by side



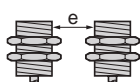
Face to face



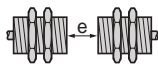
e: respect the distances indicated on the detection curves

$e \geq 4 \times S_n$

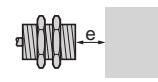
XXV18●



$e > 25 \text{ mm}$

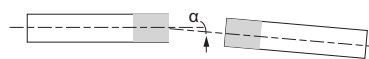


$e > 700 \text{ mm}$



$e > 60 \text{ mm}$

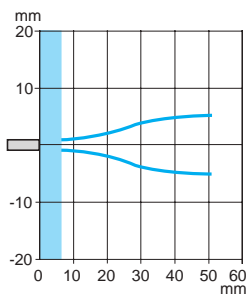
Thru-beam sensors



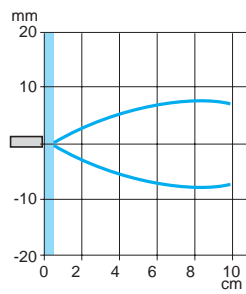
| Sensors | α |
|-------------------|----------------|
| XX●12●●/XX●F1●● | $\pm 5^\circ$ |
| XX●18A4●●/XX●K1A4 | $\pm 10^\circ$ |
| XX●18A2●●/XX●K1A2 | |

Curves

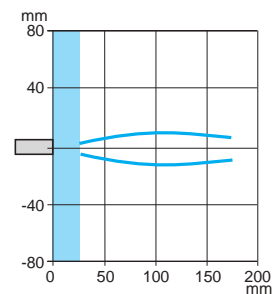
XX512A1KAM8



XX512A2●NAM8



XX518A1KAM12



Ultrasonic sensors

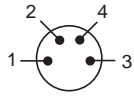
XX range, General purpose
Cylindrical, plastic or metal
DC supply, solid-state digital output

Schemes

Digital output, Ø 12 sensor, M8 connector

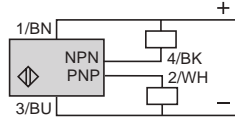
XX512A1KAM8

4-wire type



1 (+)
3 (-)
2 PNP output
4 NPN output

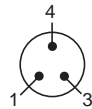
NO outputs, PNP and NPN



(-) BU (Blue) (+) BN (Brown)
WH (White) BK (Black)

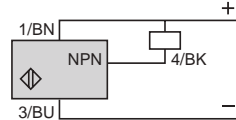
XX512A2●

3-wire type



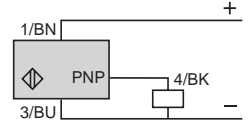
1 (+)
3 (-)
4 NPN or PNP output

NO outputs, NPN



(-) BU (Blue) (+) BN (Brown)
BK (Black)

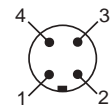
NO outputs, PNP



Digital output, Ø 18 sensor, M12 connector, Ø 30 (XX6V3●, XXBV3●)

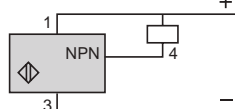
XXV18B1●●●M12

3-wire type

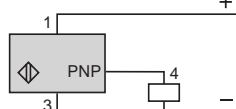


1 (+)
3 (-)

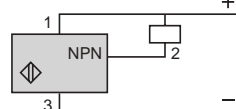
NO outputs, NPN



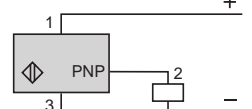
NO outputs, PNP



NC outputs, NPN



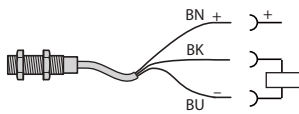
NC outputs, PNP



Digital output, Ø 18 sensor, pre-cabled

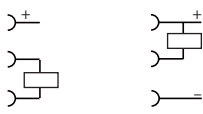
XXV18B1●●●L●

3-wire type



(-) BU (Blue) (+) BN (Brown)

PNP/NO, NC

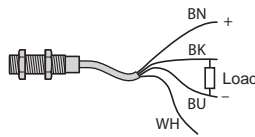


BK (Black)

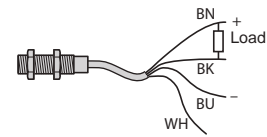
NPN/NO, NC

XX518A3●●●L2

PNP output



NPN output

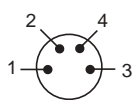


Thru-beam sensors: XXT12●/XXR12●, XXT18●/XXR18●, XXTF1●/XXRF1●

Transmitter

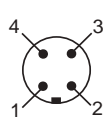
XXT12A8M8, XXT18A3M12

M8

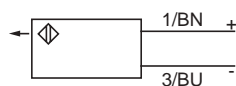


1 (+)
3 (-)

M12



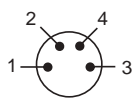
1 (+)
3 (-)



Receiver

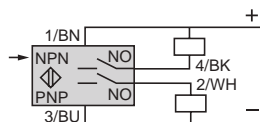
XXR12A8KBM8

M8



1 (+)
2 (PNP)
3 (-)
4 (NPN)

NPN, PNP, NO



Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal

DC supply, solid-state digital or analog output



XX518A3NAL2



XX918A3C2M12



XXT18A3M12



XXZPB100

Diffuse mode

Ø 18 sensors, digital output

| Sensors | Sensing distance (Sn) m | Function/output | Connection | Reference | Weight kg |
|--------------|----------------------------|-----------------|----------------------|---------------------|--------------|
| Ø 18 Plastic | 0.5 (adjustable) | NO/NPN | Pre-cabled (L = 2 m) | XX518A3NAL2 | 0.08 |
| | | NO/PNP | Pre-cabled (L = 2 m) | XX518A3PAL2 | 0.08 |
| | | NO/NPN | M12 connector | XX518A3NAM12 | 0.033 |
| | | NO/PNP | M12 connector | XX518A3PAM12 | 0.033 |

Ø 18 sensors, analog output

| | | | | | |
|--------------|-----|---------|---------------|---------------------|-------|
| Ø 18 Plastic | 0.5 | 4-20 mA | M12 connector | XX918A3C2M12 | 0.033 |
| | | 0-10 V | M12 connector | XX918A3F1M12 | 0.033 |

Thru-beam mode

Ø 18 sensors, digital output

| | | | | | |
|-------------|------|-----------------|---------------|---------------------|------|
| Transmitter | 0.61 | - | M12 connector | XXT18A3M12 | 0.04 |
| Receiver | 0.61 | NO/PNP + NO/NPN | M12 connector | XXR18A3KAM12 | 0.04 |
| Transmitter | 1 | - | M12 connector | XXT18A4M12 | 0.04 |
| Receiver | 1 | NO/PNP + NO/NPN | M12 connector | XXR18A4KAM12 | 0.04 |

Accessories

Teach pushbutton

| Teach pushbutton | For use with sensors | Reference | Weight kg |
|---|-------------------------------|-----------------|--------------|
| Selection of detection window Length of cable: 152 mm Input: M12 female connector Output: M12 male connector | XX918A● XX9V3A● XX9D1A● | XXZPB100 | 0.035 |

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal

DC supply, solid-state digital or analog output

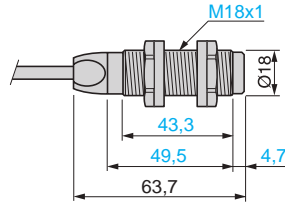
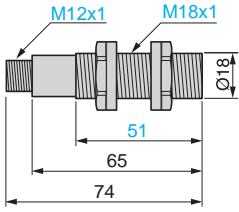
| Sensor type | | XX●18A3● | XX518A3● |
|--|--------------------------|-------------------------------|--|
| General characteristics | | | |
| Conformity to standards | | CE, IEC 60947-5-2 | |
| Product certifications | | UL | UL, cCSAus |
| Nominal sensing distance (Sn) | | m 0.6 | 0.5 |
| Blind zone (in diffuse mode the object is not detected in this zone, in reflex mode the background is not detected in this zone) | | mm – | 0 ... 51 (XX518A3●) |
| Detection window | | Fixed | Remotely adjustable or by using teach button |
| Detection system | Diffuse mode | – | ● |
| | Reflex mode | – | ● |
| | Thru-beam mode | ● | – |
| Transmission frequency (transmitter resonance) | | kHz 300 | 300 |
| Differential travel | | mm < 2.5 | < 2.5 |
| Repeat accuracy | | mm ± 1.27 | ± 1.27 |
| Overall beam angle (see detection lobe) | | 6° | 6° |
| Minimum size of object to be detected | | – | |
| Cylinder Ø (in mm), at distance (in mm) | | Ø 38 to 600 Ø 114 to 1 000 | Ø 2.5 to 150 |
| Deviation angle from 90° of the object to be detected | | – | ± 7° |
| Materials | Case | ULTEM® | Valox® |
| | Sensing face (1) | Silicone | Epoxy |
| Connection | Connector | M12, 4-pin | M12, 4-pin |
| | Pre-cabled (wire c.s.a.) | – | 4 x 0.08 mm ² / AWG 28 |

(1) Silicone face for optimum chemical resistance.

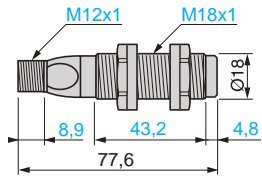
Dimensions

XX518A3●AM12, XXT18A●M12, XXR18A●KAM12

XX518A3●AL2



XX918A3●M12

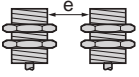


Setting-up precautions

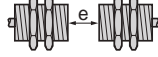
Minimum mounting distances

Diffuse sensors, cylindrical type

Side by side



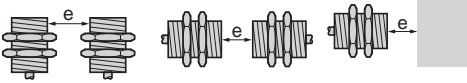
Face to face



e: respect the distances indicated on the detection curves

$$e \geq 4 \times S_n$$

XXV18●

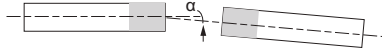


$e > 25 \text{ mm}$

$e > 700 \text{ mm}$

$e > 60 \text{ mm}$

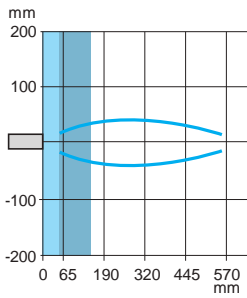
Thru-beam



| Sensors | α |
|-------------------|----------------|
| XX●18A4●●/XX●K1A4 | $\pm 10^\circ$ |

Curves

XX518A3●●L2,
XX518A3●AM12,
XX918A3●●M12



Blind zone for diffuse sensors.

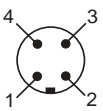
Blind zone for reflex sensors.

Schemes

Digital output, $\varnothing 18$ sensor, M12 connector

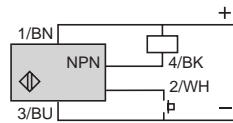
XX518A3●

3-wire type



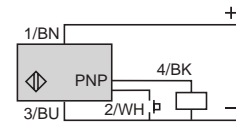
1 (+) 2 Teach input (WH)
3 (-) 4 NPN or PNP output

NO outputs, NPN



(-) BU (Blue) (+) BN (Brown)
BK (Black)

NO outputs, PNP



Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 18 mm

Diffuse mode, solid-state digital or analog output

Configurable by software



XXA18P1•M12



XXS18P1•M12



XXA18B1•M12
XXA18S1•M12



XXS18B1•M12
XXS18S1•M12



XXZPB100

Diffuse mode

Sensors with solid-state digital output, M12 connector

| Sensors | Sensing distance (Sn) Adjustable | Function/output | Sensing axis | Reference | Weight |
|---------------------------|-------------------------------------|-------------------|--------------|-------------|--------|
| | | | | | kg |
| Ø 18 Plastic | 1 | NO or NC (1)/ PNP | Straight | XXS18P1PM12 | 0.033 |
| | | | 90° angled | XXA18P1PM12 | 0.040 |
| Ø 18 Nickel-plated brass | 1 | NO or NC (1)/ PNP | Straight | XXS18B1PM12 | 0.050 |
| | | | 90° angled | XXA18B1PM12 | 0.055 |
| Ø 18 Stainless steel 316L | 1 | NO or NC (1)/ PNP | Straight | XXS18S1PM12 | 0.050 |
| | | | 90° angled | XXA18S1PM12 | 0.055 |

Sensors with analog output, M12 connector

| Sensors | Sensing distance (Sn) Adjustable | Analog output (2) | Sensing axis | Reference | Weight | | |
|---------------------------|-------------------------------------|--------------------------|--------------|-------------|------------|-------------|-------|
| | | | | | kg | | |
| Ø 18 Plastic | 1 | 4-20 mA | Straight | XXS18P1AM12 | 0.033 | | |
| | | | 90° angled | XXA18P1AM12 | 0.040 | | |
| | | 0-10 V | Straight | XXS18P1VM12 | 0.033 | | |
| | | | 90° angled | XXA18P1VM12 | 0.040 | | |
| | | Ø 18 Nickel-plated brass | 1 | 4-20 mA | Straight | XXS18B1AM12 | 0.050 |
| | | | | | 90° angled | XXA18B1AM12 | 0.055 |
| Ø 18 Stainless steel 316L | 1 | 4-20 mA | Straight | XXS18S1AM12 | 0.050 | | |
| | | | 90° angled | XXA18S1AM12 | 0.055 | | |

Accessories

| Description | For use with sensor | Reference | Weight kg |
|---|---------------------|-----------|-----------|
| Teach pushbutton Input: M12 female connector Output: M12 male connector | XXS18●● XXA18●● | XXZPB100 | 0.035 |

Configuration interface and configuration kit for the synchronization function

See page 78.

(1) Output function (NO or NC) and mode (window, reflex, proximity, pump) are selectable using the XXZPB100 remote teach pushbutton.

(2) Selectable using the XXZPB100 remote teach pushbutton.

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 18 mm

Diffuse mode, solid-state digital or analog output

Configurable by software



Accessories

| Description | Type | Length m | Reference | Weight kg |
|-------------|------|----------|-----------|-----------|
|-------------|------|----------|-----------|-----------|

Connection accessories for synchronization function

| | | | | |
|--|----------|----|----------------------|-------|
| Pre-wired connector 5-pin, 5-wire female M12 connector/ bare wires PVC cable | Straight | 2 | XZCPV11V12L2 | 0.090 |
| | | 5 | XZCPV11V12L5 | 0.201 |
| | | 10 | XZCPV11V12L10 | 0.360 |
| | Elbowed | 2 | XZCPV12V12L2 | 0.090 |
| | | 5 | XZCPV12V12L5 | 0.201 |
| | | 10 | XZCPV12V12L10 | 0.360 |

Connection accessories without synchronization function

| | | | | |
|--|----------|----|---------------------|-------|
| Pre-wired connector 5-pin, 4-wire female M12 connector/ bare wires PVC cable | Straight | 2 | XZCP1141L2 | 0.090 |
| | | 5 | XZCP1141L5 | 0.190 |
| | | 10 | XZCP1141L10 | 0.370 |
| | Elbowed | 2 | XZCP1241L2 | 0.090 |
| | | 5 | XZCP1241L5 | 0.190 |
| | | 10 | XZCP1241L10 | 0.370 |
| Female M12 connector 5-pin, Pg 7 cable gland | Straight | – | XZCC12FDM50B | 0.020 |
| | Elbowed | – | XZCC12FCM50B | 0.020 |

Mounting accessory

| Description | For use with sensor | Reference | Weight kg |
|------------------|---------------------|----------------|-----------|
| Fixing clamp (1) | XXS18●● XXA18●● | XXZB118 | 0.010 |

(1) Recommended to use in applications below 0°C.

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 18 mm

Diffuse mode, solid-state digital or analog output

Configurable by software

| Sensor type | | XX●18●1PM12 | XX●18●1AM12 | XX●18●1VM12 |
|---|--------------|--|---|--|
| General characteristics | | | | |
| Conformity to standards | | EN/IEC 60947-5-2, UL 508, and CSA C22.2 n°14 | | |
| Compliance with regulations | | CE (based on EMC directive 2014/30/EU), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | |
| Product certifications | | cULus with class 2 power supply, E2, EAC, and RCM | | |
| Nominal sensing distance (Sn) | | m | 1 (adjustable) | |
| Blind zone (in diffuse mode the object is not detected in this zone) | | m | 0.105 | |
| Detection window | | Remotely adjustable or by using external teachbutton XXZPB100 | | |
| Transmission frequency (transmitter resonance) | | kHz | 200 | |
| Differential travel | | mm | < 5 | – |
| Repeat accuracy (repeatability) | | 0.1 % | | |
| Minimum size of object to be detected | | Cylinder Ø 1 mm up to sensing distance of 0.6 m | | |
| Tilt angle with 100 x 100 mm target | | ± 7° at 1 m, ± 35° at 0.5 m, ± 10° at 0.9 m | | |
| Materials | Case | XX●18P●●: PBT XX●18B●●: Nickel-plated brass XX●18S●●: Stainless steel 316L | | |
| | Sensing face | Epoxy, polyurethane, and butyl | | |
| Connection | | M12 connector - 5-pin | | |
| Supply characteristics | | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | | V | 12...24 V $\overline{\text{---}}$ | 24 V $\overline{\text{---}}$ |
| Voltage limits (including ripple) | | V | 10...30 V $\overline{\text{---}}$ | 10...30 V $\overline{\text{---}}$ |
| Current consumption, no-load | | mA | < 30 | < 30 |
| Output characteristics | | | | |
| LED indicators | Output state | | Yellow LED | Yellow LED |
| | Echo state | | Green LED | Green LED |
| Switching capacity (with overload and short-circuit protection) | | | < 100 mA | – |
| Resistive load impedance | | Ω | – | 12 V $\overline{\text{---}}$, load ≤ 250 Ω 24 V $\overline{\text{---}}$, load ≤ 850 Ω |
| Voltage drop | | V | < 2 | – |
| Internal temperature compensation | | | Yes | Yes |
| Maximum switching frequency | | Hz | 11 | – |
| Delays | First-up | ms | 120 | 180 |
| | Response | ms | 45 | – |
| | Recovery | ms | 45 | 100 |
| Environment characteristics | | | | |
| Degree of protection Conforming to IEC 60529 and EN/IEC 60947-5-2 | | | IP 65, IP 67 | |
| Storage temperature | | °C | -40...+80 | |
| Operating temperature | | °C | -25...+70 (1) | |
| Relative humidity | | | < 95%, without condensation | |
| Vibration resistance Conforming to IEC 60068-2-6 | | | Amplitude ± 1 mm (f = 10...55 Hz) | |
| Mechanical shock resistance Conforming to IEC 60068-2-27 | | | 30 gn, duration 11 ms, in all 3 axes | |
| Resistance to electromagnetic interference | | | Conforming to EN/IEC 60947-5-2 and UNECE R10-05 | |

(1) For applications below 0°C, it is recommended to use the **XXZB118** fixing clamp (see page 31).

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 18 mm

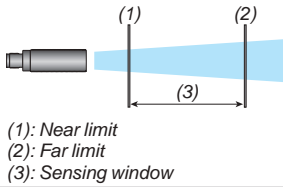
Diffuse mode, solid-state digital or analog output

Configurable by software

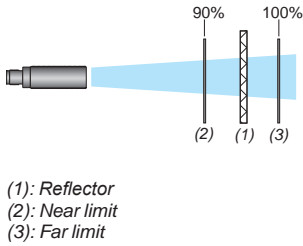
Operating diagrams for digital output sensors

Settings with teach procedure

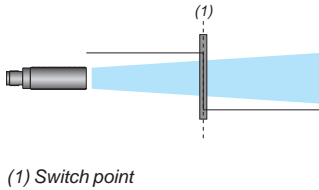
Window mode



Reflex mode

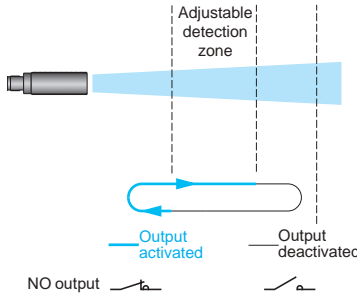


Proximity mode

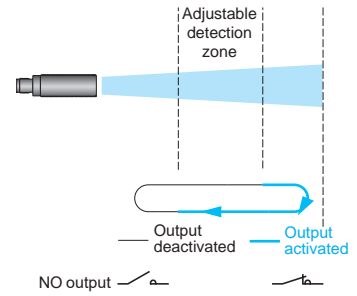


Pump/Hysteresis mode

Emptying (stored in high threshold memory)



Filling (stored in low threshold memory)



Operating diagram for analog output sensors

Near and far limits setting with teach procedure

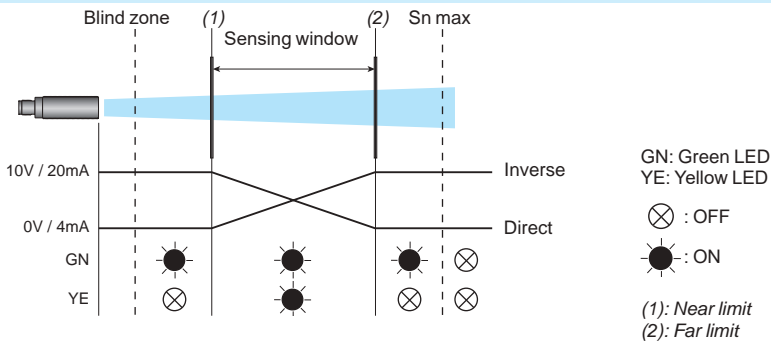
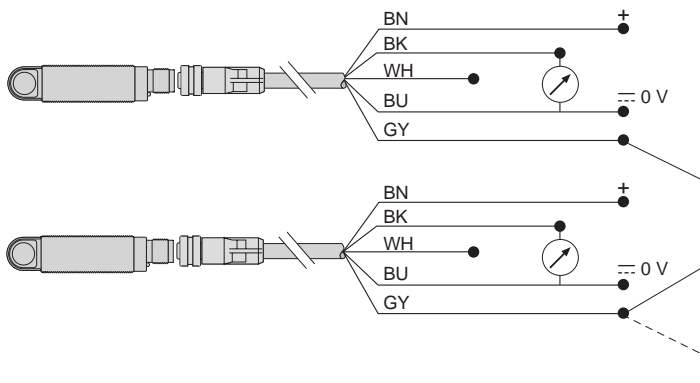


Diagram for the synchronization function (side by side application)



NB: To enable synchronization between several sensors, all of the wires of pin no.5 (gray) must be electrically connected together. A maximum of 8 sensors can be synchronized. To enable "Multiplexer" function for the sensors, use the XX Configuration Software. Without synchronization or multiplexing, the sensors must be at least 50 cm away from each other in order to avoid mutual interference.

Ultrasonic sensors

XX range, General purpose

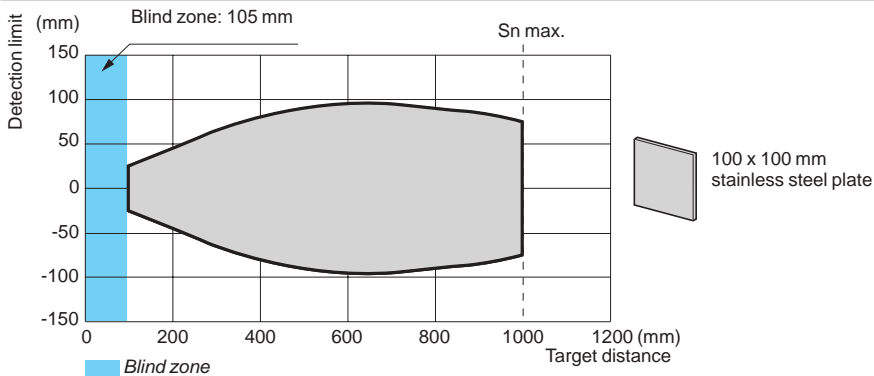
Cylindrical, plastic or metal, Ø 18 mm

Diffuse mode, solid-state digital or analog output

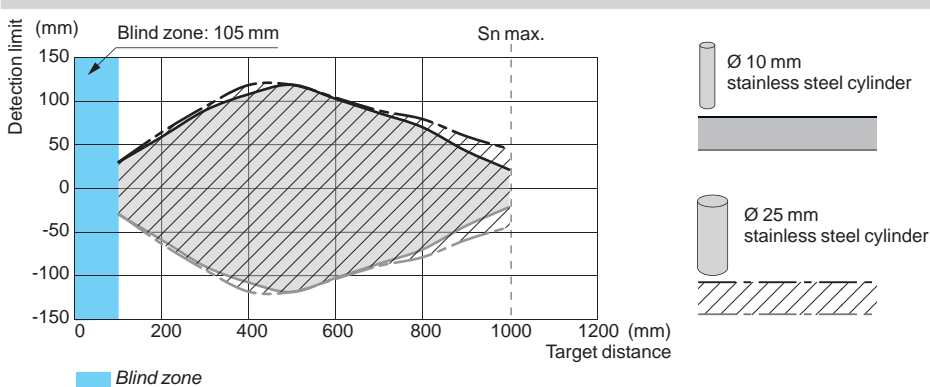
Configurable by software

Curves

Detection curve with 100 x 100 mm square target



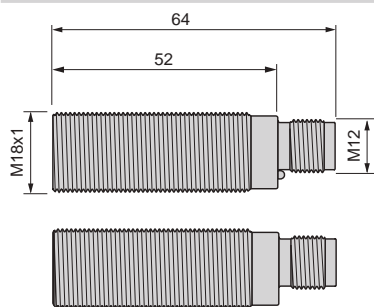
Detection curve with round bar



Dimensions

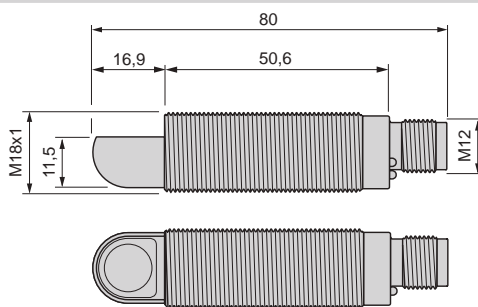
Plastic sensors, straight

XXS18P1●M12



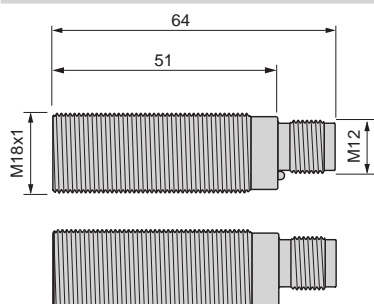
Plastic sensors, 90° angled

XXA18P1●M12



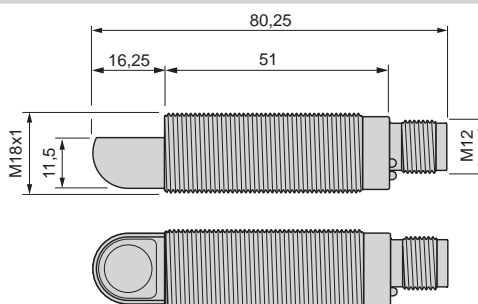
Nickel-plated brass and stainless steel sensors, straight

XXS18B1●M12 and XXS18S1●M12



Nickel-plated brass and stainless steel sensors, 90° angled

XXA18B1●M12 and XXA18S1●M12



Ultrasonic sensors

XX range, General purpose

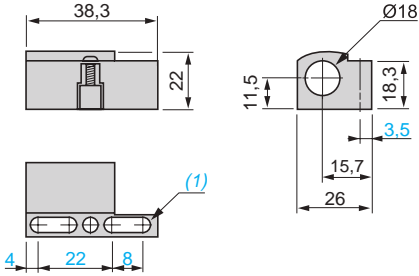
Cylindrical, plastic or metal, Ø 18 mm

Diffuse mode, solid-state digital or analog output

Configurable by software

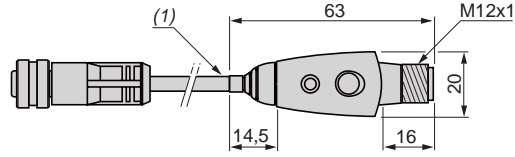
Dimensions (continued)

Fixing clamp XXZB118



(1) 2 elongated holes Ø 4 X 8 mm

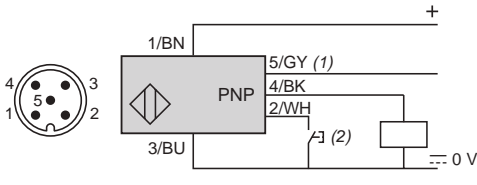
Teach pushbutton XXZPB100



(1) Cable length: 152 mm

Connections

Connector wiring



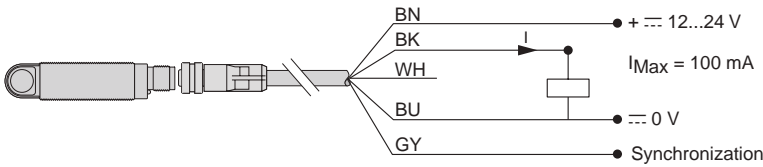
| Pin number | Wire color | Digital output description | Analog output description | |
|------------|------------|------------------------------------|------------------------------------|------------------------------------|
| | | | 4-20 mA | 0-10 V |
| 1 | BN: Brown | +12...24 V $\overline{\text{---}}$ | +12...24 V $\overline{\text{---}}$ | +14...24 V $\overline{\text{---}}$ |
| 2 | WH: White | Input teach | | |
| 3 | BU: Blue | 0 V $\overline{\text{---}}$ | | |
| 4 | BK: Black | Output | | |
| 5 | GY: Gray | Synchronization | | |

(1) Synchronization.

(2) External setting pushbutton or XXZPB100 remote teach pushbutton (see page 30).

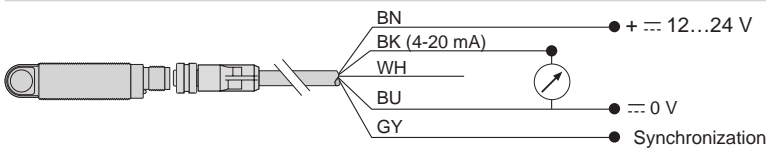
Wiring scheme (digital output NO or NC)

XXS18•1PM12 and XXA18•1PM12



Wiring scheme (analog output 4-20 mA)

XXS18•1AM12 and XXA18•1AM12

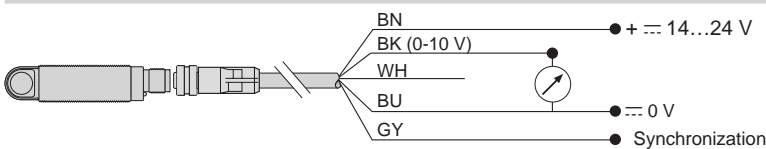


4-20 mA:

- For 12 V $\overline{\text{---}}$, load $\leq 250 \Omega$
- For 24 V $\overline{\text{---}}$, load $\leq 850 \Omega$

Wiring scheme (analog output 0-10 V)

XXS18•1VM12 and XXA18•1VM12



0-10 V:

1 k Ω ... ∞

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal

DC supply, solid-state digital or analog output



Diffuse mode

Solid-state digital output, M12 connector

| Sensors | Sensing distance (Sn) m | Function/output | Reference | Weight kg |
|-----------------------------|----------------------------|-----------------|--------------|--------------|
| Ø 30 Plastic | 1 (adjustable) | NO/PNP + NO/NPN | XX630A1KAM12 | 0.09 |
| | | NO/NPN | XX6V3A1NAM12 | 0.09 |
| | | NO/PNP | XX6V3A1PAM12 | 0.09 |
| | 2 (adjustable) | NO/NPN + NC/NPN | XX630A1NCM12 | 0.09 |
| | | NO/PNP + NC/PNP | XX630A1PCM12 | 0.09 |
| | | NO/NPN + NC/NPN | XX630A2NCM12 | 0.09 |
| 8 (adjustable) | NO/NPN + NC/NPN | XX630A3NCM12 | 0.11 | |
| | NO/PNP + NC/PNP | XX630A3PCM12 | 0.11 | |
| Ø 30 Stainless steel 303 | 1 (adjustable) | NO/NPN + NC/NPN | XX630S1NCM12 | 0.09 |
| | | NO/PNP + NC/PNP | XX630S1PCM12 | 0.09 |

Standard analogue output, M12 connector

| Sensors | Sensing distance (Sn) m | Analogue output (Slope selection using teach button) | Reference | Weight kg |
|-----------------------------|----------------------------|--|--------------|--------------|
| Ø 30 Plastic | 1 | 4-20 mA | XX930A1A2M12 | 0.095 |
| | | 0-10 V | XX930A1A1M12 | 0.095 |
| | | 4-20 mA | XX9V3A1C2M12 | 0.090 |
| | | 0-10 V | XX9V3A1F1M12 | 0.090 |
| | 2 | 4-20 mA | XX930A2A2M12 | 0.095 |
| | | 0-10 V | XX930A2A1M12 | 0.095 |
| 8 | 4-20 mA | XX930A3A2M12 | 0.115 | |
| | 0-10 V | XX930A3A1M12 | 0.115 | |
| Ø 30 Stainless steel 303 | 1 | 4-20 mA | XX930S1A2M12 | 0.095 |
| | | 0-10 V | XX930S1A1M12 | 0.095 |

250 ms delayed analogue output (for unstable object), M12 connector

| | | | | |
|-----------------|---|---------|-----------------|-------|
| Ø 30 Plastic | 1 | 4-20 mA | XX930A1A2230M12 | 0.095 |
| | 2 | 4-20 mA | XX930A2A2230M12 | 0.095 |

Ultrasonic sensors

XX range, General purpose
Cylindrical, plastic or metal
DC supply, solid-state digital output

| Sensor type | XX6V3A1● | XX630A1● XX630A2● XX630S1● | XX630A3● | XX930A1● XX930A2● XX930S1● | XX930A3● | XX9V3A1● | |
|--|-------------------|---|---|--------------------------------------|--|--|---|
| General characteristics | | | | | | | |
| Conformity to standards | CE, IEC 60947-5-2 | | | CE, IEC 60947-5-2 | | | |
| Product certifications | UL, cCSAus (1) | | | UL, cCSAus | | | |
| Nominal sensing distance (Sn) | m | 1 | 1 or 2 (2) | 8 | 1 or 2 (3) | 8 | 1 |
| Blind zone (in diffuse mode the object is not detected in this zone, in reflex mode the background is not detected in this zone) | mm | 0...100 | 0...51 (XX630●1) 0...120 (XX630A2●) | 0...300 | 0...51 or 0...120 (3) | 0...300 | 0...100 |
| Detection window | | Remotely adjustable or by using external teach button | Adjustable using teach button on sensor | | Adjustable using teach button on sensor | | Remotely adjustable or by using external teach button |
| Detection system | Diffuse | ● | ● | ● | – | – | – |
| | Reflex | ● | – | – | – | – | – |
| | Thru-beam | – | – | – | – | – | – |
| Transmission frequency (transmitter resonance) | kHz | 180 | 200 | 75 | 200 | 75 | 180 |
| Differential travel | mm | < 2.5 | < 2.5 | < 12.7 | | | |
| Repeat accuracy | mm | ± 1.6 | ± 0.87 | ± 2.54 | ± 0.9 | ± 2.54 | ± 0.9 1.6mm |
| Overall beam angle (see detection lobe) | | 7° | 10° | 16° | 10° | 16° | 7° |
| Minimum size of object to be detected | | Cylinder Ø 50 mm at distance 1 m | Cylinder Ø 1.6 mm at distance 635 mm | Cylinder Ø 51 mm at distance 4732 mm | Cylinder Ø 1.6 mm up to a sensing distance of 635 mm | Cylinder Ø 51 mm up to a sensing distance of 4732 mm | Cylinder Ø 50 mm up to a sensing distance of 1 m |
| Deviation angle from 90° of the object to be detected | | ± 5° | ± 7° or ± 10° (2) | ± 5° | ± 8° | ± 5° | ± 5° |
| Materials | Case | Valox® | ULTEM® | ULTEM® | ULTEM® : XX930A1● and XX930A2● | ULTEM® | Valox® |
| | | Stainless steel 303 for XX630AS1●●●● | | | Stainless steel 303: XX930S1● | – | |
| | Sensing face (4) | Epoxy | Silicone | Epoxy | Silicone | Epoxy | |
| Connection | | M12 connector, 4-pin | | | | | |

(1) Only XX6V3A1●, XX630A1●, XX630A2●, XX630S1● and XX630A3● sensors are cCSAus certified.

(2) The first value is given for XX630A1● and XX630S1●, the second value for XX630A2●.

(3) The first value is given for XX930A1● and XX930S1●, the second value for XX930A2●.

(4) Silicone face for optimum chemical resistance.

Ultrasonic sensors

XX range, General purpose
Cylindrical, plastic or metal
DC supply, solid-state digital output

| Sensor type | | XX6V3A1● | XX630A1● XX630A2● XX630S1● | XX630A3● | XX930A1● XX930A2● XX930S1● | XX930A3● | XX9V3A1● | |
|---|---|---|--|--------------|---|-----------------------------------|-----------------------------------|-----------------|
| Supply characteristics | | | | | | | | |
| Rated supply voltage | V | 12...24 V $\overline{\text{---}}$ with protection against reverse polarity | | | $\overline{\text{---}}$ 15...24 V | $\overline{\text{---}}$ 15...24 V | $\overline{\text{---}}$ 15...24 V | |
| Voltage limits (including ripple) | V | $\overline{\text{---}}$ 10...28 V | | | $\overline{\text{---}}$ 10...28 V | – | | |
| Current consumption, no-load | mA | 60 | 50 or 100 (1) | 50 | 60 or 80 (2) | 60 | 60 | |
| Output characteristics | | | | | | | | |
| LED indicators | Output state | Yellow LED | | | Yellow LED | – | | |
| | Power on | Green LED | | | Green LED | – | | |
| | Setting-up assistance | Multicolour LED | | | Dual colour LED | – | | |
| Slope type | | – | | | Direct or inverse by using teach button XXZPB100 | | | |
| Switching capacity (with overload and short-circuit protection) | mA | < 100 | | | – | – | | |
| Voltage drop | V | < 100 | | | – | – | | |
| Maximum switching frequency | Hz | 70 | 10 or 16 (1) | 2 | – | – | | |
| Delays | First-up | ms | 75 | 720 | 800 | 720 | 1 200 | 75 |
| | Response | ms | 15 | 20 or 25 (1) | 200 | | | |
| | Recovery | ms | 75 | 20 | 200 | 250 (delayed) 50 (standard) | 250 | 180 |
| Resistive load impedance | 4-20 mA | Ω | – | | | 10...500 | | 10...350 |
| | 0-10 V | Ω | – | | | 1 k... ∞ | | 2 k... ∞ |
| Environment characteristics | | | | | | | | |
| Degree of protection | Conforming to IEC 60529 and IEC 60947-5-2 | IP 67 | IP 65 or IP 67 (1) IP67 for plastic versions. IP65 for stainless steel versions. | IP 67 | IP 67 | IP 67 | IP 67 | |
| Storage temperature | °C | - 40...+ 80 | | | | | | |
| Operating temperature | °C | 0...+ 70 | 0...+ 60 or 0...+ 50 (1) | - 20...+ 60 | 0...+ 50 | - 20...+ 60 | 0...+ 70 | |
| Vibration resistance | Conforming to IEC 60068-2-6 | Amplitude \pm 1 mm (f = 10...55 Hz); \pm 2 mm for XXV18B1● | | | Amplitude \pm 1 mm (f = 10...55 Hz) | | | |
| Mechanical shock resistance | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes 50 gn, duration 11 ms, in all 3 axes for XXV18B1● | | | 30 gn, duration 11 ms, in all 3 axes | | | |
| Resistance to electromagnetic interference | | Conforming to IEC 60947-5-2 | | | | | | |

(1) The first value is given for XX630A1● and XX630S1●, the second value for XX630A2●.

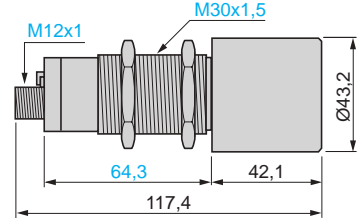
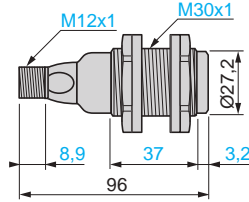
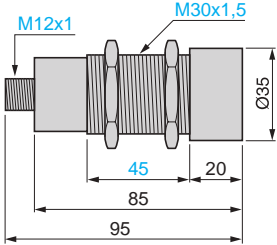
(2) The first value is given for XX930A1● and XX930S1●, the second value for XX930A2●.

Dimensions

XX630A1●●M12
XX630S1●●M12
XX630A2●●M12
XX930A1A●M12
XX230A1●●A00M12
XX230A2●●A00M12

XX6V3A1●AM12
XX9V3A1●●M12

XX630A3●●M12
XX930A3A●M12



Curves

XXV18B1●

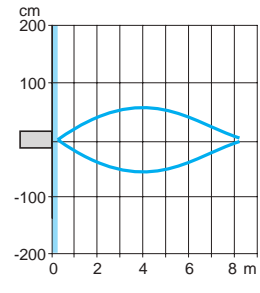
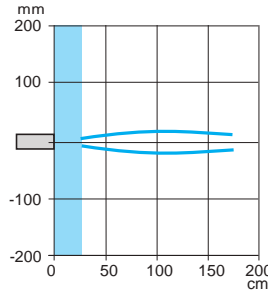
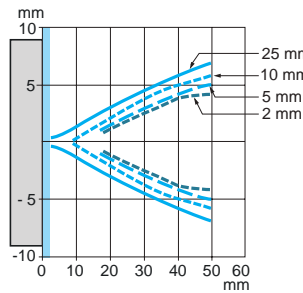
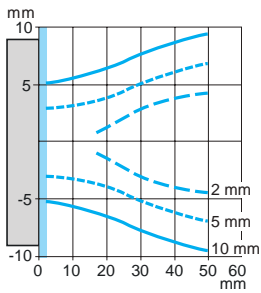
Square object

Cylindrical object

XX630A2●CM12

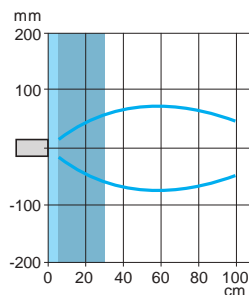
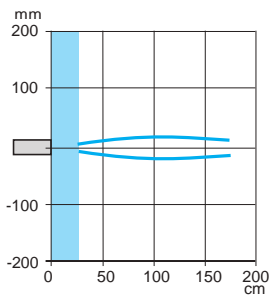
XX630A3●CM12

XX930A3●●M12



XX230A2●

XX230A1●, XX630A1●CM12, XX6V3A1●AM12, XX930A1●●M12, XX9V3A1●●M12, XX8D1A1●AM12, XXBD1A1●AM12



Blind zone for diffuse sensors
Blind zone for reflex sensors

Ultrasonic sensors

XX range, Application

Sensors for monitoring 2 levels

Cylindrical plastic case, M18 x 1 and M30 x 1.5

DC supply, solid-state digital output



XX218A3P●M12



XX230A12NA00M12

Sensors for monitoring 2 levels

| Sensors | Sensing distance (Sn) m | Function/output | Reference | Weight kg |
|-----------------------------------|----------------------------|-----------------|------------------------|--------------|
| Ø 18, threaded M18 x 1 | | | | |
| 2 emptying levels | 0.5 (adjustable) | NO/PNP | XX218A3PHM12 | 0.035 |
| 2 filling levels | 0.5 (adjustable) | NO/PNP | XX218A3PFM12 | 0.035 |
| Ø 30, threaded M30 x 1.5 | | | | |
| 2 levels 2 independent outputs | 1 (adjustable) | NO/NPN + NO/NPN | XX230A12NA00M12 | 0.090 |
| | | NO/PNP + NO/PNP | XX230A12PA00M12 | 0.090 |
| 2 emptying levels | 2 (adjustable) | NO/PNP + NO/PNP | XX230A22PA00M12 | 0.090 |
| | | NO/PNP + NO/PNP | XX230A10PA00M12 | 0.090 |
| 2 filling levels | 1 (adjustable) | NO/PNP + NO/PNP | XX230A11PA00M12 | 0.090 |
| | | NO/PNP + NO/PNP | XX230A21PA00M12 | 0.090 |

Accessories

Teach pushbutton

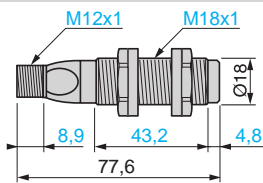
| Teach pushbutton | For use with sensors | Reference | Weight kg |
|---|----------------------|-----------------|--------------|
| Selection of detection window Length of cable: 152 mm Input: M12 female connector Output: M12 male connector | XX218A3● | XXZPB100 | 0.035 |

Other connection and fixing accessories

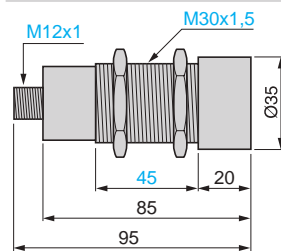
See page 82.

Dimensions

XX218A3P●M12

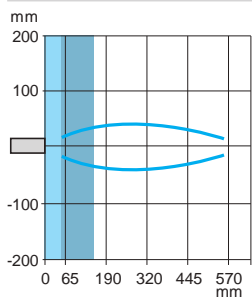


XX230A1●●A00M12
XX230A2●●A00M12

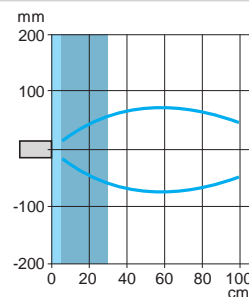


Curves

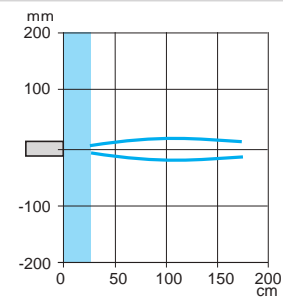
XX218A3●●M12



XX230A1●●●●●M12



XX230A2●●●●●M12



Blind zone for diffuse sensors.

Blind zone for reflex sensors.

Ultrasonic sensors

XX range, Application

Sensors for monitoring 2 levels

Cylindrical plastic case, M18 x 1 and M30 x 1.5

DC supply, solid-state digital output

| Sensor type | | XX218A3●●●● | XX230A1●●●● | XX230A2●●●● |
|---|--|--|--|-----------------|
| General characteristics | | | | |
| Conformity to standards | | CE, IEC 60947-5-2 | | |
| Product certifications | | UL, cCSAus | UL, cCSAus | UL, cCSAus |
| Nominal sensing distance (Sn) | | m 0.50 (adjustable) | 1 (adjustable) | 2 (adjustable) |
| Blind zone (no object must pass through this zone whilst the sensor is operating) | | mm 0...51 | 0...51 | 0...120 |
| Detection window | | Remotely adjustable or by using external teach button | Adjustable using teach button on sensor | |
| Transmission frequency | | kHz 300 | 200 | |
| Differential travel | | mm < 2.5 | < 2.5 | < 2.5 |
| Repeat accuracy | | mm ± 1.27 | ± 0.9 | |
| Overall beam angle (see detection lobe) | | 6° | 10° | 10° |
| Minimum size of object to be detected | | Cylinder Ø 2.5 mm up to a sensing distance of 150 mm | Cylinder Ø 1.6 mm up to a sensing distance of 305 mm | |
| Deviation angle from 90° of the object to be detected | | ± 7° | ± 10° on 305 x 305 mm | |
| Materials | | Case | Valox® | ULTEM® |
| | | Sensing face (1) | Epoxy | Silicone |
| Connection | | Connector | M12, 4-pin | |
| Supply characteristics | | | | |
| Rated supply voltage | | V 12...24 V $\overline{\text{DC}}$ with protection against reverse polarity | | |
| Voltage limits (including ripple) | | V 10...28 V $\overline{\text{DC}}$ | | |
| Current consumption, no-load | | mA 40 | 100 | |
| Output characteristics | | | | |
| LED indicators | | Output state | Yellow LED | Multicolour LED |
| | | Power on | Green LED | – |
| | | Setting-up assistance | Dual colour LED | Multicolour LED |
| | | Distance indication | – | Yellow LED |
| Switching capacity | | mA | < 100 (PNP and NPN) with overload and short-circuit protection | |
| Voltage drop | | V | < 1 (PNP and NPN) | |
| Delays | | First-up | ms 100 | 1000 |
| | | Response | ms 15 | 150 |
| | | Recovery | ms 1000 | 1000 |
| Environment characteristics | | | | |
| Degree of protection | | Conforming to IEC 60529 and IEC 60947-5-2 | IP 67 | IP 65 |
| Storage temperature | | °C | - 40...+ 80 | - 10...+ 80 |
| Operating temperature | | °C | - 20...+ 65 | 0...+ 50 |
| Vibration resistance | | Conforming to IEC 60068-2-6 | Amplitude ± 1 mm (f = 10...55 Hz) | |
| Mechanical shock resistance | | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes | |
| Resistance to electromagnetic interference | | | Conforming to IEC 60947-5-2 | |

(1) Silicone face for optimum chemical resistance.

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm

Diffuse mode, solid-state digital or analog output

Configurable by software



Diffuse mode

Sensors with solid-state digital output, M12 connector

| Sensors | Sensing Function/ distance output (Sn) | Sensing axis | Reference | Weight | |
|--------------------------------|--|----------------------|------------------|--------------|-------------|
| | | | | kg | |
| Ø 30 Plastic | 1 | NO or NC (1)/PNP | Straight | XXS30P1PM12 | 0.047 |
| | | | 90° angled | XXA30P1PM12 | 0.100 |
| | 2 | NO or NC (1)/PNP | Straight | XXS30P2PM12 | 0.095 |
| | | | 90° angled | XXA30P2PM12 | 0.100 |
| | 4 | NO or NC (1)/PNP | Straight | XXS30P4PM12 | 0.115 |
| | 8 | NO or NC (1)/PNP x 2 | Straight | XXS30P8PPM12 | 0.210 |
| NO or NC (1)/NPN x2 | | Straight | XXS30P8NNM12 | 0.210 | |
| Ø 30 Nickel-plated brass | 1 | NO or NC (1)/PNP | Straight | XXS30B1PM12 | 0.165 |
| | | | 90° angled | XXA30B1PM12 | 0.175 |
| | 2 | NO or NC (1)/PNP | Straight | XXS30B2PM12 | 0.165 |
| | | | 90° angled | XXA30B2PM12 | 0.175 |
| | 4 | NO or NC (1)/PNP | Straight | XXS30B4PM12 | 0.195 |
| | Ø 30 Stainless steel 316L | 1 | NO or NC (1)/PNP | Straight | XXS30S1PM12 |
| | | | 90° angled | XXA30S1PM12 | 0.170 |
| 2 | | NO or NC (1)/PNP | Straight | XXS30S2PM12 | 0.160 |
| | | | 90° angled | XXA30S2PM12 | 0.170 |
| 4 | | NO or NC (1)/PNP | Straight | XXS30S4PM12 | 0.190 |

Sensors with analog output, adjustable sensing distance, M12 connector

| Sensors | Sensing Function/ distance output (Sn) | Sensing axis | Reference | Weight | | |
|-----------------|--|--------------|-------------------|-------------|--------------|-------------|
| | | | | kg | | |
| Ø 30 Plastic | 1 | 4-20 mA | Straight | XXS30P1AM12 | 0.047 | |
| | | | | 0-10 V | XXS30P1VM12 | 0.047 |
| | | 90° angled | 4-20 mA | XXA30P1AM12 | 0.100 | |
| | | | 0-10 V | XXA30P1VM12 | 0.100 | |
| | | 2 | 4-20 mA | Straight | XXS30P2AM12 | 0.095 |
| | | | | | 0-10 V | XXS30P2VM12 |
| | 90° angled | | 4-20 mA | XXA30P2AM12 | 0.100 | |
| | | | 0-10 V | XXA30P2VM12 | 0.100 | |
| | 4 | | 4-20 mA | Straight | XXS30P4AM12 | 0.115 |
| | | | | | 0-10 V | XXS30P4VM12 |
| | | 8 | 4-20 mA + PNP (2) | Straight | XXS30P8APM12 | 0.210 |
| | | | 0-10 V + PNP (2) | Straight | XXS30P8VPM12 | 0.210 |

(1) NO or NC: configurable by software (see page 78).

(2) One analogic output and one digital output with NO or NC configurable by software (see page 78).

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm

Diffuse mode, solid-state digital or analog output

Configurable by software



Diffuse mode (continued)

Sensors with analog output, adjustable sensing distance, M12 connector

| Sensors | Sensing distance | Function/ output | Sensing axis | Reference | Weight | |
|---------------------------------|------------------|------------------|--------------|-------------|-------------|-------|
| | (Sn) m | | | | | kg |
| Ø 30 Nickel-plated brass | 1 | 4-20 mA | Straight | XXS30B1AM12 | 0.165 | |
| | | 0-10 V | Straight | XXS30B1VM12 | 0.165 | |
| | | 4-20 mA | 90° angled | XXA30B1AM12 | 0.175 | |
| | 0-10 V | 90° angled | XXA30B1VM12 | 0.175 | | |
| | | 2 | 4-20 mA | Straight | XXS30B2AM12 | 0.165 |
| | | | 0-10 V | Straight | XXS30B2VM12 | 0.165 |
| 4-20 mA | 90° angled | | XXA30B2AM12 | 0.175 | | |
| 0-10 V | 90° angled | XXA30B2VM12 | 0.175 | | | |
| | 4 | 4-20 mA | Straight | XXS30B4AM12 | 0.195 | |
| | | 0-10 V | Straight | XXS30B4VM12 | 0.195 | |
| Ø 30 Stainless steel 316L | 1 | 4-20 mA | Straight | XXS30S1AM12 | 0.160 | |
| | | 0-10 V | Straight | XXS30S1VM12 | 0.160 | |
| | | 4-20 mA | 90° angled | XXA30S1AM12 | 0.170 | |
| | | 0-10 V | 90° angled | XXA30S1VM12 | 0.170 | |
| | 2 | 4-20 mA | Straight | XXS30S2AM12 | 0.160 | |
| | | 0-10 V | Straight | XXS30S2VM12 | 0.160 | |
| | | 4-20 mA | 90° angled | XXA30S2AM12 | 0.170 | |
| | | 0-10 V | 90° angled | XXA30S2VM12 | 0.170 | |
| | 4 | 4-20 mA | Straight | XXS30S4AM12 | 0.190 | |
| | | 0-10 V | Straight | XXS30S4VM12 | 0.190 | |

Accessories

| Teach pushbutton | For use with sensors | Reference | Weight kg |
|---|----------------------|-----------|--------------|
| Selection of detection window Length of cable: 152 mm Input: M12 female connector Output: M12 male connector | XXS30●● XXA30●● | XXZPB100 | 0.035 |

Configuration interface and configuration kit for the synchronization function

See page 78.

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm

Diffuse mode, solid-state digital or analog output

Configurable by software



XZCPV11V12L2



XZCPV12V12L2



XZCPV1164L10



XZCC12FDM50B



XXZB130

Accessories (continued)

| Description | Type | Length | Reference | Weight kg |
|--|----------|--------|---------------|-----------|
| Pre-wired connector 5-pin, 5-wire female M12 connector/bare wires PVC cable | Straight | 2 | XZCPV11V12L2 | 0.090 |
| | | 5 | XZCPV11V12L5 | 0.201 |
| | | 10 | XZCPV11V12L10 | 0.360 |
| | Elbowed | 2 | XZCPV12V12L2 | 0.090 |
| | | 5 | XZCPV12V12L5 | 0.201 |
| | | 10 | XZCPV12V12L10 | 0.360 |

Connection accessories without synchronization function

| | | | | |
|--|----------|----|--------------|-------|
| Pre-wired connector 5-pin, 5-wire female M12 connector/bare wires PVC cable | Straight | 2 | XZCPV1164L2 | 0.090 |
| | | 5 | XZCPV1164L5 | 0.190 |
| | | 10 | XZCPV1164L10 | 0.370 |
| | Elbowed | 2 | XZCPV1264L2 | 0.090 |
| | | 5 | XZCPV1264L5 | 0.201 |
| | | 10 | XZCPV1264L10 | 0.360 |
| Female M12 connector 5-pin, Pg 7 cable gland | Straight | – | XZCC12FDM50B | 0.020 |
| | | | XZCC12FDM50B | 0.020 |

Mounting accessory

| Description | For use with sensor | Weight kg |
|--------------|---------------------|------------------|
| Fixing clamp | XXS30●● XXA30●● | XXZB130 0.010 |

Configuration interface and configuration kit for the synchronization function

See page 78.

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 1 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

| Sensor type | | XXS30P1PM12 | XXS30P1AM12 | XXS30P1VM12 |
|---|--|--|--------------------------------------|--|
| General characteristics | | | | |
| Conformity to standards | | EN/IEC 60947-5-2, UL 508, and CSA C22.2 n°14 | | |
| Compliance with regulations | | CE (based on EMC directive 2014/30/EU), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | |
| Product certifications | | cULus with class 2 power supply, E2, EAC, RCM, and ECOLAB | | |
| Nominal sensing distance (Sn) | | m | 1 (adjustable) | |
| Blind zone (in diffuse mode the object is not detected in this zone) | | m | 0.105 | |
| Detection window | | Remotely adjustable or by using external teachbutton XXZPB100 | | |
| Transmission frequency (transmitter resonance) | | kHz | 200 | |
| Differential travel | | mm | < 5 | – |
| Repeat accuracy (repeatability) | | 0.1 % | | |
| Minimum size of object to be detected | | Cylinder Ø 1 mm up to sensing distance of 0.6m | | |
| Tilt angle with 100 x 100 mm target | | ± 7° at 1 m, ± 10° at 0.9 m ± 35° at 0.5 m | | |
| Materials | | Case | XX●30P●: PBT | |
| | | Sensing face | Epoxy, resin, and rubber | |
| Connection | | M12 connector - 5-pin | | |
| Supply characteristics | | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | | V | ≐ 12...24 V | ≐ 12...24 V |
| Voltage limits (including ripple) | | V | ≐ 10...30 V | ≐ 14...30 V |
| Current consumption, no-load | | mA | < 30 | < 30 |
| Output characteristics | | | | |
| LED indicators | | Output state | Yellow LED | Yellow LED |
| | | Echo state | Green LED | Green LED |
| Switching capacity (with overload and short-circuit protection) | | < 100 mA | | |
| Resistive load impedance | | Ω | – | ≐ 12 V, load ≤ 250 Ω ≐ 24 V, load ≤ 850 Ω |
| Voltage drop | | V | < 2 | – |
| Internal temperature compensation | | Yes | | |
| Maximum switching frequency | | Hz | 11 | – |
| Delays | | First-up | ms | 120 |
| | | Response | ms | 45 |
| | | Recovery | ms | 45 |
| | | | | 180 |
| | | | | 100 |
| | | | | 100 |
| Environment characteristics | | | | |
| Degree of protection | | Conforming to IEC 60529 and EN/IEC 60947-5-2 | IP 65, IP 67 | |
| Storage temperature | | °C | - 40...+ 80 | |
| Operating temperature | | °C | - 25...+ 70 | |
| Relative humidity | | < 95%, without condensation | | |
| Vibration resistance | | Conforming to IEC 60068-2-6 | Amplitude ± 1 mm (f = 10...55 Hz) | |
| Mechanical shock resistance | | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes | |
| Resistance to electromagnetic interference | | Conforming to EN/IEC 60947-5-2 and UNECE R10-05 | | |

Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 1 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

| Sensor type | XXA30P1PM12 XX●30B1PM12 XX●30S1PM12 | XXA30P1AM12 XX●30B1AM12 XX●30S1AM12 | XXA30P1VM12 XX●30B1VM12 XX●30S1VM12 |
|---|--|---|---|
| General characteristics | | | |
| Conformity to standards | EN/IEC 60947-5-2, UL 508, and CSA C22.2 n°14 | | |
| Compliance with regulations | CE (based on EMC directive 2014/30/EU), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | |
| Product certifications | cULus with class 2 power supply, E2, EAC, RCM, and ECOLAB | | |
| Nominal sensing distance (Sn) | m | 1 (adjustable) | |
| Blind zone (in diffuse mode the object is not detected in this zone) | m | 0.155 | |
| Detection window | Remotely adjustable or by using external teachbutton XXZPB100 | | |
| Transmission frequency (transmitter resonance) | kHz | 120 | |
| Differential travel | mm | < 5 | - |
| Repeat accuracy (repeatability) | | 0.1 % | |
| Minimum size of object to be detected | Cylinder Ø 1 mm up to sensing distance of 1m | | |
| Tilt angle with 100 x 100 mm target | ± 12° at 1 m, ± 15° at 0.9 m ± 45° at 0.5 m | | |
| Materials | Case | XX●30P●: PBT XX●30B●: Nickel-plated brass XX●30S●: Stainless steel 316L | |
| | Sensing face | Epoxy, resin, and rubber | |
| Connection | M12 connector - 5-pin | | |
| Supply characteristics | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | V | 12...24 V $\overline{\text{---}}$ | 12...24 V $\overline{\text{---}}$ |
| Voltage limits (including ripple) | V | 10...30 V $\overline{\text{---}}$ | 14...30 V $\overline{\text{---}}$ |
| Current consumption, no-load | mA | < 65 | < 65 |
| Output characteristics | | | |
| LED indicators | Output state | Yellow LED | Yellow LED |
| | Echo state | Green LED | Green LED |
| Switching capacity (with overload and short-circuit protection) | | < 100 mA | - |
| Resistive load impedance | Ω | - | 12 V, load ≤ 250 Ω 24 V, load ≤ 850 Ω |
| Voltage drop | V | < 2 | - |
| Internal temperature compensation | | Yes | Yes |
| Maximum switching frequency | Hz | 11 | |
| Delays | First-up | ms | 120 |
| | Response | ms | 45 |
| | Recovery | ms | 45 |
| Environment characteristics | | | |
| Degree of protection Conforming to IEC 60529 and EN/IEC 60947-5-2 | | IP 65, IP 67 | |
| Storage temperature | °C | - 40...+ 80 | |
| Operating temperature | °C | - 25...+ 70 | |
| Relative humidity | | < 95%, without condensation | |
| Vibration resistance Conforming to IEC 60068-2-6 | | Amplitude ± 1 mm (f = 10...55 Hz) | |
| Mechanical shock resistance Conforming to IEC 60068-2-27 | | 30 gn, duration 11 ms, in all 3 axes | |
| Resistance to electromagnetic interference | | Conforming to EN/IEC 60947-5-2 and UNECE R10-05 | |

Ultrasonic sensors

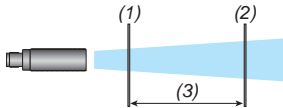
XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 1 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Operating diagrams for digital output sensors

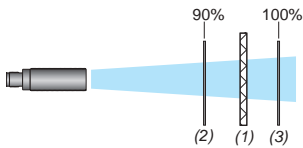
Settings with teach procedure

Window mode



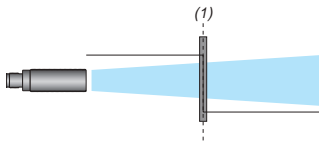
- (1): Near limit
- (2): Far limit
- (3): Sensing window

Reflex mode



- (1): Reflector
- (2): Near limit
- (3): Far limit

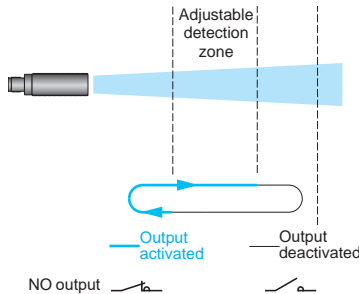
Proximity mode



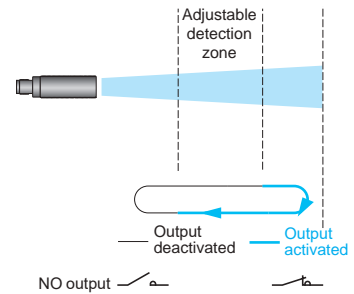
- (1) Switch point.

Pump/Hysteresis mode

Emptying (stored in high threshold memory)



Filling (stored in low threshold memory)



Operating diagram for analog output sensors

Near and far limits setting with teach procedure

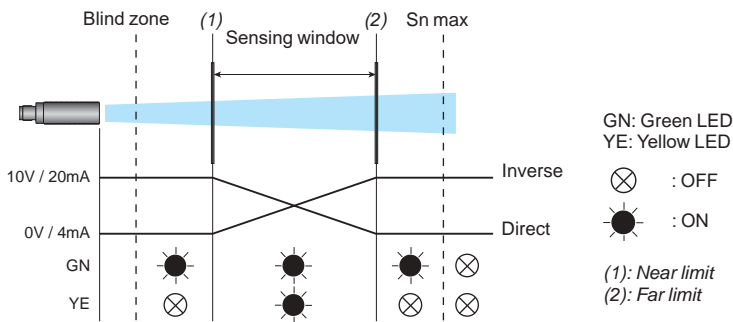
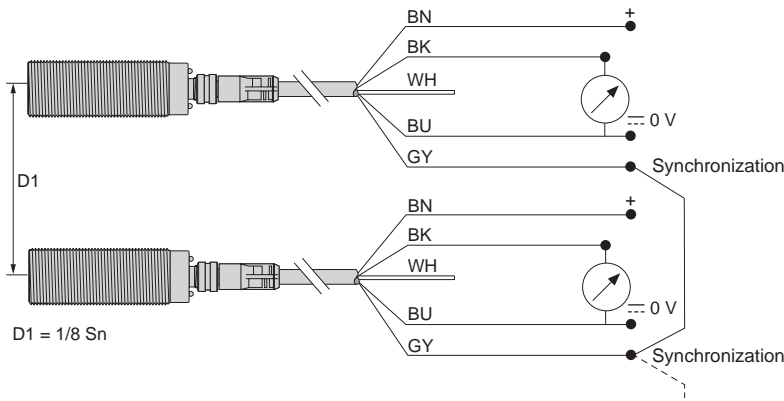


Diagram for the synchronization function (side by side application)



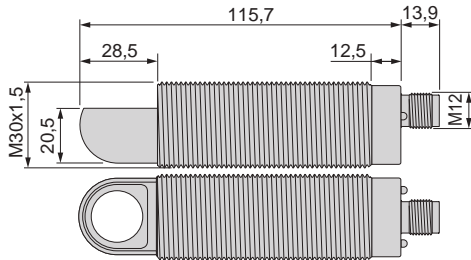
NB: To enable synchronization between several sensors, all of the wires of pin no.5 (gray) must be electrically connected together. A maximum of 8 sensors can be synchronized. To enable "Multiplexer" function for the sensors, use the XX Configuration Software. Without synchronization or multiplexing, the sensors must be at least 50 cm away from each other in order to avoid mutual interference.

Ultrasonic sensors

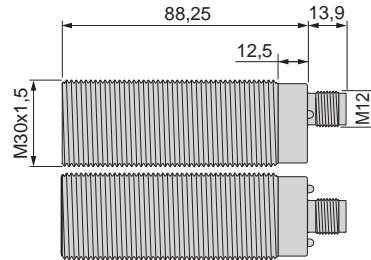
XX range, General purpose
Cylindrical, plastic or metal, Ø 30 mm, 1 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Dimensions

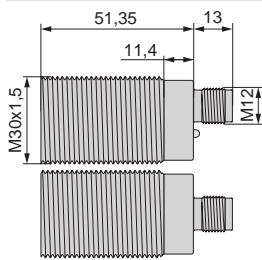
XXA30●1●M12



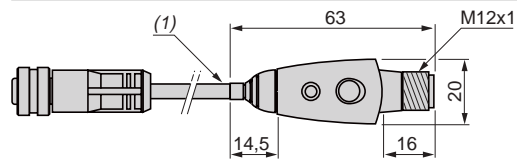
XXS30B1●M12, XXS30S1●M12



XXS30P1PM12, XXS30P1AM12, XXS30P1VM12



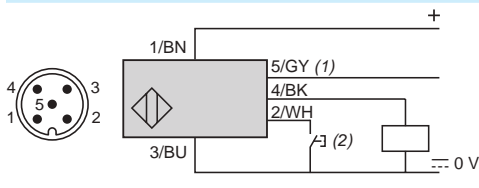
Teach pushbutton XXZPB100



(1) Cable length: 152 mm

Connections

Connector wiring



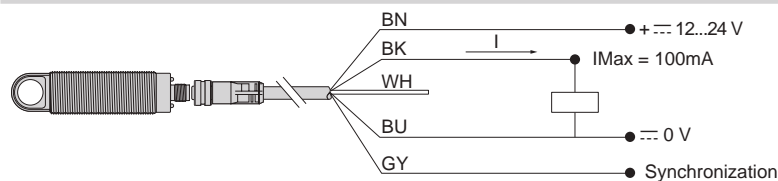
| Pin number | Wire color | Digital output description | Analog output description | |
|------------|------------|----------------------------|---------------------------|-----------------------|
| | | | 4-20 mA | 0-10 V |
| 1 | BN: Brown | +12...24 V \square | + \square 12...24 V | + \square 14...24 V |
| 2 | WH: White | Input teach | | |
| 3 | BU: Blue | 0 V \square | | |
| 4 | BK: Black | Output | | |
| 5 | GY: Gray | Synchronization | | |

(1) Synchronization.

(2) External setting pushbutton or XXZPB100 remote teach pushbutton (see page 43).

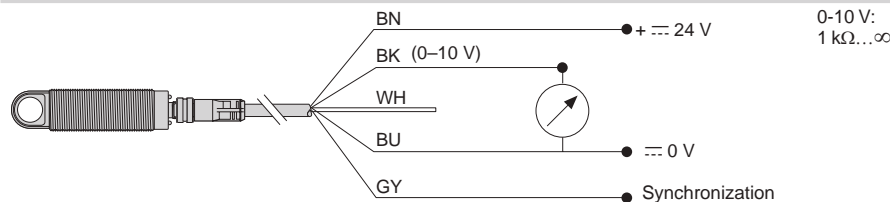
Wiring scheme (digital output NO or NC)

XXA30●●PM12/XXS30●●PM12



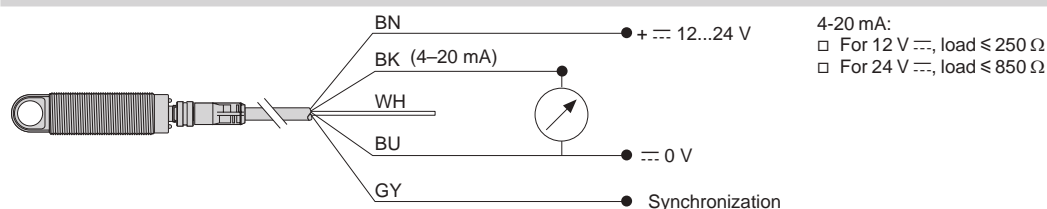
Wiring scheme (analog output 0-10V)

XX●30●●VM12



Wiring scheme (analog output 4-20 mA)

XX●30●●AM12



Ultrasonic sensors

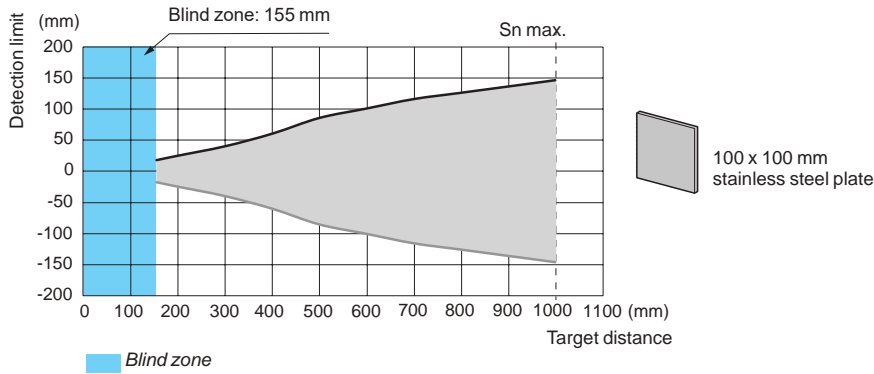
XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 1 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

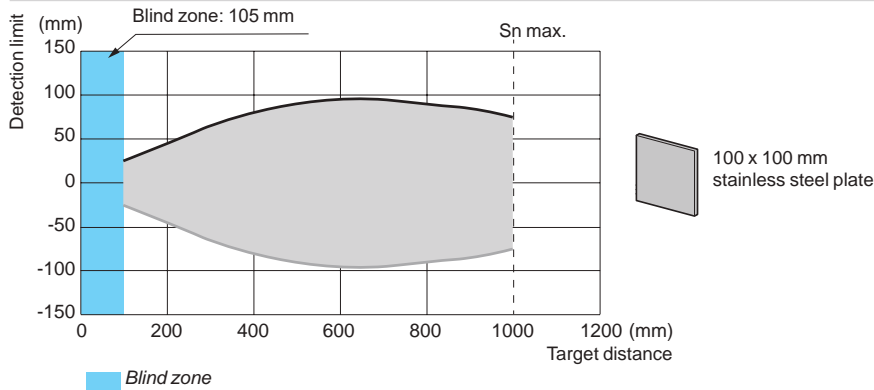
Curves

Detection curve with 100 x 100 mm square target

XXA30●1●M12, XXS30B1●M12, XXS30S1●M12

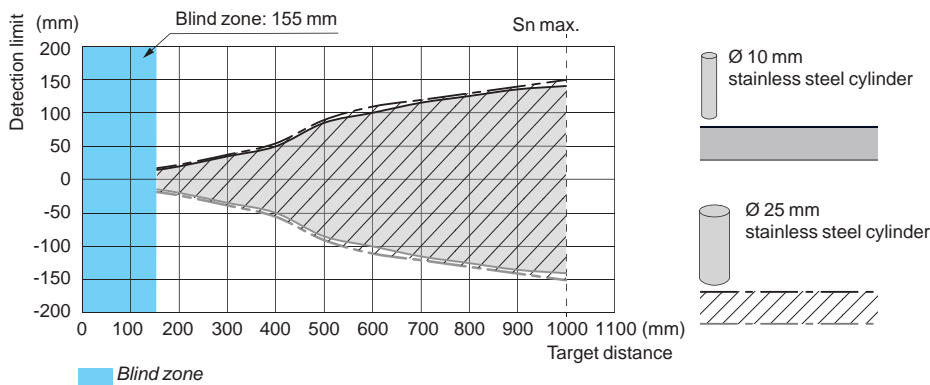


XXS30P1PM12, XXS30P1AM12, XXS30P1VM12

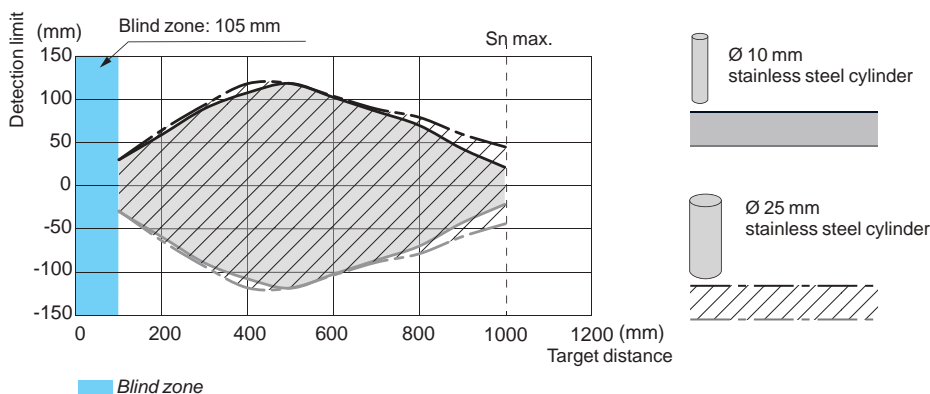


Detection curve with round bar

XXA30●1●M12, XXS30B1●M12, XXS30S1●M12



XXS30P1PM12, XXS30P1AM12, XXS30P1VM12



Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 2 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

| Sensor type | XX●30P2PM12 XX●30B2PM12 XX●30S2PM12 | XX●30P2AM12 XX●30B2AM12 XX●30S2AM12 | XX●30P2VM12 XX●30B2VM12 XX●30S2VM12 |
|---|--|---|--|
| General characteristics | | | |
| Conformity to standards | EN/IEC 60947-5-2, UL 508, and CSA C22.2 n°14 | | |
| Compliance with regulations | CE (based on EMC directive 2014/30/EU), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | |
| Product certifications | cULus with class 2 power supply, E2, EAC, RCM, and ECOLAB | | |
| Nominal sensing distance (Sn) | m | 2 (adjustable) | |
| Blind zone (in diffuse mode the object is not detected in this zone) | m | 0.155 | |
| Detection window | Remotely adjustable or by using external teachbutton XXZPB100 | | |
| Transmission frequency (transmitter resonance) | kHz | 120 | |
| Differential travel | mm | < 10 | – |
| Repeat accuracy (repeatability) | 0.1 % | | |
| Minimum size of object to be detected | Cylinder Ø 1 mm up to sensing distance of 1.4m | | |
| Tilt angle with 100 x 100 mm target | ± 10° at 2 m, ± 12° at 1.8 m ± 45° at 1m | | |
| Materials | Case | XX●30P●: PBT XX●30B●: Nickel-plated brass XX●30S●: Stainless steel 316L | |
| | Sensing face | Epoxy, resin, and rubber | |
| Connection | M12 connector - 5-pin | | |
| Supply characteristics | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | V | 12...24 V $\overline{\text{---}}$ | 12...24 V $\overline{\text{---}}$ |
| Voltage limits (including ripple) | V | 10...30 V $\overline{\text{---}}$ | 10...30 V $\overline{\text{---}}$ |
| Current consumption, no-load | mA | < 65 | < 65 |
| Output characteristics | | | |
| LED indicators | Output state | Yellow LED | Yellow LED |
| | Echo state | Green LED | Green LED |
| Switching capacity (with overload and short-circuit protection) | < 100 mA | | |
| Resistive load impedance | Ω | – | $\overline{\text{---}}$ 12 V, load ≤ 250 Ω $\overline{\text{---}}$ 24 V, load ≤ 850 Ω |
| Voltage drop | V | < 2 | – |
| Internal temperature compensation | Yes | | |
| Maximum switching frequency | Hz | 5.5 | – |
| Delays | First-up | ms | 150 |
| | Response | ms | 90 |
| | Recovery | ms | 90 |
| | | | 250 |
| | | | – |
| | | | 200 |
| | | | 200 |
| Environment characteristics | | | |
| Degree of protection | Conforming to IEC 60529 and EN/IEC 60947-5-2 | IP 65, IP 67 | |
| Storage temperature | °C | - 40...+ 80 | |
| Operating temperature | °C | - 25...+ 70 | |
| Relative humidity | < 95%, without condensation | | |
| Vibration resistance | Conforming to IEC 60068-2-6 | Amplitude ± 1 mm (f = 10...55 Hz) | |
| Mechanical shock resistance | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes | |
| Resistance to electromagnetic interference | Conforming to EN/IEC 60947-5-2 and UNECE R10-05 | | |

Ultrasonic sensors

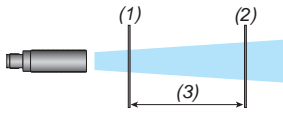
XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 2 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

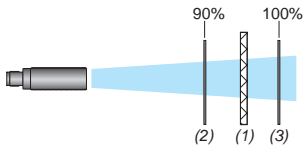
Operating diagrams for digital output sensors

Settings with teach procedure

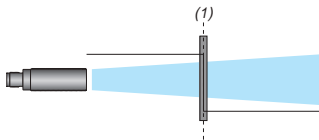
Window mode



Reflex mode



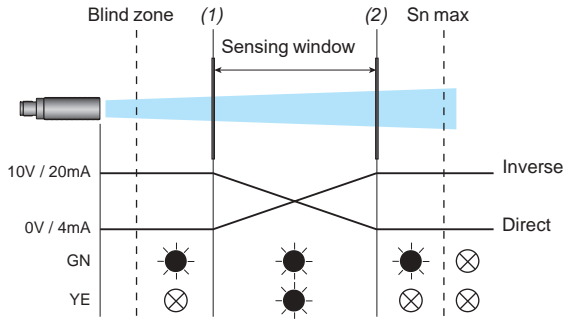
Proximity mode



(1) Switch point

Operating diagram for analog output sensors

Near and far limits setting with teach procedure



GN: Green LED
YE: Yellow LED

⊗ : OFF

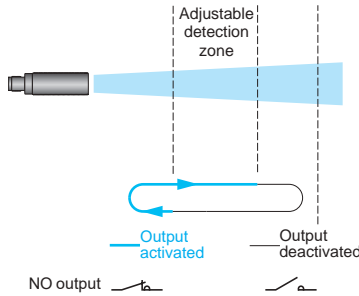
● : ON

(1): Near limit

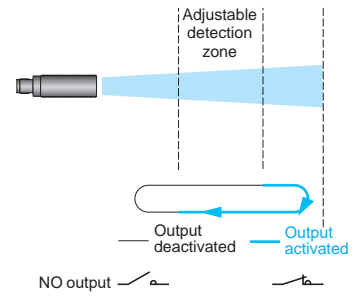
(2): Far limit

Pump/Hysteresis mode

Emptying (stored in high threshold memory)



Filling (stored in low threshold memory)



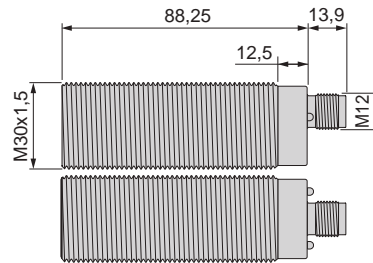
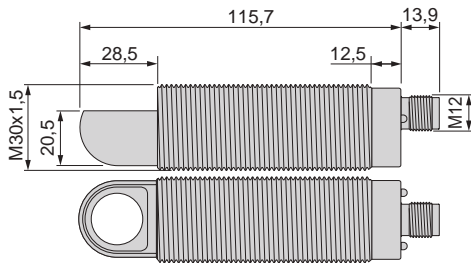
Ultrasonic sensors

XX range, General purpose
Cylindrical, plastic or metal, Ø 30 mm, 2 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Dimensions

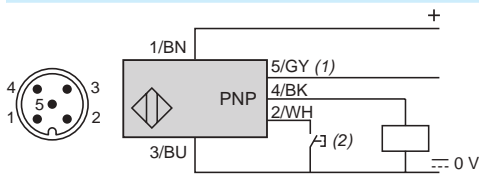
XX●30P2PM12, XX●30B2PM12, XX●30S2PM12

XX●30P2AM12, XX●30B2AM12, XX●30S2AM12
XX●30P2VM12, XX●30B2VM12, XX●30S2VM12



Connections

Connector wiring



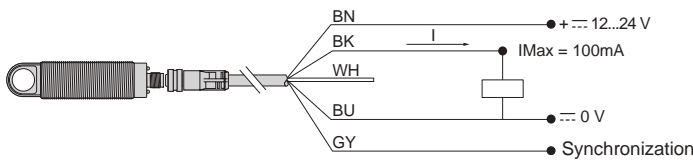
| Pin number | Wire color | Digital output description | Analog output description | |
|------------|------------|----------------------------|---------------------------|------------|
| | | | 4-20 mA | 0-10 V |
| 1 | BN: Brown | +12...24 V | +12...24 V | +14...24 V |
| 2 | WH: White | Input teach | | |
| 3 | BU: Blue | 0 V | | |
| 4 | BK: Black | Output | | |
| 5 | GY: Gray | Synchronization | | |

(1) Synchronization.

(2) External setting pushbutton or XXZPB100 remote teach pushbutton (see page 43).

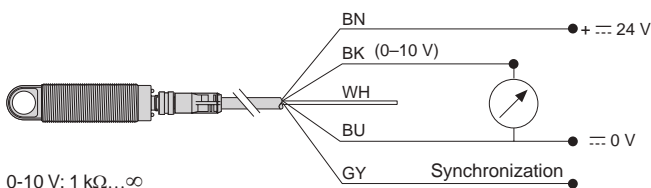
Wiring scheme (digital output NO or NC)

XXS30●PM12, XXA30●PM12



Wiring scheme (analog output 0-10V)

XX●30●VM12



0-10 V: 1 kΩ...∞

Wiring scheme (analog output 4-20 mA)

XX●30●AM12

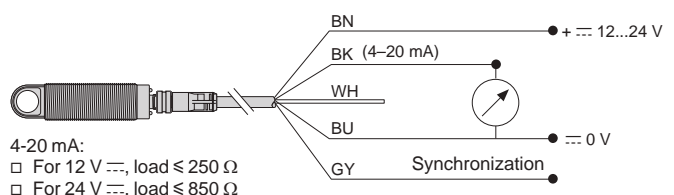
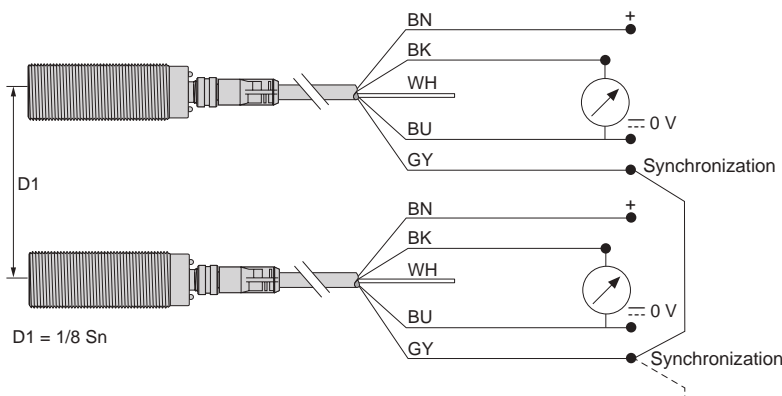


Diagram for the synchronization function (Side by side application)



NB: To enable synchronization between several sensors, all of the wires of pin no.5 (gray) must be electrically connected together. A maximum of 8 sensors can be synchronized. To enable "Multiplexer" function for the sensors, use the XX Configuration Software. Without synchronization or multiplexing, the sensors must be at least 50 cm away from each other in order to avoid mutual interference.

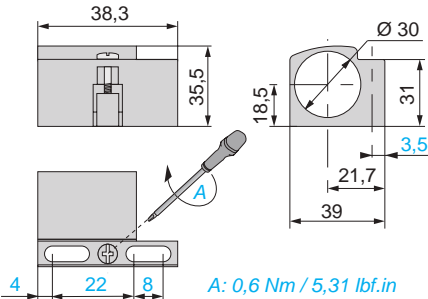
Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 2 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

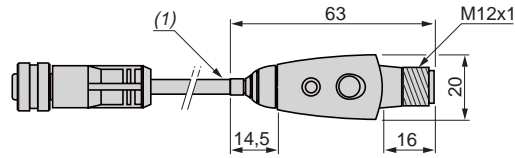
Dimensions (continued)

Fixing clamp XXZB130



A: 0,6 Nm / 5,31 lbf.in

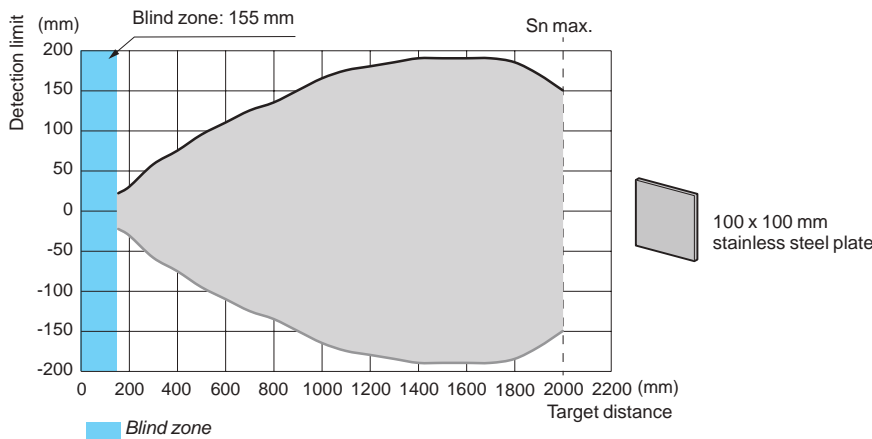
Teach pushbutton XXZPB100



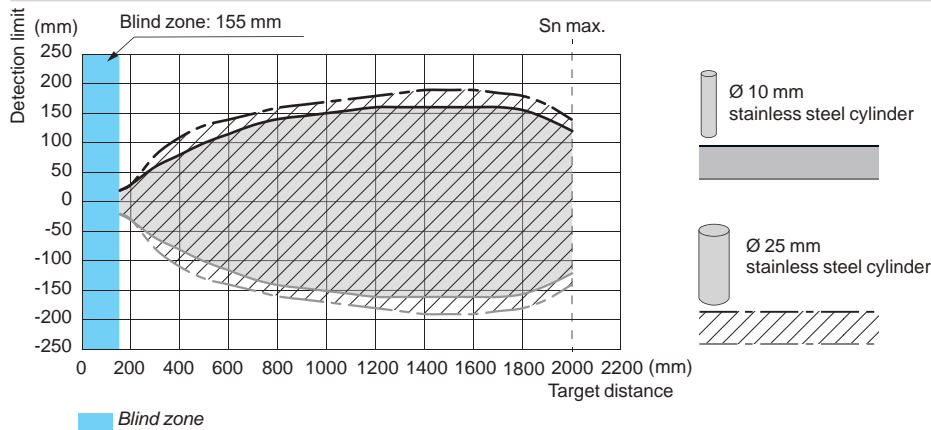
(1) Cable length: 152 mm

Curves

Detection curve with 100 x 100 mm square target



Detection curve with round bar



Ultrasonic sensors

XX range, General purpose
Cylindrical, plastic or metal, Ø 30 mm, 4 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

| Sensor type | | XXS30●4PM12 | XXS30●4AM12 | XXS30●4VM12 |
|---|--|--|--|-----------------------------------|
| General characteristics | | | | |
| Conformity to standards | | EN/IEC 60947-5-2, UL 508, and CSA C22.2 n°14 | | |
| Compliance with regulations | | CE (based on EMC directive 2014/30/EU), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | |
| Product certifications | | cULus with class 2 power supply, E2, EAC, RCM, and ECOLAB | | |
| Nominal sensing distance (Sn) | m | 4 (adjustable) | | |
| Blind zone (in diffuse mode the object is not detected in this zone) | m | 0.420 | | |
| Detection window | | Remotely adjustable or by using external teachbutton XXZPB100 | | |
| Transmission frequency (transmitter resonance) | kHz | 80 | | |
| Differential travel | mm | < 20 | – | |
| Repeat accuracy (repeatability) | | 0.1 % | | |
| Minimum size of object to be detected | | Cylinder Ø 1 mm up to sensing distance of 1.8m | | |
| Tilt angle with 500 x 500 mm target | | ± 7° at 4 m, ± 10° at 3.6 m ± 40° at 2 m | | |
| Materials | Case | XXS30●: PBT XXS30●: Nickel-plated brass XXS30●: Stainless steel 316L | | |
| | Sensing face | Epoxy, resin, and rubber | | |
| Connection | | M12 connector - 5-pin | | |
| Supply characteristics | | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | V | 12...24 V $\overline{\text{---}}$ | 12...24 V $\overline{\text{---}}$ | 24 V $\overline{\text{---}}$ |
| Voltage limits (including ripple) | V | 10...30 V $\overline{\text{---}}$ | 10...30 V $\overline{\text{---}}$ | 14...30 V $\overline{\text{---}}$ |
| Current consumption, no-load | mA | < 65 | < 65 | < 65 |
| Output characteristics | | | | |
| LED indicators | Output state | Yellow LED | Yellow LED | Yellow LED |
| | Echo state | Green LED | Green LED | Green LED |
| Switching capacity (with overload and short-circuit protection) | | < 100 mA | – | – |
| Resistive load impedance | Ω | – | 12 V $\overline{\text{---}}$, load ≤ 250 Ω 24 V $\overline{\text{---}}$, load ≤ 850 Ω | ≥ 1 kΩ |
| Voltage drop | V | < 2 | – | – |
| Internal temperature compensation | | Yes | Yes | Yes |
| Maximum switching frequency | Hz | 2.7 | – | – |
| Delays | First-up | ms 250 | 500 | 500 |
| | Response | ms 180 | – | – |
| | Recovery | ms 180 | 400 | 400 |
| Environment characteristics | | | | |
| Degree of protection | Conforming to IEC 60529 and EN/IEC 60947-5-2 | IP 65, IP 67 | | |
| Storage temperature | | °C - 40...+ 80 | | |
| Operating temperature | | °C - 25...+ 70 (1) | | |
| Relative humidity | | < 95%, without condensation | | |
| Vibration resistance | Conforming to IEC 60068-2-6 | Amplitude ± 1 mm (f = 10...55 Hz) | | |
| Mechanical shock resistance | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes | | |
| Resistance to electromagnetic interference | | Conforming to EN/IEC 60947-5-2 and UNECE R10-05 | | |

Ultrasonic sensors

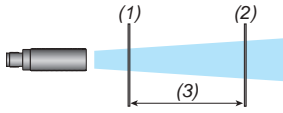
XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 4 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Operating diagrams for digital output sensors

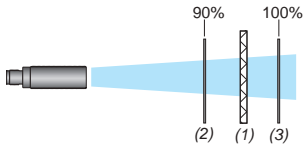
Settings with teach procedure

Window mode



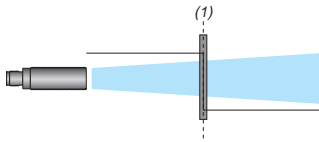
- (1): Near limit
- (2): Far limit
- (3): Sensing window

Reflex mode



- (1): Reflector
- (2): Near limit
- (3): Far limit

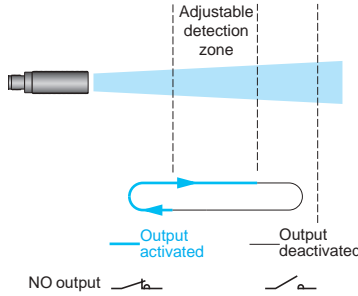
Proximity mode



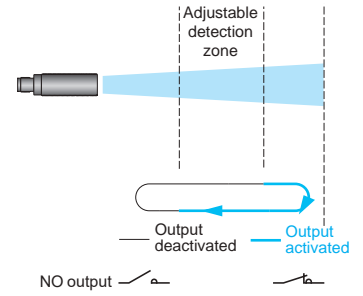
- (1): Switch point

Pump/Hysteresis mode

Emptying (stored in high threshold memory)

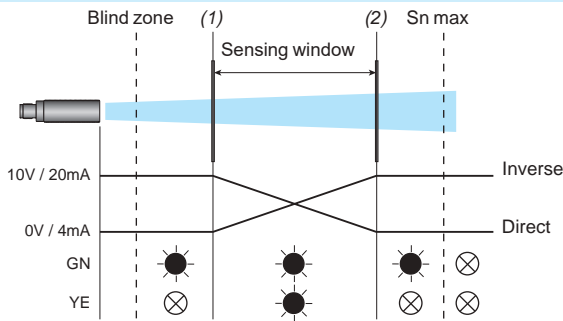


Filling (stored in low threshold memory)



Operating diagram for analog output sensors

Near and far limits setting with teach procedure



GN: Green LED
YE: Yellow LED

⊗ : OFF

● : ON

- (1): Near limit
- (2): Far limit

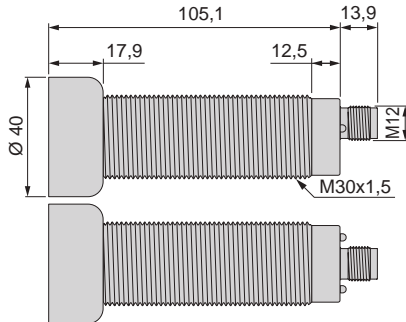
Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 4 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

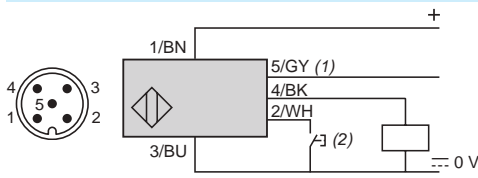
Dimensions

XXS30P4PM12, XXS30B4PM12, XXS30S4PM12



Connections

Connector wiring



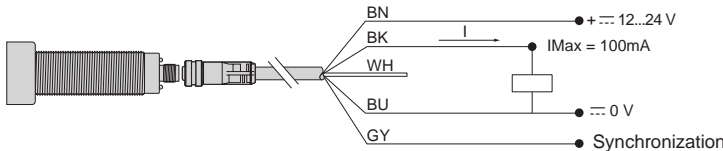
| Pin number | Wire color | Digital output description | Analog output description | |
|------------|------------|----------------------------|---------------------------|------------|
| | | | 4-20 mA | 0-10 V |
| 1 | BN: Brown | +12...24 V | +12...24 V | +14...24 V |
| 2 | WH: White | Input teach | | |
| 3 | BU: Blue | 0 V | | |
| 4 | BK: Black | Output | | |
| 5 | GY: Gray | Synchronization | | |

(1) Synchronization.

(2) External setting pushbutton or **XXZPB100** remote teach pushbutton (see page 43).

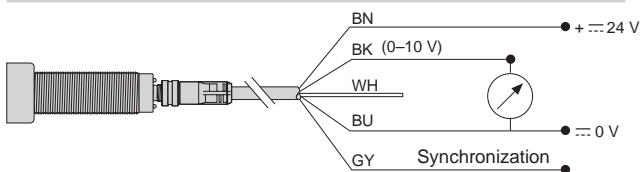
Wiring scheme (digital output NO or NC)

XXS30●●PM12



Wiring scheme (analog output 0-10V)

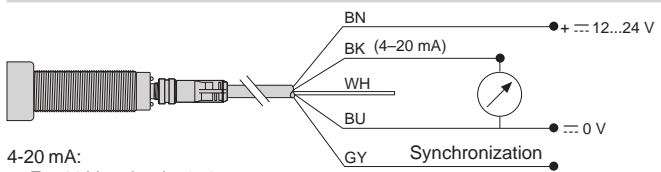
XX●30●●VM12



0-10 V: 1 kΩ...∞

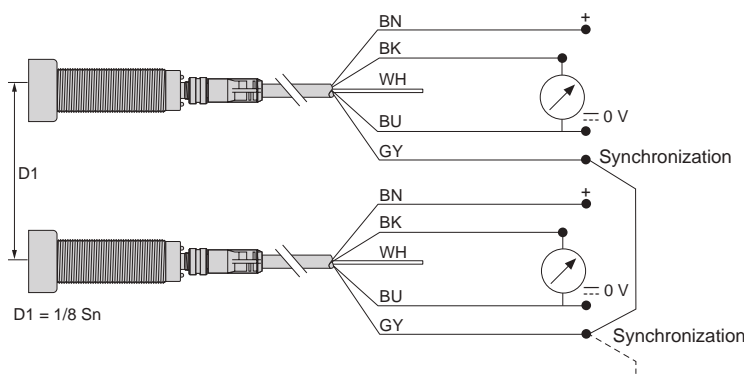
Wiring scheme (analog output 4-20 mA)

XX●30●●AM12



4-20 mA:
 For 12 V, load ≤ 250 Ω
 For 24 V, load ≤ 850 Ω

Diagram for the synchronization function (Side by side application)



NB: To enable synchronization between several sensors, all of the wires of pin no. 5 (gray) must be electrically connected together. A maximum of 8 sensors can be synchronized. To enable "Multiplexer" function for the sensors, use the XX Configuration Software. Without synchronization or multiplexing, the sensors must be at least 50 cm away from each other in order to avoid mutual interference.

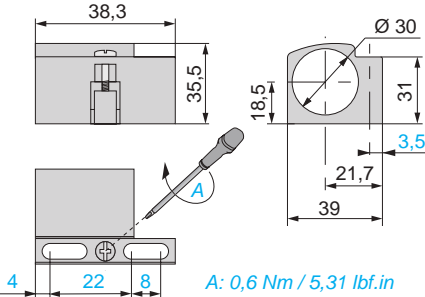
Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 4 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Dimensions (continued)

Fixing clamp XXZB130

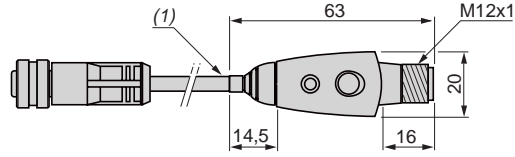


4

22 8

A: 0,6 Nm / 5,31 lbf.in

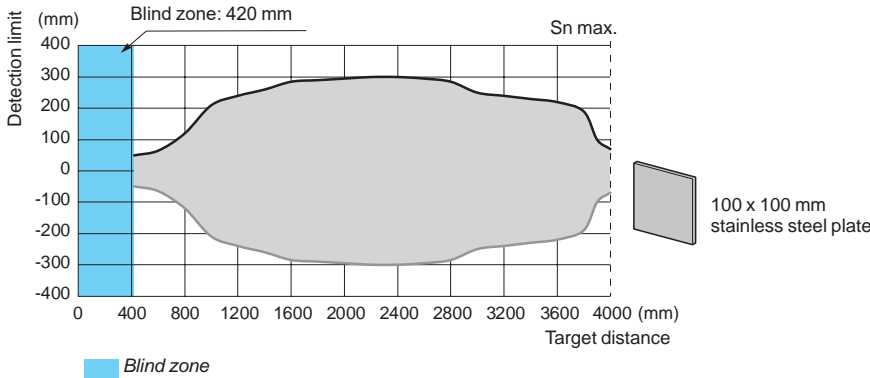
Teach pushbutton XXZPB100



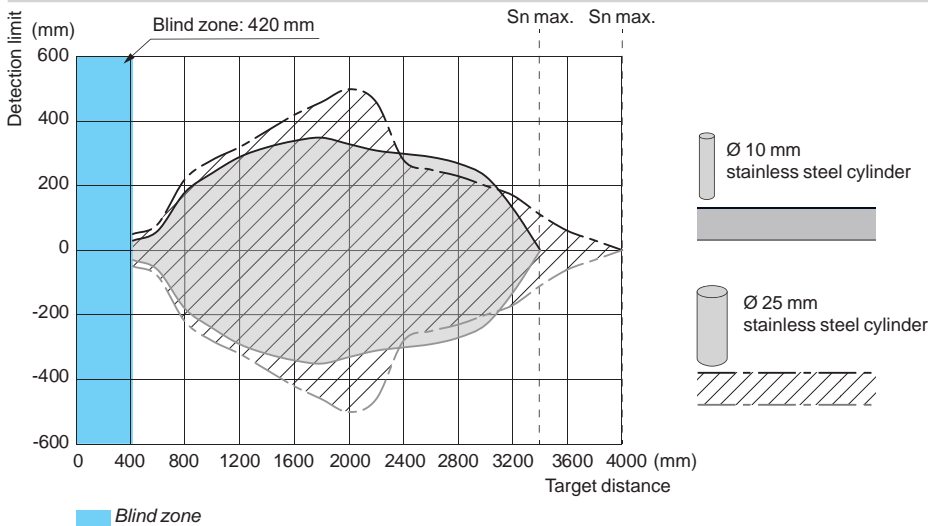
(1) Cable length: 152 mm

Curves

Detection curve with 100 x 100 mm square target



Detection curve with round bar



Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 8 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

| Sensor type | | XXS30P8PPM12 XXS30P8NNM12 | XXS30P8APM12 | XXS30P8VPM12 | | |
|---|--|--|---|---|---|-----|
| General characteristics | | | | | | |
| Conformity to standards | | EN/IEC 60947-5-2, UL 508 and CSA C22.2 n° 14 | | | | |
| Compliance with regulations | | CE (based on EMC directive 2014/30/EU), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | | | |
| Product certifications | | cULus with class 2 power supply, E2, EAC, RCM, and ECOLAB | | | | |
| Nominal sensing distance (Sn) | | m | 8 (adjustable) | | | |
| Blind zone (in diffuse mode the object is not detected in this zone) | | m | 0.290 | | | |
| Detection window | | Remotely adjustable or by using external teachbutton XXZPB100 | | | | |
| Transmission frequency (transmitter resonance) | | kHz | 75 | | | |
| Differential travel | | mm | < 12.7 | – | | |
| Repeat accuracy (repeatability) | | 0.1 % | | | | |
| Minimum size of object to be detected | | Cylinder Ø 1 mm up to sensing distance of 1.8m | | | | |
| Tilt angle with 500 x 500 mm target | | ± 4° at 8 m, ± 5° at 7.2 m ± 12° at 4 m | | | | |
| Materials | | Case | PBT | | | |
| | | Sensing face | Epoxy, resin, and rubber | | | |
| Connection | | M12 connector - 5-pin | | | | |
| Supply characteristics | | | | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | | V | ≐ 12...24 V | ≐ 12...24 V | ≐ 24 V | |
| Voltage limits (including ripple) | | V | ≐ 10...30 V | ≐ 10...30 V | ≐ 14...30 V | |
| Current consumption, no-load | | mA | < 50 | < 50 | < 50 | |
| Output characteristics | | | | | | |
| LED indicators | | Output state | 1 dual colour LED (yellow/green) 1 three-colour LED (yellow/green/red) | 1 dual colour LED (yellow/green) 1 three-colour LED (yellow/green/red) | 1 dual colour LED (yellow/green) 1 three-colour LED (yellow/green/red) | |
| | | Echo state | Green LED | Green LED | Green LED | |
| Switching capacity (with overload and short-circuit protection) | | | < 100 mA | – | – | |
| Resistive load impedance | | Ω | – | ≐ 12 V, load ≤ 250 Ω ≐ 24 V, load ≤ 850 Ω | ≥ 1 kΩ | |
| Voltage drop | | V | < 2 | – | – | |
| Internal temperature compensation | | | Yes | Yes | Yes | |
| Maximum switching frequency | | Hz | 2 | – | – | |
| Delays | | First-up | ms | 600 | 600 | |
| | | Response | ms | 300 | – | – |
| | | Recovery | ms | 300 | 500 | 500 |
| Environment characteristics | | | | | | |
| Degree of protection | | Conforming to IEC 60529 and EN/IEC 60947-5-2 | IP 65, IP 67 | | | |
| Storage temperature | | °C | - 40...+ 85 | | | |
| Operating temperature | | °C | - 25...+ 70 | | | |
| Relative humidity | | < 95%, without condensation | | | | |
| Vibration resistance | | Conforming to IEC 60068-2-6 | Amplitude ± 1 mm (f = 10...55 Hz) | | | |
| Mechanical shock resistance | | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes | | | |
| Resistance to electromagnetic interference | | Conforming to EN/IEC 60947-5-2 and UNECE R10-05 | | | | |

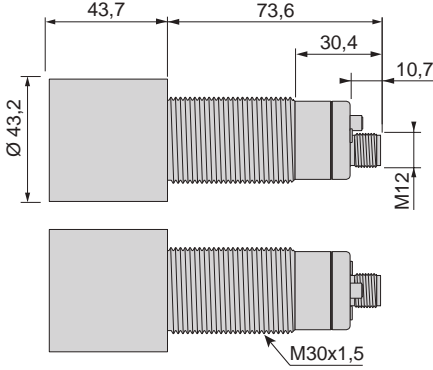
Ultrasonic sensors

XX range, General purpose

Cylindrical, plastic or metal, Ø 30 mm, 8 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Dimensions

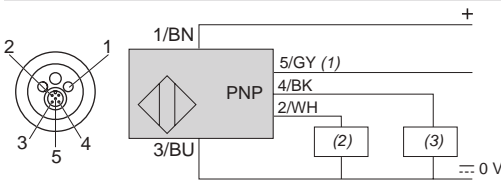
XXS30P8PPM12, XXS30P8NNM12, XXS30P8APM12, XXS30P8VPM12



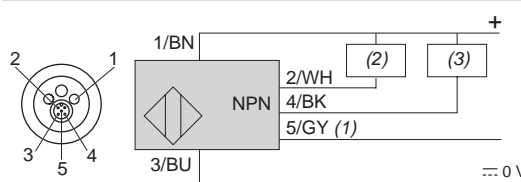
Connections

Connector wiring

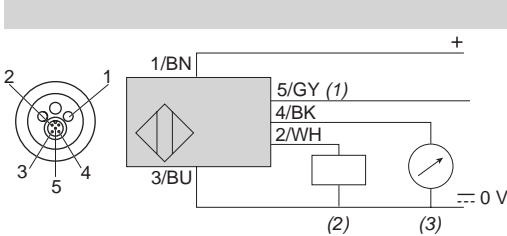
XXS30P8PPM12



XXS30P8NNM12



XXS30P8APM12, XXS30P8VPM12



Pin number

Wire color

Digital output description

Analog output description

| Pin number | Wire color | Digital output description | Analog output description | |
|------------|------------|----------------------------|---------------------------|---------------|
| | | | 4-20 mA | 0-10 V |
| 1 | BN: Brown | +12...24 V | +12...24 V | +24 V |
| 2 | WH: White | Output 2 | PNP output | PNP output |
| 3 | BU: Blue | 0 V | - | - |
| 4 | BK: Black | Output 1 | 4-20 mA output | 0-10 V output |
| 5 | GY: Gray | Synchronization | | |

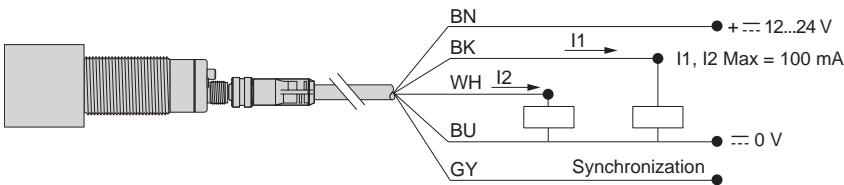
(1) Synchronization

(2) Output 2

(3) Output 1

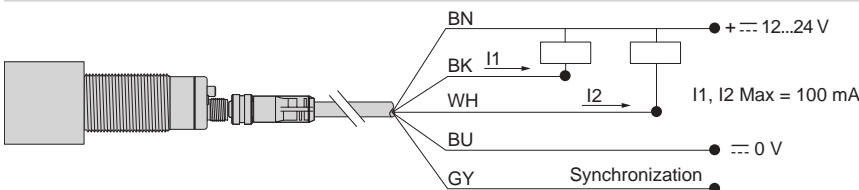
Wiring scheme (digital output PNP, NO or NC)

XXS30P8PPM12



Wiring scheme (digital output NPN, NO or NC)

XXS30P8NNM12



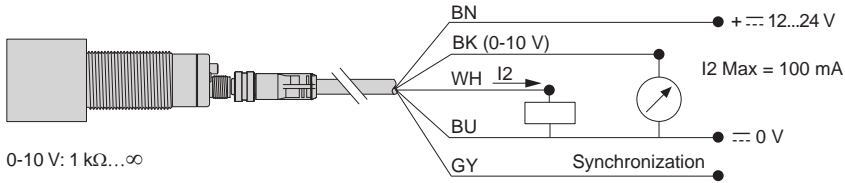
Ultrasonic sensors

XX range, General purpose
Cylindrical, plastic or metal, Ø 30 mm, 8 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Connections (continued)

Wiring scheme (analog output 0-10 V and PNP, NO or NC)

XXS30P8VPM12



Wiring scheme (analog output 4-20 mA and PNP, NO or NC)

XXS30P8APM12

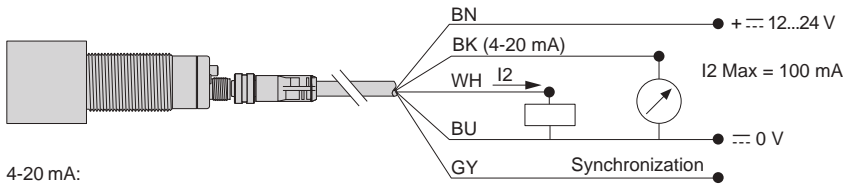
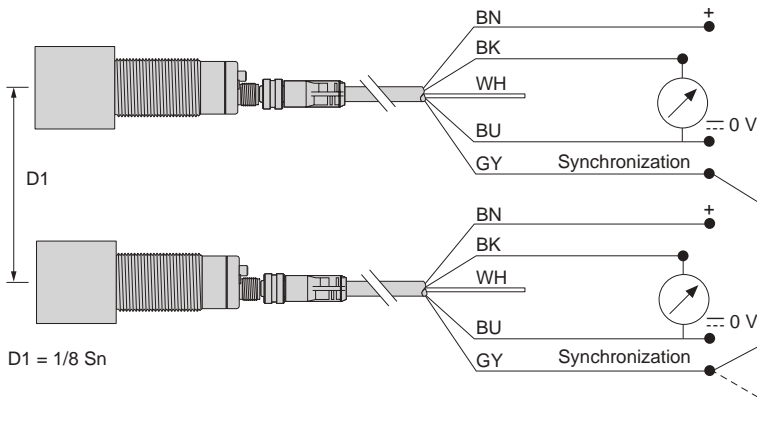


Diagram for the synchronization function (Side by side application)



NB: To enable synchronization between several sensors, all of the wires of pin no. 5 (gray) must be electrically connected together. A maximum of 8 sensors can be synchronized. To enable "Multiplexer" function for the sensors, use the XX Configuration Software. Without synchronization or multiplexing, the sensors must be at least 50 cm away from each other in order to avoid mutual interference.

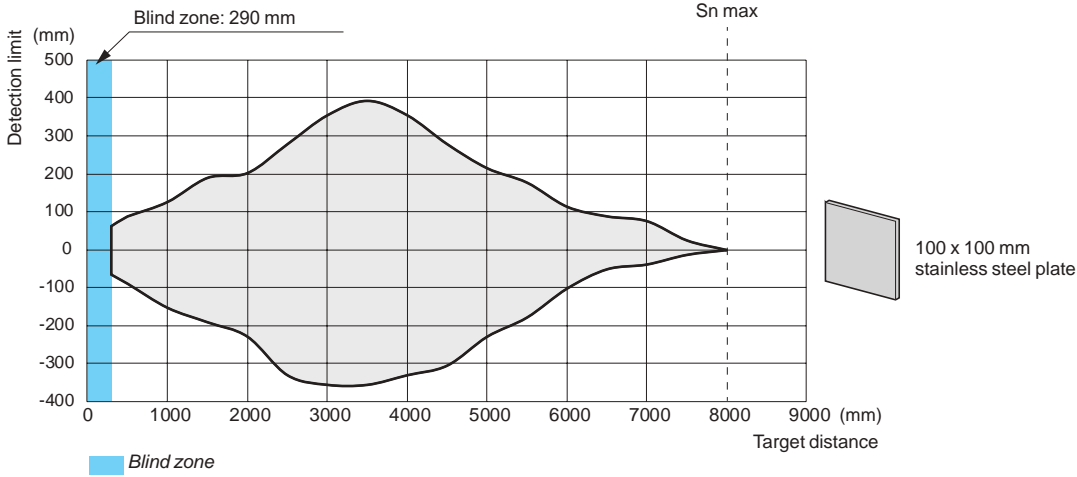
Ultrasonic sensors

XX range, General purpose

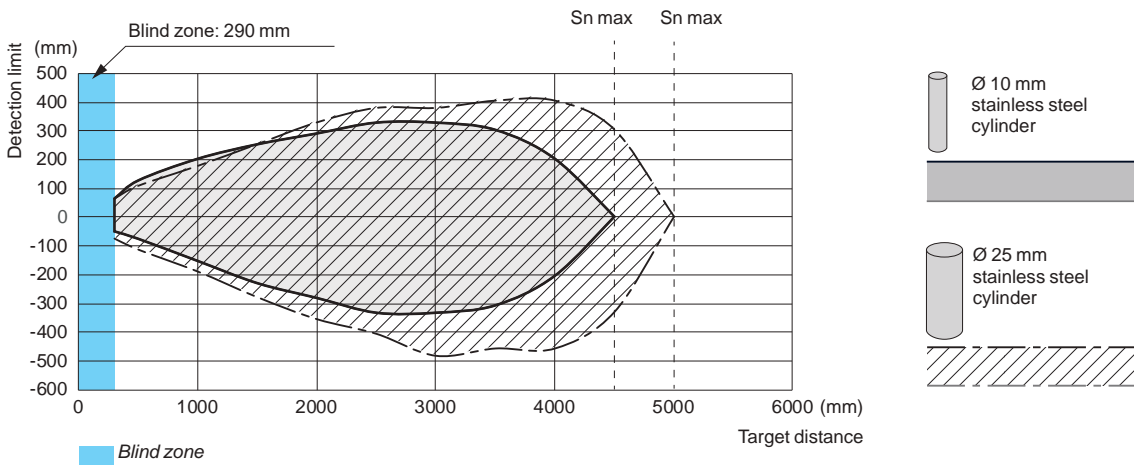
Cylindrical, plastic or metal, Ø 30 mm, 8 m sensing distance. Diffuse mode, solid-state digital or analog output. Configurable by software

Curves

Detection curve with 100 x 100 mm square target

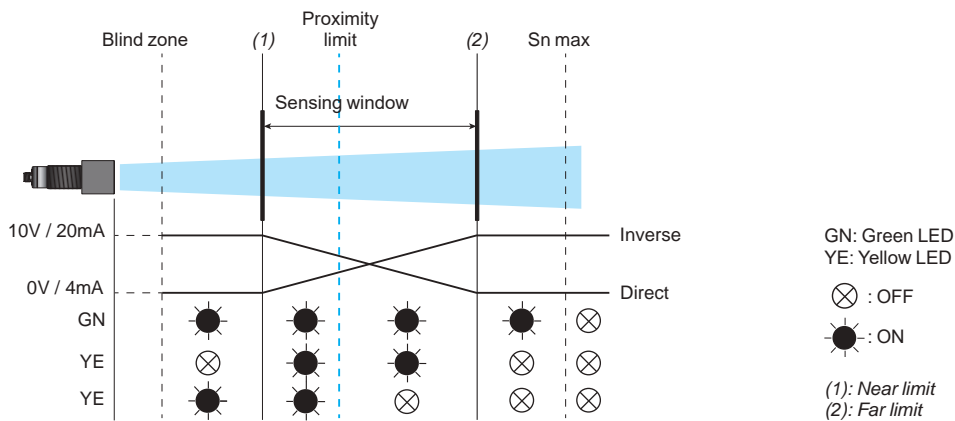


Detection curve with round bar



Operating diagram for analog output sensors

Near and far limits setting with teach procedure



Ultrasonic sensors

XX range, Wide Beam

Obstacle detection system for mobile equipment.

Configurable by software

Wide Beam ultrasonic sensors

Telemecanique Sensors has expanded its range of ultrasonic sensors with the "XX Wide Beam" offer to meet the specific needs of mobile equipment such as:

- Lift trucks
- Cherry pickers
- Mobile elevating work platforms
- Self-propelled ride-on handling trucks
- Ground support equipment
- Aircraft access platforms, etc.



These sensors are designed to detect the following kinds of obstacles when mobile equipment is lifting or rotating: ceilings, beams, cables, scaffolding, other platforms or buckets, etc.

Compact and flush mountable in metal, these sensors are easy to install with:

- A remote Deutsch DTM04 connector on a 0.15 m cable, or
- A remote M12 connector on a 0.15 m cable, or
- A 0.5 m cable

They operate silently and are also suitable for indoor use.

The XX configuration software makes these sensors easy to program.

The synchronization function is used to reduce interference between sensors, even when installed close to each other, thus helping to ensure objects are detected over a wide area.

Important: This device does not have a Performance Level or Safety Integrity Level or any other type of capability with regard to functional safety.

For safety applications, visit our website: www.tesensors.com

Compact solution for detecting obstacles



Certified

- > E2 according to UN Regulation 10R-06
- > cULus

Obstacle detection system

- > **Wide detection area:** Fewer sensors are needed to cover a given area.
- > Better tilt angle for enhanced detection of targets and surfaces, even those that are slightly reflective or curved
- > **Rugged sensors suitable for use in harsh environments**
- > Operation in temperatures as low as -40 °C with no adverse impact on detection capability
- > Thermoplastic UV-resistant front face that can tolerate potential damage caused by building materials or bad weather
- > IP69K rating for high-pressure washdown
- > **Noise detection capability to assist the user**
- > The sensor is equipped with a noise detection function that is enabled by default. When noise detection is enabled, the sensor's analog output emits 2 mA or 5 volts, depending on model (100 for CANJ by default), when it detects excessive environmental noise.
- > Noise detection settings can be changed using the configuration interface and software (see page 78).

Ultrasonic sensors

XX range, Wide Beam

Obstacle detection system for mobile equipment.

Configurable by software



XXW54P3●●L01DM6



XXW54P3●PL01M12



XXW54P3●PL05



XXZKITDM6

References

| Description | Sensing distance (Sn) m | Function/ output | Connections | Reference | Weight kg |
|--|----------------------------|----------------------|---|-----------------|--------------|
| Diffuse sensors with 0.5...4.5 V analog output and solid state digital output | | | | | |
| Ø 54 mm plastic sensor | 3 | 0.5...4.5 V + PNP | 0.15 m cable with remote Deutsch DTM04 6-pin connector | XXW54P3HPL01DM6 | 0.115 |
| | | | 0.15 m cable with remote M12, 5-pin connector | XXW54P3HPL01M12 | 0.115 |
| | | | 0.5 m cable | XXW54P3HPL05 | 0.115 |

Diffuse sensors with 4...20 mA analog output and solid state digital output

| | | | | | |
|------------------------------|---|--------------------|---|-----------------|-------|
| Ø 54 mm plastic sensor | 3 | 4...20 mA + PNP | 0.15 m cable with remote Deutsch DTM04 6-pin connector | XXW54P3APL01DM6 | 0.115 |
| | | | 0.15 m cable with remote M12, 5-pin connector | XXW54P3APL01M12 | 0.115 |
| | | | 0.5 m cable | XXW54P3APL05 | 0.115 |

Diffuse sensors with CAN SAE J1939 communication

| | | | | | |
|------------------------------|---|----------|---|----------------|-------|
| Ø 54 mm plastic sensor | 3 | CANJ1939 | 0.15 m cable with remote Deutsch DTM04 6-pin connector | XXW54P3JL01DM6 | 0.115 |
| | | | 0.5 m cable | XXW54P3JL05 | 0.115 |

Connection accessory

| Description | Connections | Reference | Weight kg |
|---|---|-----------|--------------|
| Configuration cable for sensors XXW54P3●●L01DM6 | 1 m cable with ■ one female Deutsch DTM04 6-pin connector and ■ one male M12 4-pin connector | XXZKITDM6 | 0.050 |

Configuration software, interface, and kit for synchronization function

See page 78.

Ultrasonic sensors

XX range, Wide Beam

Obstacle detection system for mobile equipment.

Configurable by software

| Sensor type | XXW54P3HPL01DM6 | XXW54P3APL01DM6 | XXW54P3HPL05 | XXW54P3APL05 |
|---|--|--|--|--|
| General characteristics | | | | |
| Conforming to standards | EN/IEC 60947-5-2, UL 60947-5-2 and CSA C22.2 n° 60947-5-2 | | | |
| Compliance with regulations | CE (based on the EMC directive 2014/30/UE), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | | |
| Product certifications | UKCA, E2, cULus | | | |
| Nominal sensing distance (Sn) | m | 0.425...3 | | |
| Blind zone | mm | 425 | | |
| Detection window | Adjustable using XX configuration software, up to 4 m | | | |
| Transmission frequency (transmitter resonance) | kHz | 48 | | |
| Differential travel | mm | < 20 | | |
| Repeat accuracy | 0.1 % | | | |
| Sensor accuracy | 2 % | | | |
| Minimum size of object to be detected | Cylinder Ø 10 mm up to a sensing distance of 3 m | | | |
| Tilt angle with 500 x 500 mm target | ± 6° at 4 m, ± 10° at 3 m, ± 45° at 1.5 m | | | |
| Materials | Casing | PBT (Valox), UV resistant | | |
| | Sensing face | PEI (ULTEM) with PUR coating, UV resistant | | |
| Fixing method | Using 2 M4 screws (not provided). 2 x Ø 4.32 mm stainless steel inserts and silicone washers are provided with the sensor. Tightening torque ≤ 3 Nm (26.6 lb-in) | | | |
| Connection | By remote Deutsch DTM04 6-pin connector, on 0.15 m Ø 6 mm TPU cable | | By 0.5 m Ø 6 mm TPU cable CSA: 5 x 0.34 mm ² | |
| Power supply characteristics | | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | V | 12...24 V $\overline{\text{---}}$. Powered by a dedicated safety extra low voltage (SELV) or a protected extra low voltage (PELV) | | |
| Voltage limits (including ripple) | V | $\overline{\text{---}}$ 9...32 | | |
| Current consumption, no-load | mA | < 50 | | |
| Output characteristics | | | | |
| Indicator lights | Output status | 1 yellow LED | | |
| | Power supply and echo status | 1 two-tone LED (white and green). White: power on; green: echo status | | |
| Switching capacity | mA | < 100 (with overload and short-circuit protection) | | |
| Resistive load impedance | | ≥ 2 K Ω | ≤ 250 Ω (12 V), ≤ 850 Ω (24 V) | ≥ 2 K Ω ≤ 250 Ω (12 V), ≤ 850 Ω (24 V) |
| Voltage drop | V | < 2 | | |
| Internal temperature compensation | Yes | | | |
| Maximum switching frequency | Hz | 1.6 | | |
| Delays | First-up | ms | 400 | |
| | Response | ms | 300 | |
| | Recovery | ms | 300 | |
| Environmental characteristics | | | | |
| Degree of protection | Conforming to IEC 60529 and EN/IEC 60947-5-2 | IP 65, IP 67, IP 69K | | |
| Storage temperature | °C | - 40...+ 85 | | |
| Operating temperature | °C | - 40...+ 70 | | |
| Relative humidity | < 95%, non-condensing | | | |
| Vibration resistance | Conforming to IEC 60068-2-6 | Amplitude ± 1 mm (f = 10...55 Hz) | | |
| Mechanical shock resistance | Conforming to IEC 60068-2-27 | 30 gn, duration 11 ms, in all 3 axes | | |
| Immunity to electromagnetic interference | Conforming to EN/IEC 60947-5-2 | | | |

Ultrasonic sensors

XX range, Wide Beam

Obstacle detection system for mobile equipment.

Configurable by software

| Sensor type | | XXW54P3HPL01M12 | XXW54P3APL01M12 | XXW54P3JL01DM6 | XXW54P3JL05 |
|--|--|--|--|---|-------------|
| General characteristics | | | | | |
| Conforming to standards | | EN/IEC 60947-5-2, UL 60947-5-2 and CSA C22.2 n° 60947-5-2 | | | |
| Compliance with regulations | | CE (based on the EMC directive 2014/30/UE), NEC (ANSI/NFPA 70), CEC (CSA C22), UNECE R10 | | | |
| Product certifications | | UKCA, E2, cULus | | | |
| Nominal sensing distance (Sn) | | m | 0.425...3 | | |
| Blind zone | | mm | 425 | | |
| Detection window | | Adjustable using XX configuration software, up to 4 m | | | |
| Transmission frequency (transmitter resonance) | | kHz | 48 | | |
| Differential travel | | mm | < 20 | | |
| Repeat accuracy | | 0.1 % | | | |
| Sensor accuracy | | 2 % | | | |
| Minimum size of object to be detected | | Cylinder Ø 10 mm up to a sensing distance of 3 m | | | |
| Tilt angle with 500 x 500 mm target | | ± 6° at 4 m, ± 10° at 3 m, ± 45° at 1.5 m | | | |
| Materials | | Casing | | PBT (Valox), UV resistant | |
| | | Sensing face | | PEI (ULTEM) with PUR coating, UV resistant | |
| Fixing method | | Using 2 M4 screws (not provided). 2 x Ø 4.32 mm stainless steel inserts and silicone washers are provided with the sensor. Tightening torque ≤ 3 Nm (26.6 lb-in) | | | |
| Connection | | By remote M12 5-pin connector, on 0.15 m Ø 6 mm TPU cable | | By remote Deutsch DTM04 6-pin connector, on 0.15 m Ø 6 mm TPU cable | |
| Power supply characteristics | | | | | |
| Rated supply voltage (Ue) with protection against reverse polarity | | V | 12...24 V $\overline{\text{---}}$. Powered by a dedicated safety extra low voltage (SELV) or a protected extra low voltage (PELV) | | |
| Voltage limits (including ripple) | | V | $\overline{\text{---}}$ 9...32 | | |
| Current consumption, no-load | | mA | < 50 | < 50 | < 101 |
| Output characteristics | | | | | |
| Indicator lights | | Output status | | 1 yellow LED | |
| | | Power supply and echo status | | 1 two-tone LED (white and green). White: power on; green: echo status | |
| Switching capacity | | mA | < 100 (with overload and short-circuit protection) | | |
| Resistive load impedance | | | ≥ 2 K Ω | ≤ 250 Ω (12 V), ≤ 850 Ω (24 V) | – |
| Voltage drop | | V | < 2 | | |
| Internal temperature compensation | | Yes | | | |
| Maximum switching frequency | | Hz | 1.6 | | |
| Delays | | First-up | | ms | |
| | | Response | | ms | |
| | | Recovery | | ms | |
| Environmental characteristics | | | | | |
| Degree of protection | | Conforming to IEC 60529 and EN/IEC 60947-5-2 | | IP 65, IP 67 | |
| Storage temperature | | °C | - 40...+ 85 | | |
| Operating temperature | | °C | - 40...+ 70 | | |
| Relative humidity | | < 95%, non-condensing | | | |
| Vibration resistance | | Conforming to IEC 60068-2-6 | | Amplitude ± 1 mm (f = 10...55 Hz) | |
| Mechanical shock resistance | | Conforming to IEC 60068-2-27 | | 30 gn, duration 11 ms, in all 3 axes | |
| Immunity to electromagnetic interference | | Conforming to EN/IEC 60947-5-2 | | | |
| Sensor type | | XXW54P3JL01DM6 | | XXW54P3JL05 | |
| CANJ1939 characteristics | | | | | |
| CAN Standard | | SAE J1939 | | | |
| CAN interface | | 2-wire (5-pin or 6-pin), electro static discharge and transient protected | | | |
| Internal terminating resistor | | 102 Ω resistor, not supplied (purchase separately) | | | |
| CAN bus type | | CAN 2.0B High speed | | | |
| CAN bus speed | | 250 k bits/s by default 500 k bits/s configurable | | | |
| J1939 frame emission rate | | ms | 50 | | |
| J1939 addressing mode | | Configurable (dynamic addressing) | | | |
| CAN identifier length | | 29 bits | | | |
| Maximum network length | | m | 40 | | |
| Maximum number of sensors | | Up to 30 sensors | | | |

Ultrasonic sensors

XX range, Wide Beam

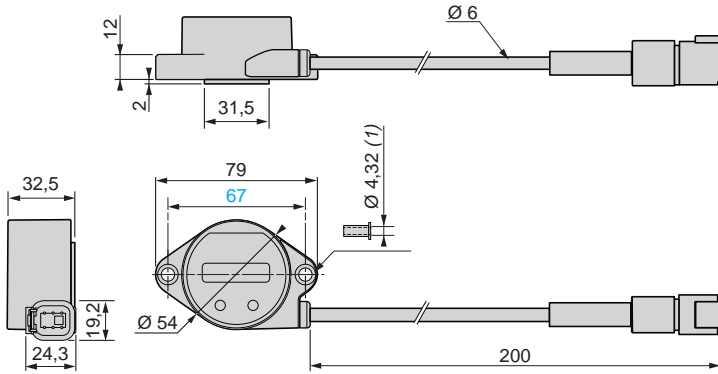
Obstacle detection system for mobile equipment.

Configurable by software

Dimensions

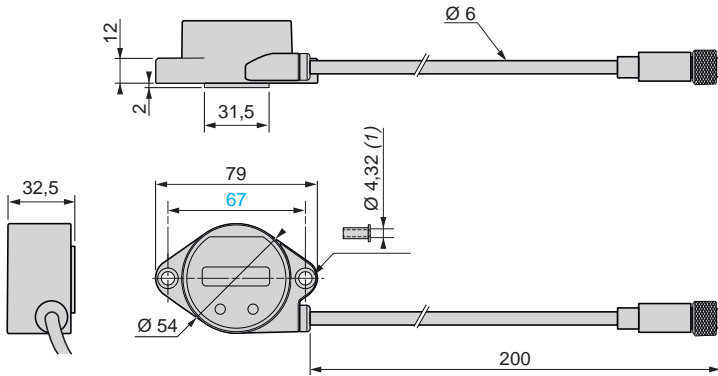
Sensors with remote Deutsch DTM04 connector

XXW54P3HPL01DM6, XXW54P3APL01DM6, XXW54P3JL01DM6



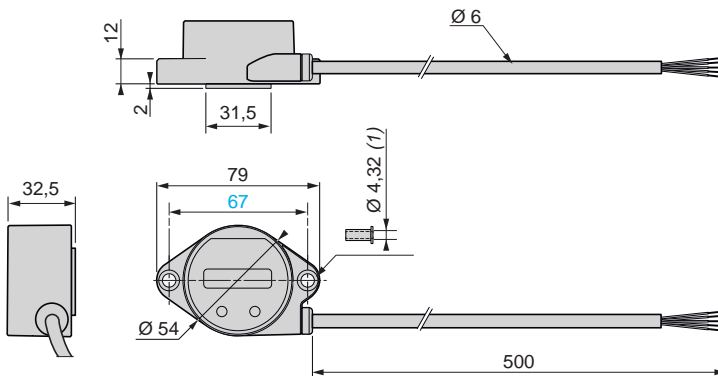
Sensors with remote M12 connector

XXW54P3HPL01M12, XXW54P3APL01M12

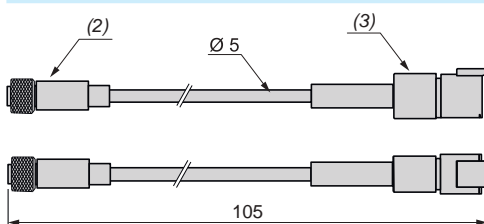


Pre-wired sensors

XXW54P3HPL05, XXW54P3APL05, XXW54P3JL05



XXZKITDM6 cable with Deutsch DTM04 connector for sensor configuration



(1) The sensor is supplied with 2 stainless steel inserts $\varnothing 4.32$ mm and 2 silicone washers. M4 screws not provided.

(2) M12 connector.

(3) Deutsch DTM04 connector.

Ultrasonic sensors

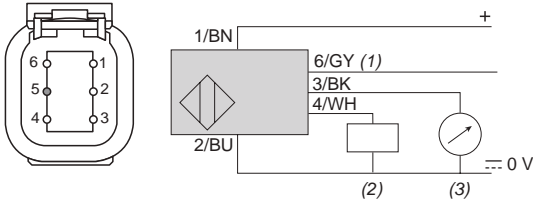
XX range, Wide Beam

Obstacle detection system for mobile equipment.

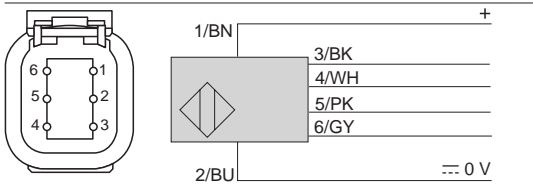
Configurable by software

Connections (continued)

Sensors with remote Deutsch DTM04 connector

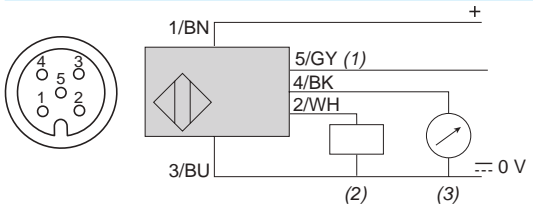


| Pin number | Wire color | Description | |
|------------|------------|-------------------------------------|-------------------------------------|
| | | XXW54P3HPL01DM6 | XXW54P3APL01DM6 |
| 1 | BN: Brown | + 12...24 V $\overline{\text{---}}$ | + 12...24 V $\overline{\text{---}}$ |
| 2 | BU: Blue | 0 V $\overline{\text{---}}$ | 0 V $\overline{\text{---}}$ |
| 3 | BK: Black | 0.5...4.5 V analog output (5) | 4...20 mA analog output (6) |
| 4 | WH: White | PNP solid-state output | PNP solid-state output |
| 5 (4) | – | Not connected | Not connected |
| 6 | GY: Gray | Synchronization | Synchronization |



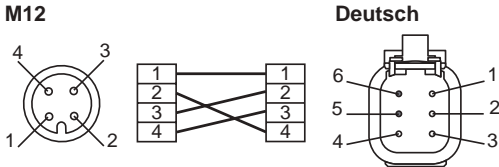
| Pin number | Wire color | Description | |
|------------|------------|-------------------------------------|--|
| | | XXW54P3JL01DM6 | |
| 1 | BN: Brown | + 12...24 V $\overline{\text{---}}$ | |
| 2 | BU: Blue | 0 V $\overline{\text{---}}$ | |
| 3 | BK: Black | XXZBOX01 communication | |
| 4 | WH: White | Synchronization | |
| 5 | PK: Pink | CAN HIGH (7) | |
| 6 | GY: Gray | CAN LOW (7) | |

Sensors with remote M12 connector



| Pin number | Wire color | Description | |
|------------|------------|-------------------------------------|-------------------------------------|
| | | XXW54P3HPL01M12 | XXW54P3APL01M12 |
| 1 | BN: Brown | + 12...24 V $\overline{\text{---}}$ | + 12...24 V $\overline{\text{---}}$ |
| 2 | WH: White | PNP solid-state output | PNP solid-state output |
| 3 | BU: Blue | 0 V $\overline{\text{---}}$ | 0 V $\overline{\text{---}}$ |
| 4 | BK: Black | 0.5...4.5 V analog output (5) | 4...20 mA analog output (6) |
| 5 | GY: Gray | Synchronization | Synchronization |

XXZKITDM6 cable

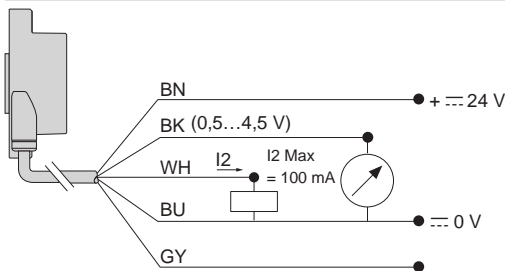


| Pin number | Wire color | Description | |
|------------|------------|--|--|
| | | M12 connector | |
| 1 | BN: Brown | + 24 V $\overline{\text{---}}$, power to sensor | |
| 2 | WH: White | Software communication | |
| 3 | BU: Blue | 0 V $\overline{\text{---}}$ | |
| 4 | BK: Black | Software communication | |

| Pin number | Couleur des fils | Description | |
|------------|------------------|--|--|
| | | Deutsch connector | |
| 1 | BN: Brown | + 24 V $\overline{\text{---}}$, power to sensor | |
| 2 | BU: Blue | 0 V $\overline{\text{---}}$ | |
| 3 | BK: Black | Software communication | |
| 4 | WH: White | Software communication | |
| 5 (8) | – | Not connected | |
| 6 (8) | – | Not connected | |

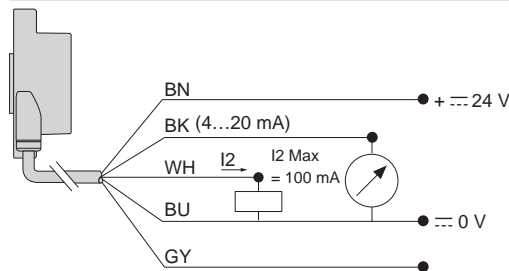
Pre-wired sensors

XXW54P3HPL05



0.5...4.5 V: load 2 k Ω ... ∞

XXW54P3APL05



4...20 mA: load \leq 250 Ω ($\overline{\text{---}}$ 12 V), load \leq 850 Ω ($\overline{\text{---}}$ 24 V).

- (1) Synchronization
- (2) Output 2
- (3) Output 1
- (4) Contact not connected, equipped with a sealing plug (provided with the sensor).
- (5) The sensor's analog output emits 5 volts when it detects excessive environmental noise.
- (6) The sensor's analog output emits 2 mA when it detects excessive environmental noise.
- (7) When noise detection is enabled, the sensor's CAN bus will output 100 by default (configurable to 6400) when it detects excessive environmental noise.
- (8) Contact not connected, equipped with a sealing plug (provided with the sensor).

Ultrasonic sensors

XX range, Wide Beam

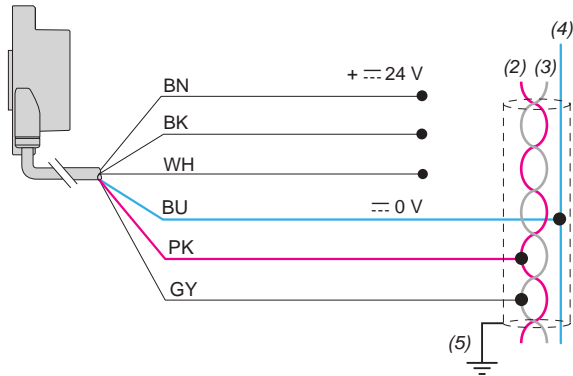
Obstacle detection system for mobile equipment.

Configurable by software

Connections (continued)

Pre-wired sensors (1)

XXW54P3JL05



(1) Connecting the detector to the **XXZBOX01** configuration interface with the **XZCC12MDM40B** connector: BN (Brown), WH (White), BU (Blue), BK (Black).

(2) CAN HIGH

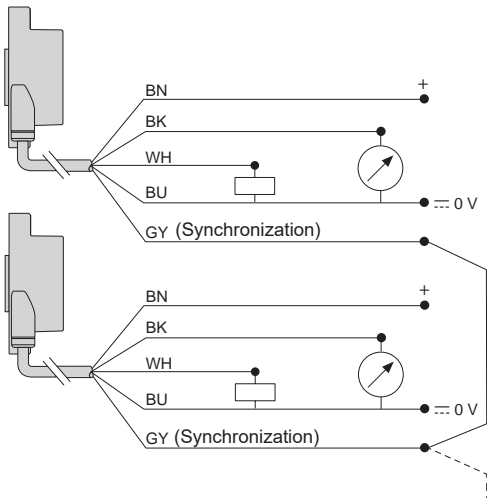
(3) CAN LOW

(4) GND

(5) EMC/GND

Synchronization function diagram (side-by-side application)

XXW54P3HPL01DM6, XXW54P3APL01DM6, XXW54P3HPL01M12, XXW54P3APL01M12, XXW54P3HPL05

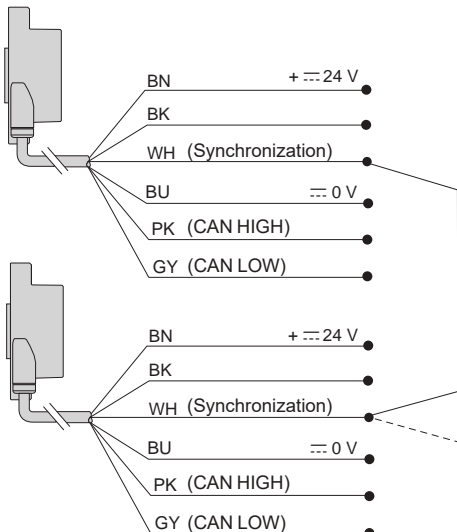


Note: Synchronization is recommended if more than one sensor is used in the same direction in order to avoid any interference between sensors due to the width of their beam.

Up to 8 sensors can be synchronized to operate side by side by electrically connecting all pin no. 6 (gray) wires together.

All sensors must be the same model and have the same cycle time setting.

XXW54P3JL01DM6, XXW54P3JL05



Note: Synchronization is recommended if more than one sensor is used in the same direction in order to avoid any interference between sensors due to the width of their beam.

Up to 8 sensors can be synchronized to operate side by side by electrically connecting all pin no. 4 (white) wires together.

All sensors must be the same model and have the same cycle time setting.

Ultrasonic sensors

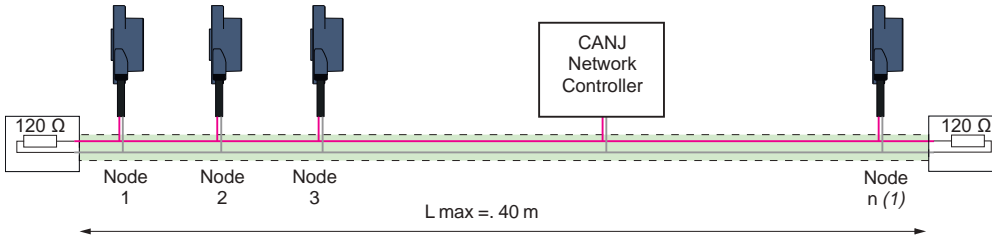
XX range, Wide Beam

Obstacle detection system for mobile equipment.

Configurable by software

Connections (continued)

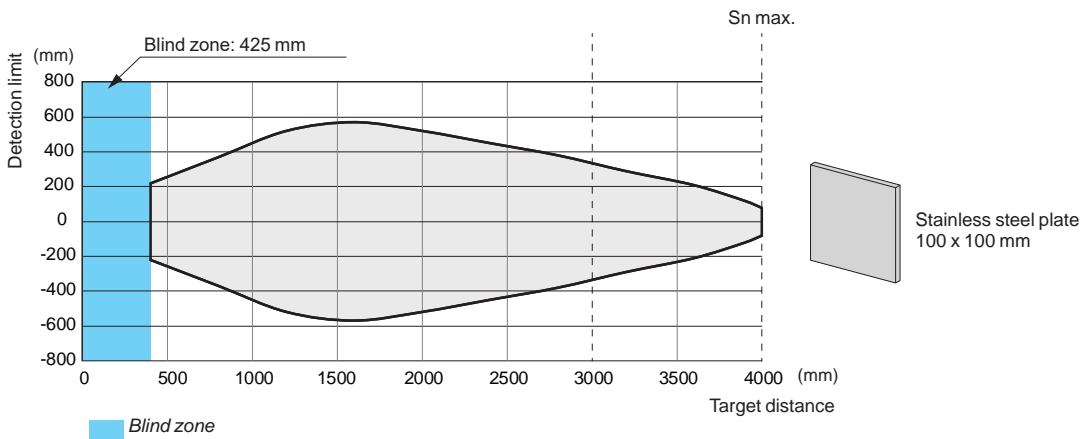
CANJ network topology



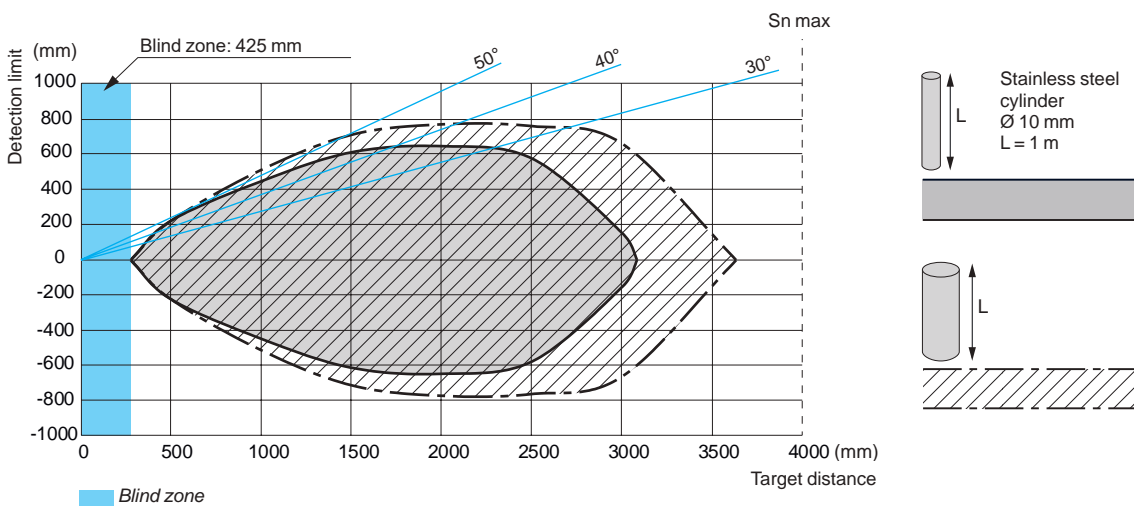
(1) Max. number: 30 sensors.

Curves

Detection curve with 100 x 100 mm square target



Detection curve with round bar



Ultrasonic sensors

XX range, Wide Beam

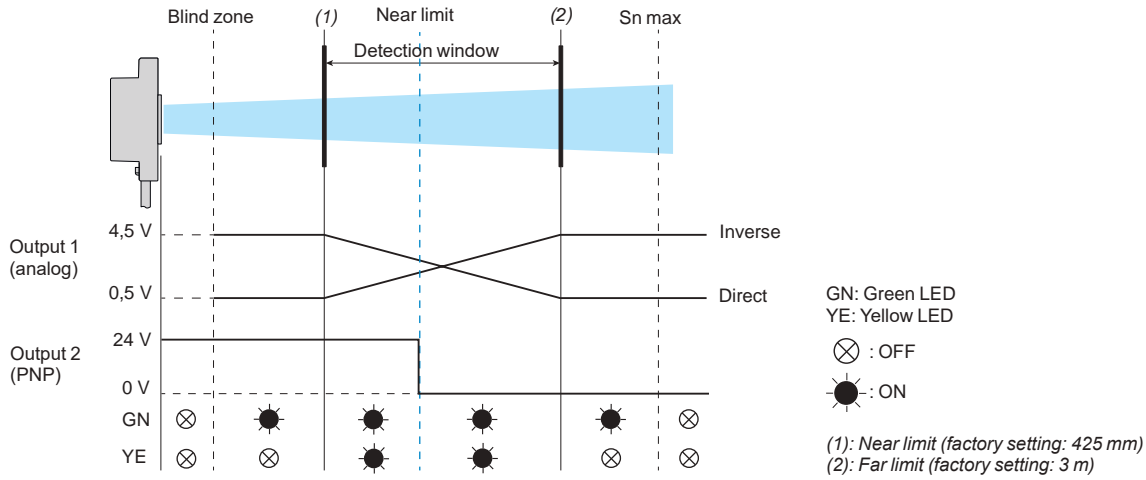
Obstacle detection system for mobile equipment.

Configurable by software

Operating diagram

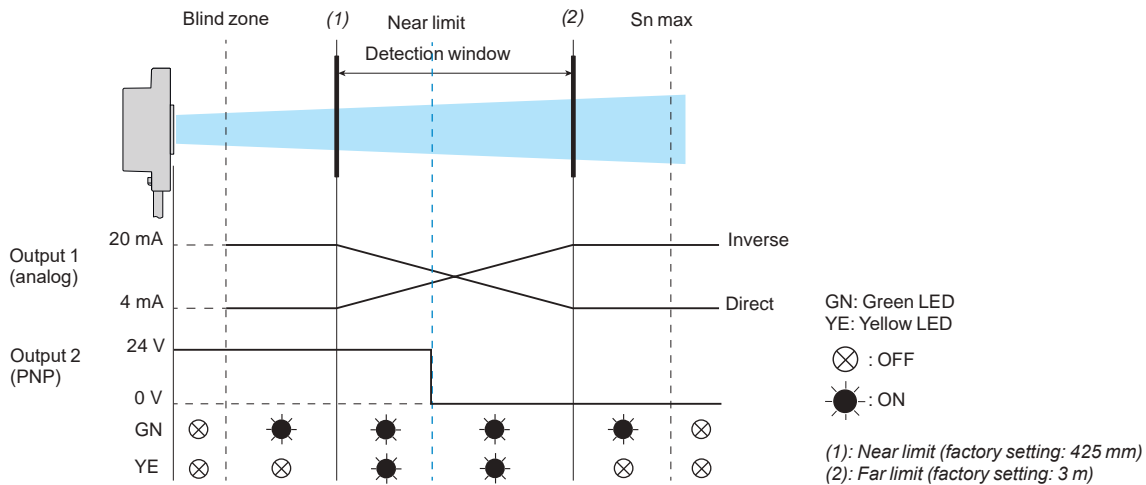
Setting the near and far limits using the configuration software

XXW54P3HPL01DM6, XXW54P3HPL05, XXW54P3HPL01M12



Note: The sensor's analog output emits 5 volts when it detects excessive environmental noise.

XXW54P3APL01DM6, XXW54P3APL05, XXW54P3APL01M12



Note: The sensor's analog output emits 2 mA when it detects excessive environmental noise.

Ultrasonic sensors

XX range, Wide Beam

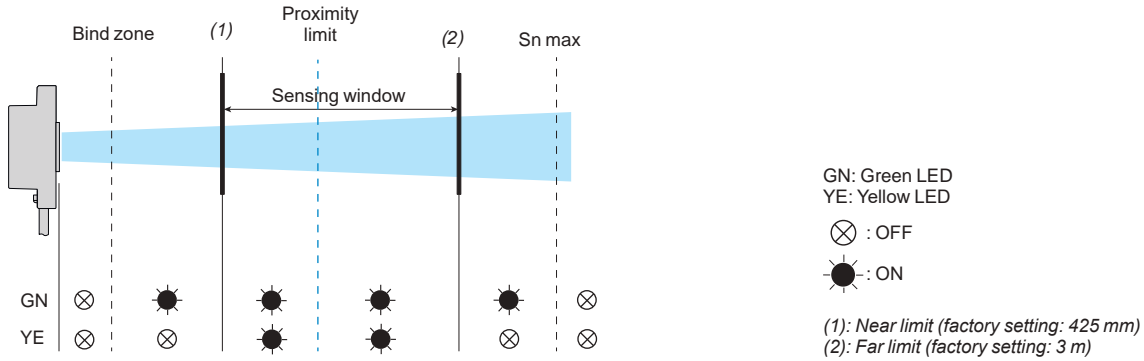
Obstacle detection system for mobile equipment.

Configurable by software

Operating diagram (continued)

Setting the near and far limits using the configuration software

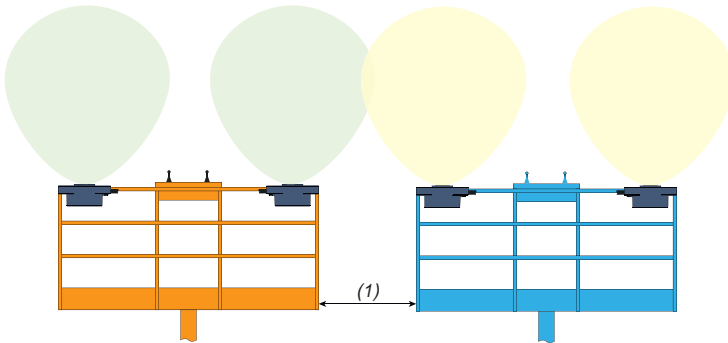
XXW54P3JL01DM6, XXW54P3JL05



Note: When noise detection is enabled, the sensor's CAN bus will output 100 by default (configurable to 6400) when it detects excessive environmental noise.

Setting-up instructions

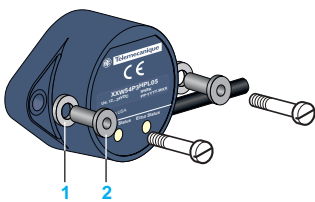
Mutual interference between two separate pieces of mobile equipment, side by side



(1) Minimum distance: 2.5 m

Note: Sensors in the same mobile equipment must be synchronized, but sensors in two separate pieces of mobile equipment cannot be synchronized.

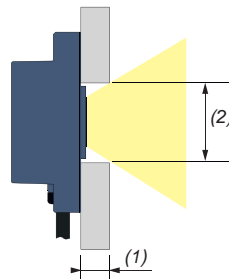
Mounting with inserts and washers



- 1 Silicone washer
- 2 Stainless steel insert

Note: The sensor is supplied with 2 stainless steel inserts \varnothing 4.32 mm and 2 silicone washers. M4 screws not provided

Flush-mounting recommendations



- (1) Max. thickness = 10 mm
- (2) Minimum \varnothing = 33 mm

Ultrasonic sensors

XX range

Flat format, plastic

DC supply, solid-state digital output



XX7F1A2NAL01M12



XX7K1A2PAM12



XX8D1A1NAM12



XXZPB100

Diffuse mode

Fixed sensing distance sensors

| Sensors | Sensing distance (Sn) | Function/output | Connection | Reference | Weight |
|---------------|-----------------------|-----------------|------------------------------------|------------------------|--------|
| mm | m | | | | kg |
| 7.6 x 19 x 33 | 0.10 | NO/NPN | 152 mm flying lead + M12 connector | XX7F1A2NAL01M12 | 0.040 |
| | | NO/PNP | 152 mm flying lead + M12 connector | XX7F1A2PAL01M12 | 0.040 |
| 16 x 30 x 74 | 0.25 | NO/PNP | M12 connector | XX7K1A2PAM12 | 0.050 |

Adjustable sensing distance sensors

| | | | | | |
|---------------------|-------------------|--------|----------------|---------------------|-------|
| 18 x 33 x 60 + Ø 18 | 0.50 (adjustable) | NO/NPN | Connecteur M12 | XX7V1A1NAM12 | 0.060 |
| | | NO/PNP | Connecteur M12 | XX7V1A1PAM12 | 0.060 |
| 80 x 80 x 34 | 1 (adjustable) | NO/NPN | Connecteur M12 | XX8D1A1NAM12 | 0.300 |
| | | NO/PNP | Connecteur M12 | XX8D1A1PAM12 | 0.300 |

Accessories

Teach pushbutton

| Description | For use with sensor | Reference | Weight |
|---|------------------------------|-----------------|--------|
| | | | kg |
| Selection of detection window Length of cable: 152 mm Input: M12 female connector Output: M12 male connector | XX7V1A1●AM12 XX8D1A1●AM12 | XXZPB100 | 0.035 |

Other connection and fixing accessories

See page 82.

Ultrasonic sensors

XX range

Flat format, plastic

Sensors with analogue output signal 0...10 V
or 4-20 mA

DF53726



XX9V1A1C2M12

108068



XX9D1A1●●M12

121388



XXZPB100

Diffuse mode

Adjustable sensing distance sensors

| Sensors | Sensing distance (Sn) | Analogue output (Slope selection using teach button) | Reference | Weight |
|------------------------|-----------------------|--|---------------------|--------|
| mm | m | | | kg |
| 18 x 33 x 65 + Ø 18 | 0.50 (adjustable) | 4-20 mA | XX9V1A1C2M12 | 0.090 |
| | | 0-10 V | XX9V1A1F1M12 | 0.060 |
| 80 x 80 x 34 | 1 (adjustable) | 4-20 mA | XX9D1A1C2M12 | 0.300 |
| | | 0-10 V | XX9D1A1F1M12 | 0.300 |

Accessories

Teach pushbutton

| Description | For use with sensors | Reference | Weight |
|--|------------------------------|-----------------|--------|
| Selection of detection window Length of cable: 152 mm Input: M12 female connector Output: M12 male connector | XX9V1A1●●M12 XX9D1A1●●M12 | XXZPB100 | 0.035 |

Other connection and fixing accessories

See page 82.

| Sensor type | XX7F1A2● | XX7K1A2● | XX7V1A1● | XX8D1A1● | XX9V1A1● | XX9D1A1● | |
|--|-------------------|---|--|--|----------------------------|--|--|
| General characteristics | | | | | | | |
| Conformity to standards | CE, IEC 60947-5-2 | | | | | | |
| Product certifications | UL | UL | UL | UL | UL, cCSAus | | |
| Nominal sensing distance (Sn) | m | 0.1 | 0.25 | 0.5 | 1 | 0.5 | 1 |
| Blind zone (in diffuse mode the object is not detected in this zone, in reflex mode the background is not detected in this zone) | mm | 0...6.4 | 0...51 | 0... 51 | 0... 100 | 0...51 | 0...100 |
| Detection window | Fixed | | Remotely adjustable or by using teach button | | | | |
| Detection system | Diffuse mode | ● | ● | ● | ● | ● | ● |
| Transmission frequency | kHz | 500 | 500 | 300 | 180 | 300 | 180 |
| Differential travel | mm | < 0.7 | < 0.35 | < 2.5 | < 2.5 | – | – |
| Repeat accuracy | mm | ± 0.7 | ± 0.7 | ± 1.27 | ± 1.6 | 1.27 | ± 1.6 |
| Overall beam angle (see detection lobe) | | 14° | 14° | 12° | 7° | 6° | 7° |
| Minimum size of object to be detected | | Cylinder Ø 2.5 mm or flat bar 1 mm wide up to 50 mm | Cylinder Ø 1.6 mm up to 76 mm | Cylinder Ø 2.5 mm or flat bar 1 mm wide for a sensing distance of 150 mm | Cylinder Ø 50 mm up to 1 m | Cylinder Ø 2.5 mm or flat bar 1 mm wide for a sensing distance of 150 mm | Cylinder Ø 50 mm up to a sensing distance of 1 m |
| Deviation angle from 90° of the object to be detected | | – | | | | ± 7° | ± 5° |
| Materials | Case | ULTEM® | | Valox® | | | |
| | Sensing face (1) | Epoxy | Silicone | Epoxy | | | |
| Connection | Connector | M12, 4-pin, on 152 mm flying lead | M12, 4-pin | | | | |
| Supply characteristics | | | | | | | |
| Rated supply voltage | V | ≐ 12...24 V | | | | ≐ 15...24 V | |
| Voltage limits (including ripple) | V | ≐ 10...28 V | | | | | |
| Current consumption, no-load | mA | 25 | 60 | 40 | 70 | 40 | 70 |

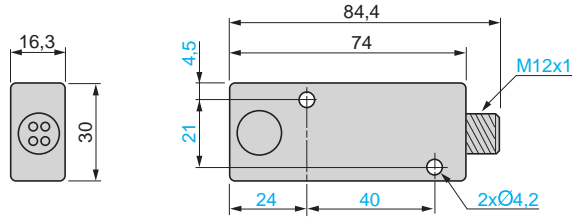
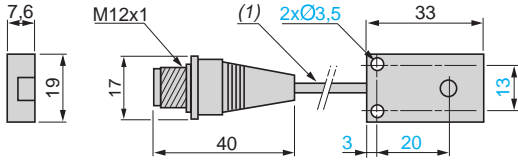
(1) Silicone face for optimum chemical resistance.

| Sensor type | | XX7F1A2● | XX7K1A2● | XX7V1A1● | XX8D1A1● | XX9V1A1● | XX9D1A1● | |
|--|---|--|--------------------------------------|----------|-----------------|----------|-----------------|----------|
| Output characteristics | | | | | | | | |
| Slope type | | Direct or inverse by using teach button (see page 72). | | | | | | |
| LED indicators | Output state | Yellow LED | | | | | | |
| | Power on | Green LED | | | Green LED | | | |
| | Setting-up assistance | – | | | Multicolour LED | | Dual colour LED | |
| Delays | First-up | ms | – | | | 100 | 75 | |
| Recovery time | | ms | – | | | 150 | 180 | |
| Resistive load impedance | 4-20 mA | Ω | – | | | 10...500 | 10...350 | |
| | 0-10 V | Ω | – | | | 1 k...∞ | 2 k fixed | |
| Switching capacity | (PNP and NPN) | mA | < 100, NO or NC function | | | | 100 | |
| Voltage drop | (PNP and NPN) | V | < 1 | < 1 | < 1 | < 1 | | |
| Maximum switching frequency | | Hz | 100 | 80 | 40 | 72 | | |
| Delays | First-up | ms | 20 | 350 | 100 | 75 | | |
| | Response | ms | 4 | 5 | 10 | 15 | | |
| | Recovery | ms | 4 | 5 | 10 | 75 | | |
| Environment characteristics | | | | | | | | |
| Degree of protection | Conforming to IEC 60529 and IEC 60947-5-2 | | IP 67 | | | | | |
| Storage temperature | | °C | - 40...+ 80 | | | | | |
| Operating temperature | | °C | - 20...+ 65 | 0...+ 50 | - 20...+ 65 | 0...+ 70 | - 20...+ 65 | 0...+ 70 |
| Vibration resistance | Conforming to IEC 60068-2-6 | | Amplitude ± 1 mm (f = 10...55 Hz) | | | | | |
| Mechanical shock resistance | Conforming to IEC 60068-2-27 | | 30 gn, duration 11 ms, in all 3 axes | | | | | |
| Resistance to electromagnetic interference | | | Conforming to IEC 60947-5-2 | | | | | |

Dimensions

XX7F1A2NAL01M12, XX7F1A2PAL01M12

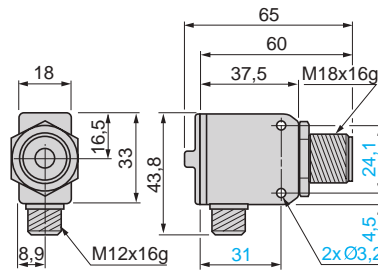
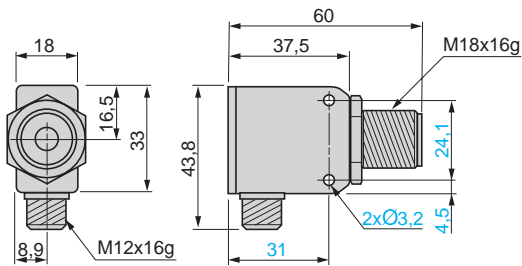
XX7K1A2PAM12



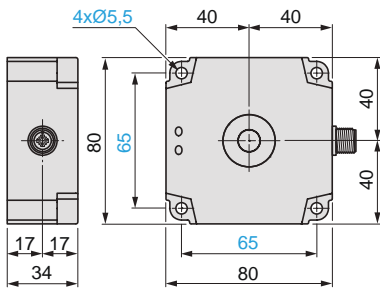
(1) Cable, length: 152 mm.

XX7V1A1NAM12, XX7V1A1PAM12

XX9V1A1C2M12, XX9V1A1F1M12

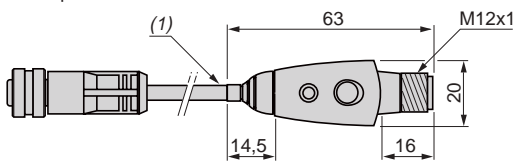


XX8D1A1NAM12, XX8D1A1PAM12, XX9D1A1C2AM12, XX9D1A1F1AM12



XXZPB100

Teach pushbutton



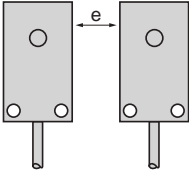
(1) Cable, length: 152 mm.

Setting-up precautions

Minimum mounting distances

Diffuse sensors, flat format

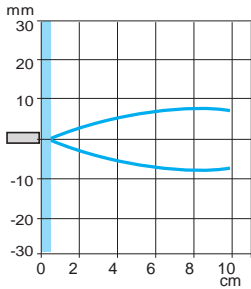
Side by side



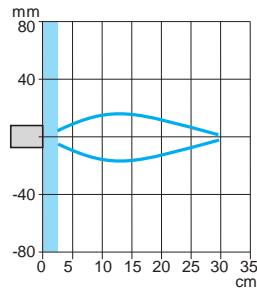
e: respect the distances indicated on the detection curves

Curves

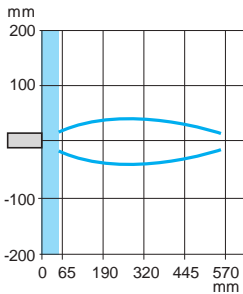
XX7F1A2NAL01M12,
XX7F1A2PAL01M12



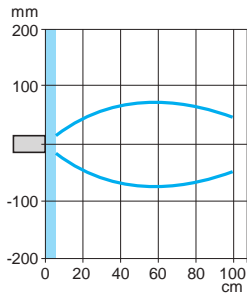
XX7K1A2PAM12



XX7V1A1NAM12, XX7V1A1PAM12,
XX9V1A1C2M12, XX9V1A1F1M12



XX8D1A1NAM12, XX8D1A1PAM12,
XX9D1A1C2AM12, XX9D1A1F1AM12

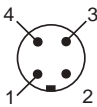


Blind zone

Schemes

M12 connector, solid-state digital output

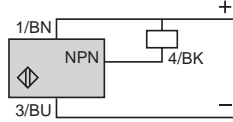
3-wire type



1 (+)
3 (-)
4 NPN or PNP output

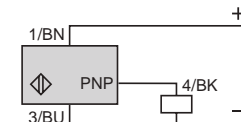
XX7F1A2NAL01M12 (1)

NO outputs, NPN



XX7F1A2PAL01M12 (1), XX7K1A2PAM12

NO outputs, PNP

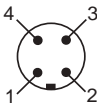


(-) BU (Blue)
(+) BN (Brown)
BK (Black)

(1) Remote connector on flying lead approximately 15 cm long.

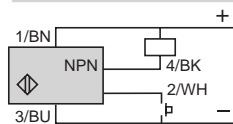
M12 connector, analogue output

4-wire type

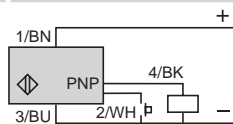


1 (+)
2 Return signal or
teach
3 (-)
4 Output signal

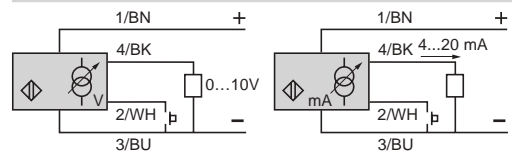
XX7V1A1NAM12
XX8D1A1NAM12



XX7V1A1PAM12
XX8D1A1PAM12



XX9V1A1C2M12, XX9V1A1F1M12, XX9D1A1C2AM12,
XX9D1A1F1AM12

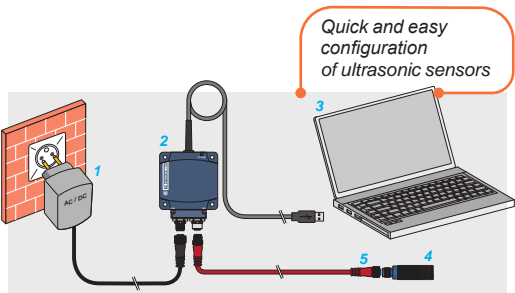


For impedance of resistive load refer to values on page 75.

XX Configuration Software

Telemecanique Sensors is now offering a solution for configuring ultrasonic XX range sensors. This software enables users to quickly find the optimal sensing solution for their applications. An interface unit connects the sensor to the PC via a USB connection.

- > **Easy configuration to unique applications**
The configuration software has more than 20 parameters that can be modified to suit the machine application. The parameters can be saved in PDF format for quick, easy reference.
- > **Real-time sensor performance display**
One of the best functions of the new software is the ability to troubleshoot and visualize the effects of the parameters on the configured sensor. The "echo display" function shows the exact position of any false echoes. The recording function can record the values of the echoes in an .xlsx or .xml file for extended periods of time.
- > **Quick duplication of programmed settings**
Optimal parameters set on one sensor can be saved and loaded on other units of the same reference. This function reduces time and effort.
- > The interface can be used to configure specific configurable models of XX ultrasonic sensors (XXS●●, XXA●● & XXW54P3●●●).



- 1: Power supply, provided with 4 adapters
- 2: Configuration interface **XXZBOX01**
- 3: XX Configuration Software, installed on a PC
- 4: Ultrasonic sensor **XXS●●, XXA●● or XXW54P3●●●**.
- 5: M12-M12 cable or Deutsch DTM04-M12.

XX Configuration Software for ultrasonic sensors

- > XX Configuration Software is available in English, French, German, Spanish, Italian, and Chinese. It can be downloaded directly from the website www.tesensors.com.
- > Recommended PC performance:
 - > Windows OS: 7 SP1 embedded standard(x86 & x64), 8.1 (x86 & x64), or 10 (x86 & x64)
 - > Internet Explorer: 9.0 or higher
 - > Disk space: 1 GB or higher
 - > RAM memory: 2 GB or higher
 - > Processor speed: 1 GHz or higher
 - > Display resolution: 1360 x 768 or higher



Ultrasonic sensors configuration interface
XXZBOX01



Ultrasonic sensors configuration kit
XXZKIT01

References

| Description | Reference | Weight kg |
|--|-----------------|-----------|
| Ultrasonic sensors configuration interface | | |
| Configuration interface provided with: | XXZBOX01 | 0.400 |
| <ul style="list-style-type: none"> ■ 1 power supply (1) ■ 1 UK adapter ■ 1 SAA adapter ■ 1 US adapter ■ 1 EU adapter | | |
| Ultrasonic sensors configuration kit | | |
| Plastic case including: | XXZKIT01 | 1.200 |
| <ul style="list-style-type: none"> ■ 1 configuration interface XXZBOX01 ■ 1 power supply (1) ■ 1 UK adapter ■ 1 SAA adapter ■ 1 US adapter ■ 1 EU adapter ■ 1 cable of 1 m, with M12 connectors (5-pin male/female) | | |

(1) Power supply: 24 V ---, 0.5 A min., with M12 connector.

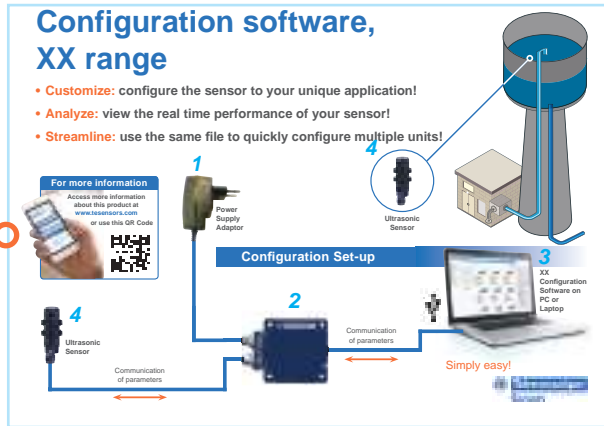
+ One of the most user-friendly ultrasonic sensor configuration software solutions

Configuration software presentation

Principle



- 1: Power supply, provided with 4 adapters
- 2: Configuration interface **XXZBOX01**
- 3: XX Configuration Software, installed on a PC
- 4: Ultrasonic sensor **XXS●●**, **XXA●●** or **XXW54P3●●●**.



Setting examples

Sensor selection

- > This page is used to manually select or auto-download the XX reference sensor to be configured. Once a reference has been selected, the user can start the configuration process.
- > There are 4 methods of selection. The **Reset search** button can reinitialize the search, regardless of the method used.
 - 1: Direct selection from the full reference list
 - 2: Selection through reference
 - 3: Manual search using criteria
 - 4: Automatic sensor detection



Detection settings

- > This tab is used to configure the sensor detection settings.



Output settings

- > This page enables the configuration of sensor outputs. If the sensor has several outputs, they may be configured separately, unless specified otherwise.

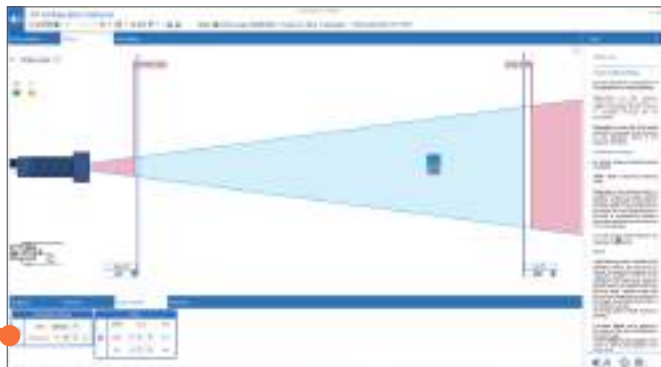


Configuration software presentation (continued)

Setting examples (continued)

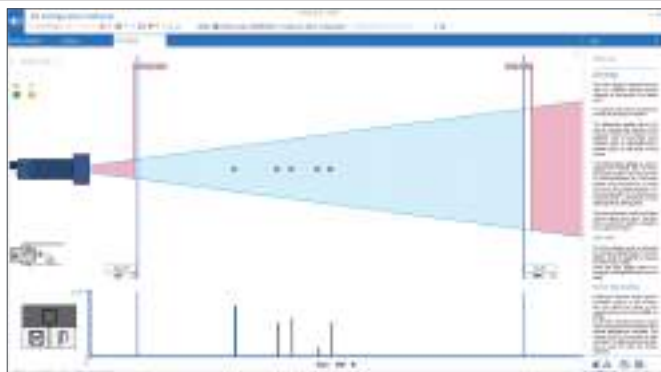
Teach method settings

- > This tab allows the configuration of the pushbutton for manual teaching. Depending on the sensor reference, the teach button is either integrated in the sensor or available through the teach pushbutton **XXZPB100** (see page 43).



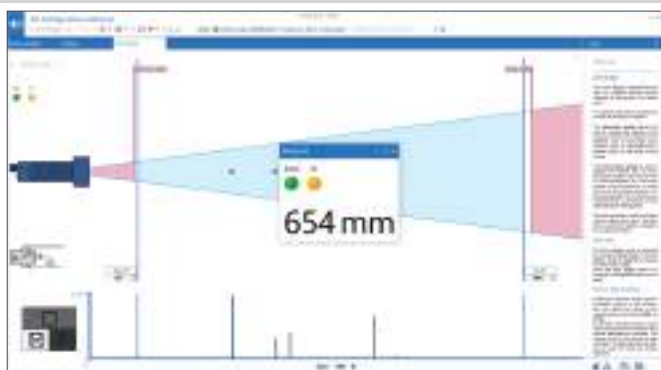
Echo display mode

- > With the “echo display” mode, the user can visualize several echoes received by the sensor in the same cycle.
- > The first valid echo is shown in blue and the others in gray. The blue echo is what the sensor considers as the detected object.
- > It is also possible to record the data over extended periods of time using the “record” function.



Measure mode

- > The “measure” button opens a pop-up window giving a real-time numerical display of the position of the object in mm or inches.



Characteristics

Supply characteristics

| | | |
|---|---|--|
| Rated supply voltage (Ue) with protection against reverse polarity | V | 24 V $\overline{\text{DC}}$ |
| Voltage limits | V | 14...30 V $\overline{\text{DC}}$ (ripple: 10% max) |
| Consumption | W | 4 (consumption excluding sensor) |

LED indicators

| | | |
|----------------|------------------|------------|
| LED indicators | Power supply | Green LED |
| | PC communication | Orange LED |
| | Error | Red LED |

Communication

| | | |
|------------------------------|-----|--------|
| Data communication baud rate | bps | 19,200 |
|------------------------------|-----|--------|

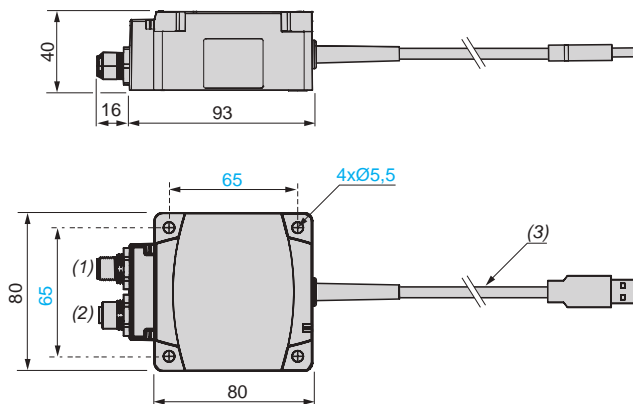
Connection

| | | |
|--|---|------------------------------------|
| Maximum cabling distance between sensor and interface | m | 3 |
| Electrical connection to sensor | | M12 female connector |
| Connection to PC or laptop | | 0.5 m USB cable , A type connector |

Environment characteristics

| | | |
|---------------------------|-------------------------|-----------------------------|
| Compliance to regulations | | CE |
| Degree of protection | Conforming to IEC 60529 | IP 40 |
| Storage temperature | °C | -20...+45 |
| Operating temperature | °C | 0...+45 |
| Relative humidity | | < 95%, without condensation |

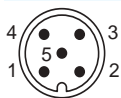
Dimensions



- (1) Male M12 connector, 5-pin: power supply
 (2) Female M12 connector, 5-pin: sensor
 (3) Cable length: 0.5 m (USB cable A type connector): PC

Connections

Interface connector for power supply adapter (M12 male)



| Pin number | Wire color | Description |
|------------|------------|-----------------------------------|
| 1 | BN: Brown | +14...30 V $\overline{\text{DC}}$ |
| 2 | WH: White | Output 2 (4) (5) |
| 3 | BU: Blue | 0 V $\overline{\text{DC}}$ |
| 4 | BK: Black | Output 1 (4) |
| 5 | - | Not used (6) |

Interface connector for sensor (M12 female)

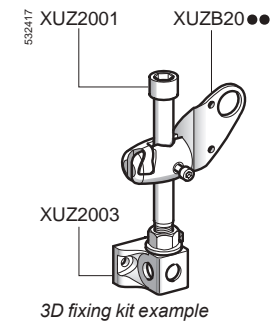


| Pin number | Description |
|------------|----------------------------|
| 1 | Power out to sensor |
| 2 | Software communication |
| 3 | 0 V $\overline{\text{DC}}$ |
| 4 | Software communication |
| 5 | Not used (6) |

(4) Output is only active during the "echo display" mode and "measure" mode.

(5) Output 2 is not available on all sensors.

(6) The 5th pins of the M12 male and M12 female connectors are electrically connected to one another.



References of accessories

Cabling accessories

| Connectors | For use with sensor | Type of connection | | Reference | Weight kg |
|-------------|---------------------|--|----------|---------------------|-----------|
| M8 3-pin | ∅ 12 | IDC (Insulation Displacement Connector) | Straight | XZCC8FDM30V | 0.010 |
| | XX512A2● | | Elbowed | XZCC8FCM30V | 0.010 |
| M8 4-pin | XX512A1● | | Straight | XZCC8FDM40V | 0.010 |
| | XX●12A8● | | Elbowed | XZCC8FCM40V | 0.010 |
| M12 | ∅ 18, ∅ 30 | Screw terminals, metal clamping ring | Straight | XZCC12FDM40B | 0.020 |
| | | | Elbowed | XZCC12FCM40B | 0.020 |
| | | Screw terminals, plastic clamping ring | Straight | XZCC12FDP40B | 0.020 |
| | | | Elbowed | XZCC12FCP40B | 0.020 |

| Pre-wired connectors | For use with sensor | Type | Cable length m | Reference | Weight kg |
|----------------------|---------------------|----------|----------------|-----------------------|-----------|
| M8 3-pin | ∅ 12 XX512A2● | Straight | 2 | XZCP0166L2 (1) | 0.080 |
| | | Elbowed | 2 | XZCP0266L2 (1) | 0.080 |
| M12 | ∅ 18, ∅ 30 | Straight | 2 | XZCP1141L2 (1) | 0.090 |
| | | Elbowed | 2 | XZCP1241L2 (1) | 0.090 |

Fixing accessories

| Description | For use with sensor | Reference | Weight kg | |
|---|-----------------------------------|---------------------|-----------------|-------|
| Fixing clamps | ∅ 12 | XSZB112 | 0.006 | |
| | ∅ 18 | XSZB118 | 0.010 | |
| | ∅ 30 | XSZB130 | 0.020 | |
| Fixing clamps (mounting on 35 mm rail) | XX●D● | XSZBD10 | 0.065 | |
| 90° fixing bracket | ∅ 12 | XXZ12 | 0.025 | |
| | ∅ 18 | XUZA118 | 0.038 | |
| | ∅ 30 | XXZ30 | 0.115 | |
| 3D fixing kit (2) | M12 rod | ∅ 12, ∅ 18 and ∅ 30 | XUZ2001 | 0.050 |
| | Support for M12 rod | ∅ 12, ∅ 18 and ∅ 30 | XUZ2003 | 0.160 |
| | Ball-joint mounted fixing bracket | ∅ 12 | XUZZ2012 | 0.175 |
| | | ∅ 18 | XUZZ2003 | 0.175 |
| | ∅ 30 | XUZZ2030 | 0.160 | |

(1) For a 5 m long cable replace L2 by L5, for a 10 m long cable replace L2 by L10.

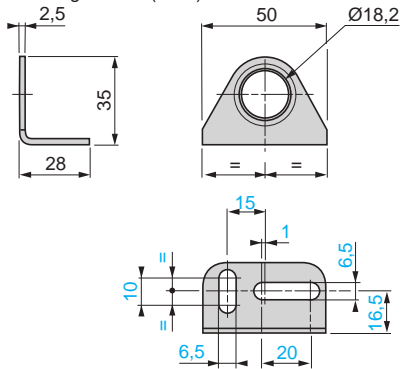
(2) To obtain a 3D fixing kit, order: rod support **XUZ2003**, M12 rod **XUZ2001** and ball-joint mounted fixing bracket **XUZZ200●**.

Dimensions of accessories

Fixing accessories

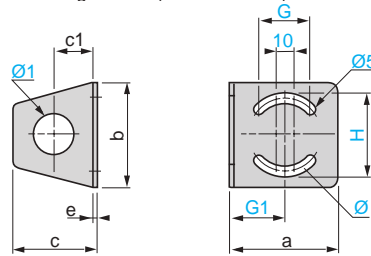
XUZA118

90° fixing bracket (Ø 18)



XXZ12, XXZ30

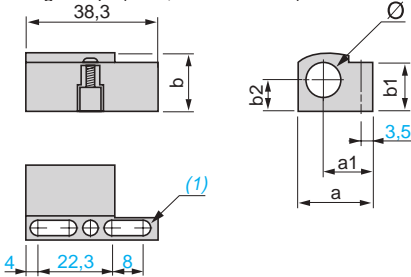
90° fixing bracket (Ø 12 and Ø 30)



| XXZ | a | b | c | c1 | e | H | G | G1 | Ø | Ø1 |
|-----|----|----|----|----|---|----|----|----|----|----|
| 12 | 35 | 40 | 33 | 18 | 2 | 31 | 18 | 18 | 25 | 13 |
| 30 | 67 | 65 | 52 | 25 | 3 | 51 | 35 | 33 | 50 | 31 |

XSZB112, XSZB118

Fixing clamps (Ø 12, Ø 18 and Ø 30)

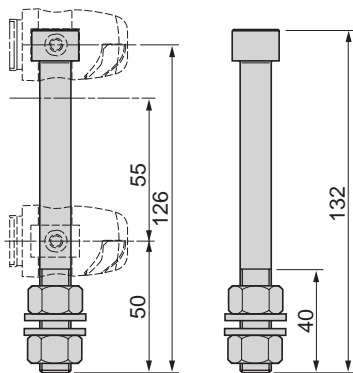


| XSZ | a | a1 | b | b1 | b2 | Ø |
|------|------|------|------|------|------|----|
| B112 | 21.9 | 14.5 | 16 | 15.5 | 8.5 | 12 |
| B118 | 26 | 15.7 | 22.3 | 20.1 | 11.5 | 18 |
| B130 | 39 | 21.7 | 35.5 | 31 | 18.5 | 30 |

(1) 2 elongated holes Ø 4 x 8.

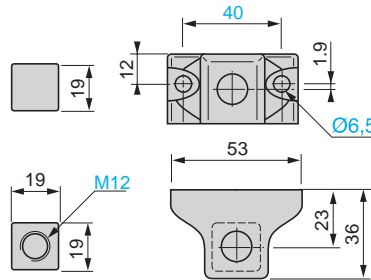
XUZ2001

M12 rod

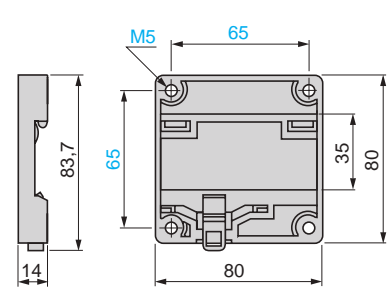


XUZ2003

Support for M12 rod

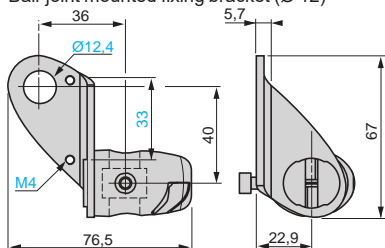


XSZBD10



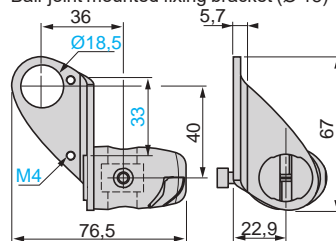
XUZB2012

Ball-joint mounted fixing bracket (Ø 12)



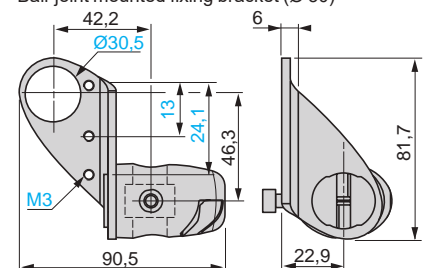
XUZB2003

Ball-joint mounted fixing bracket (Ø 18)



XUZB2030

Ball-joint mounted fixing bracket (Ø 30)



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